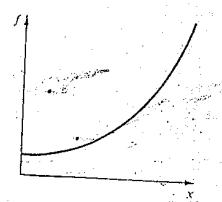
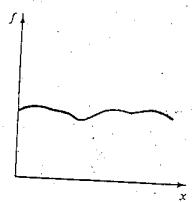


$$df = \left(\frac{df}{dx} \right) dx$$



$$dt = \left(\frac{\partial t}{\partial x} \right) dx + \left(\frac{\partial t}{\partial y} \right) dy + \left(\frac{\partial t}{\partial z} \right) dz$$

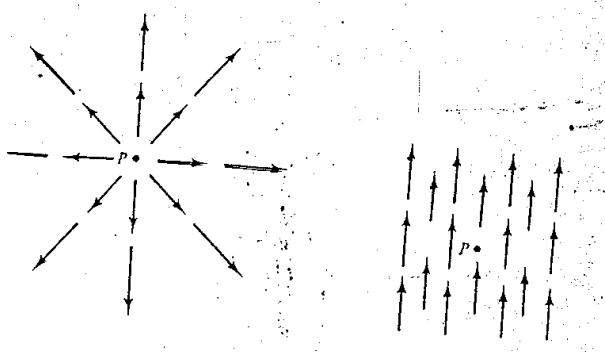
$$dt = \left(\frac{\partial t}{\partial x} \hat{i} + \frac{\partial t}{\partial y} \hat{j} + \frac{\partial t}{\partial z} \hat{k} \right) \cdot (dx \hat{i} + dy \hat{j} + dz \hat{k}) \\ = (\nabla t) \cdot (dt)$$

"The gradient ∇t points in the direction of maximum increase of the function t ."
for ever,

The magnitude $|\nabla t|$ gives the slope (rate of increase) along this maximal direction.

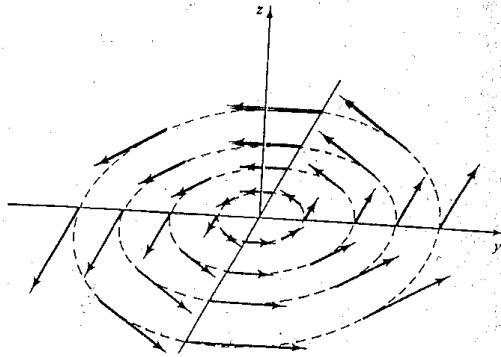
Example 3

$$\begin{aligned}\nabla \cdot \mathbf{v} &= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (\hat{i} v_x + \hat{j} v_y + \hat{k} v_z) \\ &= \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z},\end{aligned}$$



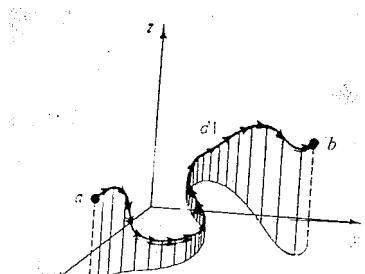
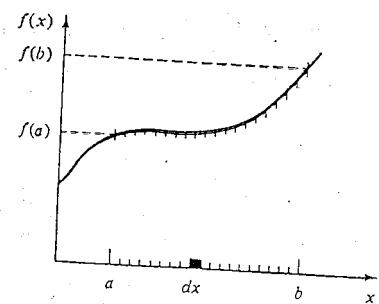
$$\nabla \times \mathbf{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

$$= \hat{i}\left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z}\right) + \hat{j}\left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x}\right) + \hat{k}\left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y}\right).$$



$$\int_a^b \left(\frac{df}{dx} \right) dx = f(b) - f(a).$$

$$\int_a^b F(x) dx = f(b) - f(a),$$

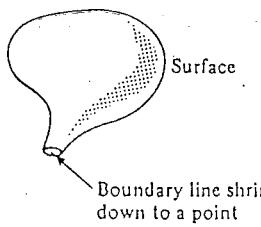


$$\int_a^b (\nabla t) \cdot dl = t(b) - t(a).$$

$$\int_{\text{volume}} (\nabla \cdot \mathbf{v}) d\tau = \int_{\text{surface}} \mathbf{v} \cdot d\mathbf{a}.$$

$\int (\text{all saucets in the volume}) = \int (\text{flow out through the surface}).$

$$\int_{\text{surface}} (\nabla \times \mathbf{v}) \cdot d\mathbf{a} = \oint_{\text{boundary line}} \mathbf{v} \cdot d\mathbf{l}$$



$$\int (\nabla \times \mathbf{v}) \cdot d\mathbf{a} = \oint \mathbf{v} \cdot d\mathbf{l}$$