

A. Relaciones vectoriales.

A.1. Vectores unitarios.

$\vec{u}_x, \vec{u}_y, \vec{u}_z$	–	coordenadas rectangulares	(constantes)
$\vec{u}_\rho, \vec{u}_\varphi, \vec{u}_z$	–	coordenadas cilíndricas	(no constantes, salvo $\vec{u}_z$)
$\vec{u}_r, \vec{u}_\theta, \vec{u}_\varphi$	–	coordenadas esféricas	(no constantes)

A.2. Transformaciones de coordenadas.

$$\begin{aligned}x &= \rho \cos \varphi = r \sin \theta \cos \varphi \\y &= \rho \sin \varphi = r \sin \theta \sin \varphi \\z &= r \cos \theta \\\rho &= \sqrt{x^2 + y^2} = r \sin \theta \\\varphi &= \tan^{-1}(y/x) \\r &= \sqrt{x^2 + y^2 + z^2} = \sqrt{\rho^2 + z^2} \\\theta &= \tan^{-1}(\sqrt{x^2 + y^2}/z) = \tan^{-1}(\rho/z)\end{aligned}$$

A.3. Transformaciones de las componentes coordenadas.

$$\begin{aligned}A_x &= A_\rho \cos \varphi - A_\varphi \sin \varphi \\&= A_r \sin \theta \cos \varphi + A_\theta \cos \theta \cos \varphi - A_\varphi \sin \varphi \\A_y &= A_\rho \sin \varphi + A_\varphi \cos \varphi \\&= A_r \sin \theta \sin \varphi + A_\theta \cos \theta \sin \varphi + A_\varphi \cos \varphi \\A_z &= A_r \cos \theta - A_\theta \sin \theta \\A_\rho &= A_x \cos \varphi + A_y \sin \varphi \\&= A_r \sin \theta + A_\theta \cos \theta \\A_\varphi &= -A_x \sin \varphi + A_y \cos \varphi \\A_r &= A_x \sin \theta \cos \varphi + A_y \sin \theta \sin \varphi + A_z \cos \theta \\&= A_\rho \sin \theta + A_z \cos \theta \\A_\theta &= A_x \cos \theta \cos \varphi + A_y \cos \theta \sin \varphi - A_z \sin \theta \\&= A_\rho \cos \theta - A_z \sin \theta\end{aligned}$$

A.4. Elementos diferenciales de longitud.

$$d\vec{l} = \begin{cases} \vec{u}_x dx + \vec{u}_y dy + \vec{u}_z dz \\ \vec{u}_\rho d\rho + \vec{u}_\varphi \rho d\varphi + \vec{u}_z dz \\ \vec{u}_r dr + \vec{u}_\theta r d\theta + \vec{u}_\varphi r \sin \theta d\varphi \end{cases}$$

A.5. Elementos diferenciales de superficie.

$$d\vec{s} = \begin{cases} \vec{u}_x dy dz + \vec{u}_y dx dz + \vec{u}_z dx dy \\ \vec{u}_\rho \rho d\varphi dz + \vec{u}_\varphi \rho d\rho dz + \vec{u}_z \rho d\rho d\varphi \\ \vec{u}_r r^2 \sin \theta d\theta d\varphi + \vec{u}_\theta r \sin \theta dr d\varphi + \vec{u}_\varphi r dr d\theta \end{cases}$$

A.6. Elementos diferenciales de volumen.

$$dv = \begin{cases} dx dy dz \\ \rho d\rho d\varphi dz \\ r^2 dr \sin \theta d\theta d\varphi \end{cases}$$

A.7. Operaciones vectoriales – coordenadas rectangulares.

$$\begin{aligned}
\vec{\nabla}\alpha &= \vec{u}_x \frac{\partial\alpha}{\partial x} + \vec{u}_y \frac{\partial\alpha}{\partial y} + \vec{u}_z \frac{\partial\alpha}{\partial z} \\
\vec{\nabla} \cdot \vec{A} &= \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} \\
\vec{\nabla} \times \vec{A} &= \vec{u}_x \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \vec{u}_y \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \vec{u}_z \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \\
\nabla^2 \alpha &= \frac{\partial^2 \alpha}{\partial x^2} + \frac{\partial^2 \alpha}{\partial y^2} + \frac{\partial^2 \alpha}{\partial z^2} \equiv \vec{\nabla} \cdot \vec{\nabla} \alpha \\
\nabla^2 \vec{A} &= \vec{u}_x \nabla^2 A_x + \vec{u}_y \nabla^2 A_y + \vec{u}_z \nabla^2 A_z \equiv \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \vec{\nabla} \times (\vec{\nabla} \times \vec{A})
\end{aligned}$$

A.8. Operaciones vectoriales – coordenadas cilíndricas.

$$\begin{aligned}
\vec{\nabla}\alpha &= \vec{u}_\rho \frac{\partial\alpha}{\partial \rho} + \vec{u}_\varphi \frac{1}{\rho} \frac{\partial\alpha}{\partial \varphi} + \vec{u}_z \frac{\partial\alpha}{\partial z} \\
\vec{\nabla} \cdot \vec{A} &= \frac{1}{\rho} \frac{\partial \rho A_\rho}{\partial \rho} + \frac{1}{\rho} \frac{\partial A_\varphi}{\partial \varphi} + \frac{\partial A_z}{\partial z} \\
\vec{\nabla} \times \vec{A} &= \vec{u}_\rho \left(\frac{1}{\rho} \frac{\partial A_z}{\partial \varphi} - \frac{\partial A_\varphi}{\partial z} \right) + \vec{u}_\varphi \left(\frac{\partial A_\rho}{\partial z} - \frac{\partial A_z}{\partial \rho} \right) + \vec{u}_z \frac{1}{\rho} \left(\frac{\partial \rho A_\varphi}{\partial \rho} - \frac{\partial A_\rho}{\partial \varphi} \right) \\
\nabla^2 \alpha &= \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \alpha}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 \alpha}{\partial \varphi^2} + \frac{\partial^2 \alpha}{\partial z^2}
\end{aligned}$$

A.9. Operaciones vectoriales – coordenadas esféricas.

$$\begin{aligned}
\vec{\nabla}\alpha &= \vec{u}_r \frac{\partial\alpha}{\partial r} + \vec{u}_\theta \frac{1}{r} \frac{\partial\alpha}{\partial \theta} + \vec{u}_\varphi \frac{1}{r \sin \theta} \frac{\partial\alpha}{\partial \varphi} \\
\vec{\nabla} \cdot \vec{A} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial A_\varphi}{\partial \varphi} \\
\vec{\nabla} \times \vec{A} &= \vec{u}_r \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} (A_\varphi \sin \theta) - \frac{\partial A_\theta}{\partial \varphi} \right) + \vec{u}_\theta \frac{1}{r} \left(\frac{1}{\sin \theta} \frac{\partial A_r}{\partial \varphi} - \frac{\partial (r A_\varphi)}{\partial r} \right) \\
&\quad + \vec{u}_\varphi \frac{1}{r} \left(\frac{\partial (r A_\theta)}{\partial r} - \frac{\partial A_r}{\partial \theta} \right) \\
\nabla^2 \alpha &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \alpha}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \alpha}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \alpha}{\partial \varphi^2} \\
\nabla^2 \vec{A} &= \vec{u}_r \left[\nabla^2 A_r - \frac{2}{r^2} \left(A_r + \cot \theta A_\theta + \operatorname{cosec} \theta \frac{\partial A_\varphi}{\partial \varphi} + \frac{\partial A_\theta}{\partial \theta} \right) \right] \\
&\quad + \vec{u}_\theta \left[\nabla^2 A_\theta - \frac{1}{r^2} \left(\operatorname{cosec}^2 \theta A_\theta - 2 \frac{\partial A_r}{\partial \theta} + 2 \cot \theta \operatorname{cosec} \theta \frac{\partial A_\varphi}{\partial \varphi} \right) \right] \\
&\quad + \vec{u}_\varphi \left[\nabla^2 A_\varphi - \frac{1}{r^2} \left(\operatorname{cosec}^2 \theta A_\varphi - 2 \operatorname{cosec} \theta \frac{\partial A_r}{\partial \varphi} - 2 \cot \theta \operatorname{cosec} \theta \frac{\partial A_\theta}{\partial \varphi} \right) \right]
\end{aligned}$$

A.10. Operaciones vectoriales – diferenciación.

$$\begin{aligned}
\vec{\nabla}(\alpha + \beta) &= \vec{\nabla}\alpha + \vec{\nabla}\beta \\
\vec{\nabla} \cdot (\vec{A} + \vec{B}) &= \vec{\nabla} \cdot \vec{A} + \vec{\nabla} \cdot \vec{B} \\
\vec{\nabla} \times (\vec{A} + \vec{B}) &= \vec{\nabla} \times \vec{A} + \vec{\nabla} \times \vec{B} \\
\vec{\nabla}(\alpha\beta) &= \alpha\vec{\nabla}\beta + \beta\vec{\nabla}\alpha \\
\vec{\nabla} \cdot (\alpha\vec{A}) &= \alpha\vec{\nabla} \cdot \vec{A} + \vec{A} \cdot \vec{\nabla}\alpha \\
\vec{\nabla} \times (\alpha\vec{A}) &= \alpha(\vec{\nabla} \times \vec{A}) - \vec{A} \times \vec{\nabla}\alpha \\
\vec{\nabla} \cdot (\vec{A} \times \vec{B}) &= \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B}) \\
\nabla^2 \vec{A} &= \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) \\
\vec{\nabla} \times (\alpha\vec{\nabla}\beta) &= \vec{\nabla}\alpha \times \vec{\nabla}\beta \\
\vec{\nabla} \times \vec{\nabla}\alpha &= 0 \\
\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) &= 0 \\
\vec{\nabla} \times (\vec{A} \times \vec{B}) &= \vec{A}(\vec{\nabla} \cdot \vec{B}) + (\vec{B} \cdot \vec{\nabla})\vec{A} - \vec{B}(\vec{\nabla} \cdot \vec{A}) - (\vec{A} \cdot \vec{\nabla})\vec{B}
\end{aligned}$$

A.11. Operaciones vectoriales – integración.

$$\begin{aligned}
\iiint_V \vec{\nabla} \cdot \vec{A} d^3r &= \oiint_S \vec{A} \cdot d\vec{s} \\
\iint_S \vec{\nabla} \times \vec{A} \cdot d\vec{s} &= \oint_l \vec{A} \cdot d\vec{l} \\
\iiint_V \vec{\nabla} \times \vec{A} d^3r &= -\oiint_S \vec{A} \times d\vec{s} \\
\iiint_V \vec{\nabla}\alpha d^3r &= \oiint_S \alpha d\vec{s} \\
\int \int_S \vec{u}_n \times \vec{\nabla}\alpha ds &= \oint_l \alpha d\vec{l}
\end{aligned}$$

B. Fórmulas útiles

B.1. Integrales de uso más frecuente.

$$\begin{aligned}
\int \frac{dx}{(a^2 + x^2)^{3/2}} &= \frac{x}{a^2 \sqrt{a^2 + x^2}} \quad ; \quad \int \frac{x dx}{(a^2 + x^2)^{3/2}} = \frac{-1}{\sqrt{a^2 + x^2}} \\
\int \frac{x dx}{\sqrt{a^2 + x^2}} &= \sqrt{a^2 + x^2} \quad ; \quad \int \frac{dx}{\sqrt{a^2 + x^2}} = \ln(x + \sqrt{a^2 + x^2})
\end{aligned}$$

$$\int \frac{x^2 dx}{(a^2 + x^2)^{3/2}} = \frac{-x}{\sqrt{a^2 + x^2}} + \ln(x + \sqrt{a^2 + x^2}) \quad ; \quad \int \frac{a dx}{a^2 + x^2} = \tan^{-1} \frac{x}{a}$$

B.2. Desarrollos más utilizados.

$$(1+x)^\alpha = 1 + \alpha x + \frac{\alpha(\alpha-1)}{2!}x^2 + \frac{\alpha(\alpha-1)(\alpha-2)}{3!}x^3 + \dots$$

$$\ln(x + \sqrt{a^2 + x^2}) = \ln a + \frac{x}{a} - \frac{1}{3!} \frac{x^3}{a^3} + \dots$$