

## 1. OUR WORK:

Development of algorithms based on non-linear ICA<sup>1</sup>, Gaussianization and principal curves that can be tuned for different goals (information maximization or error minimization):

- Sequential Principal Curves Analysis (SPCA)<sup>2</sup>
- Principal Polynomial Analysis (PPA)<sup>3</sup>
- Rotation-Based Iterative Gaussianization (RBIG)<sup>4</sup>

## 2. NON-LINEAR TECHNIQUES:

Unsupervised learning is based on considering the stimuli as vector,  $x$ , in a multidimensional space.<sup>5</sup> Then, one assumes a set of sensors or mechanisms that transform the input stimulus into a set of responses,  $r$ :

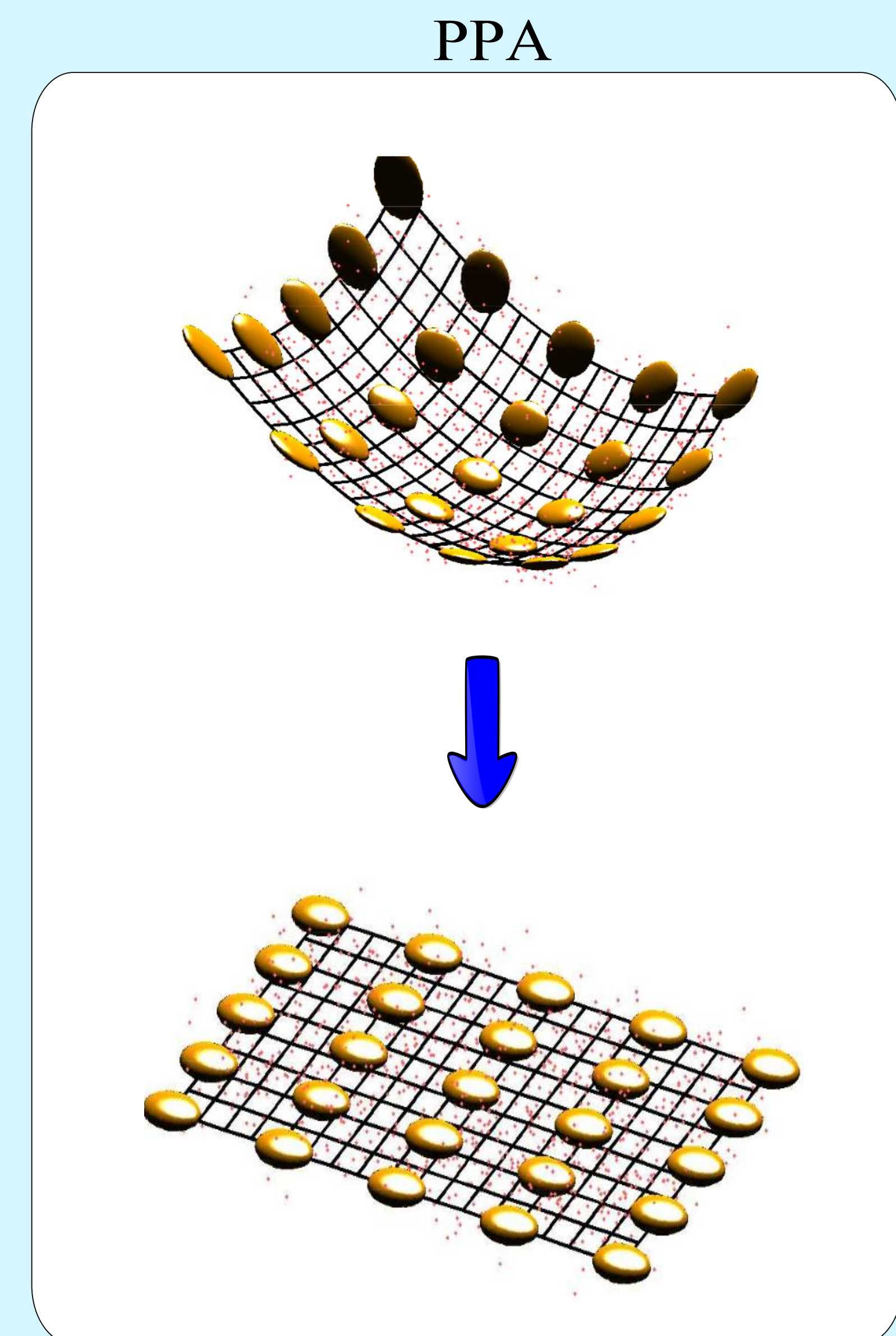
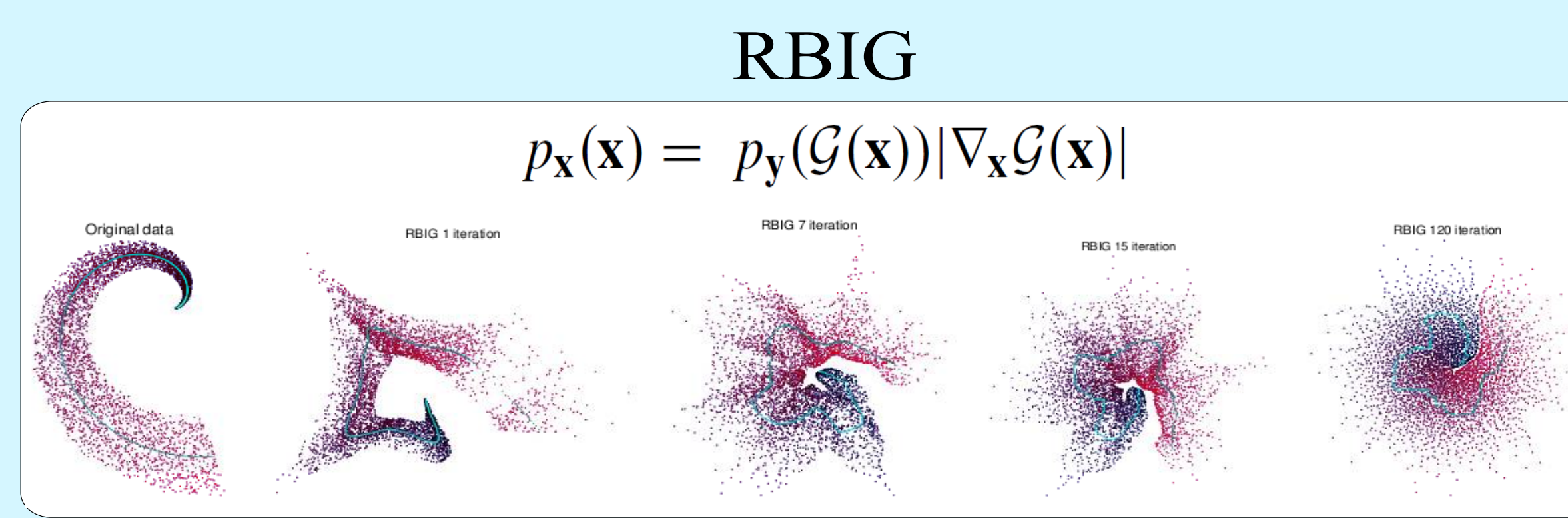
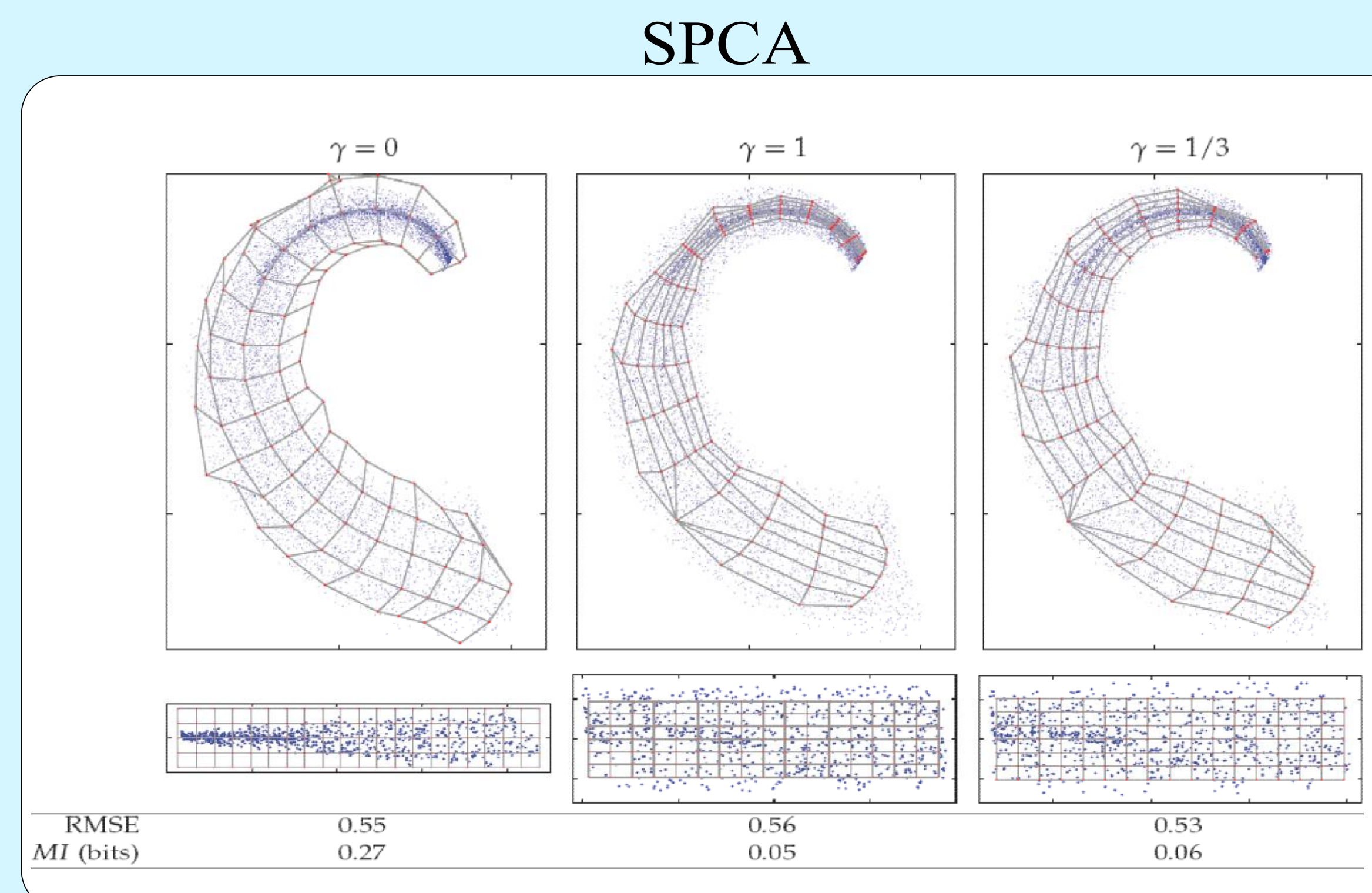
$$\begin{array}{ccc} & R & \\ x & \xrightarrow{\quad} & r \\ & R^{-1} & \end{array}$$

### ★ Requirement of sensors:

- Make experimentally testable prediction.
- Invertibility.
- Easy computation of discrimination measures in the input space.

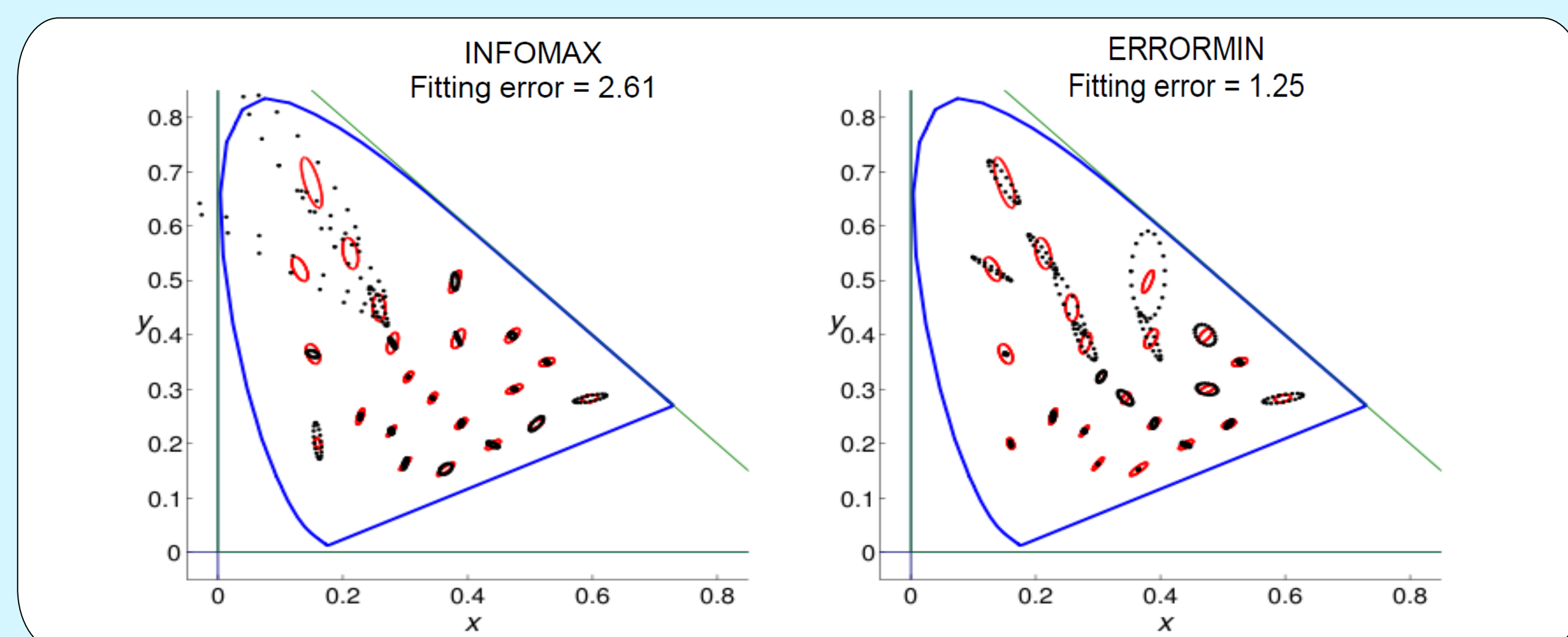
### ★ Learning Strategies:

- Identify the meaningful directions.
- Mapping into a domain where the statistical properties are perfectly determined.

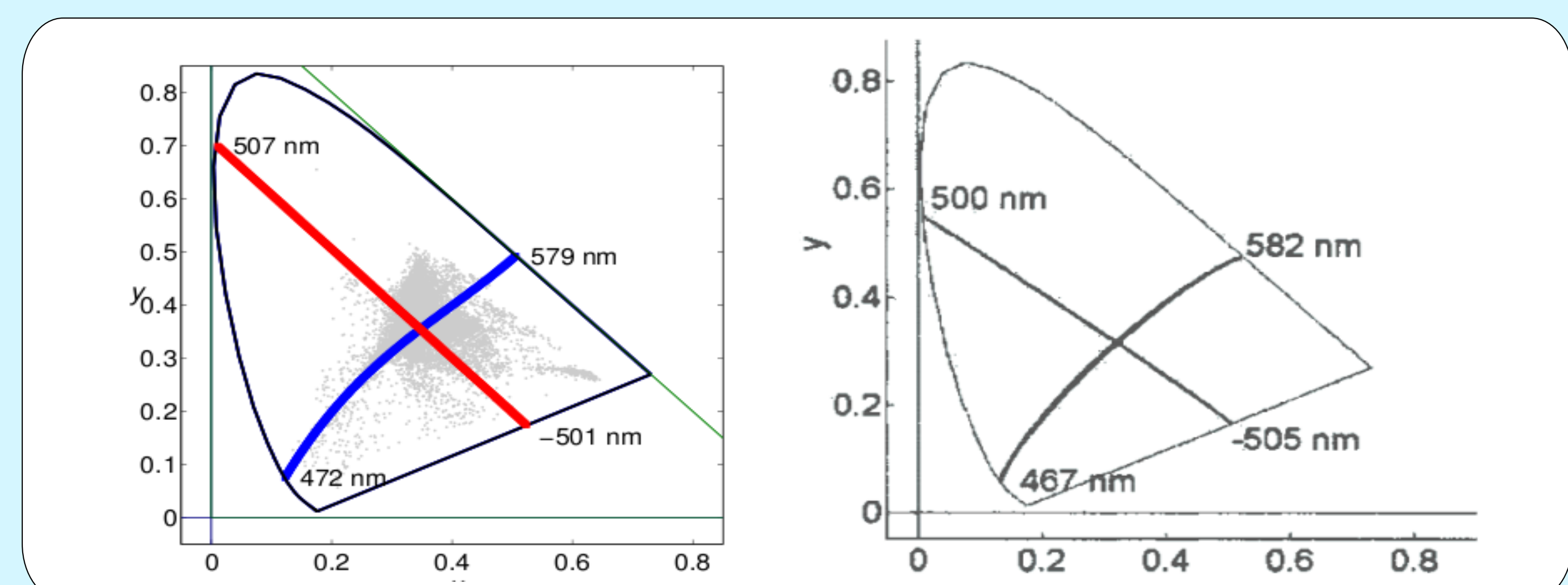


## 3. GALLERY OF PREDICTIONS:

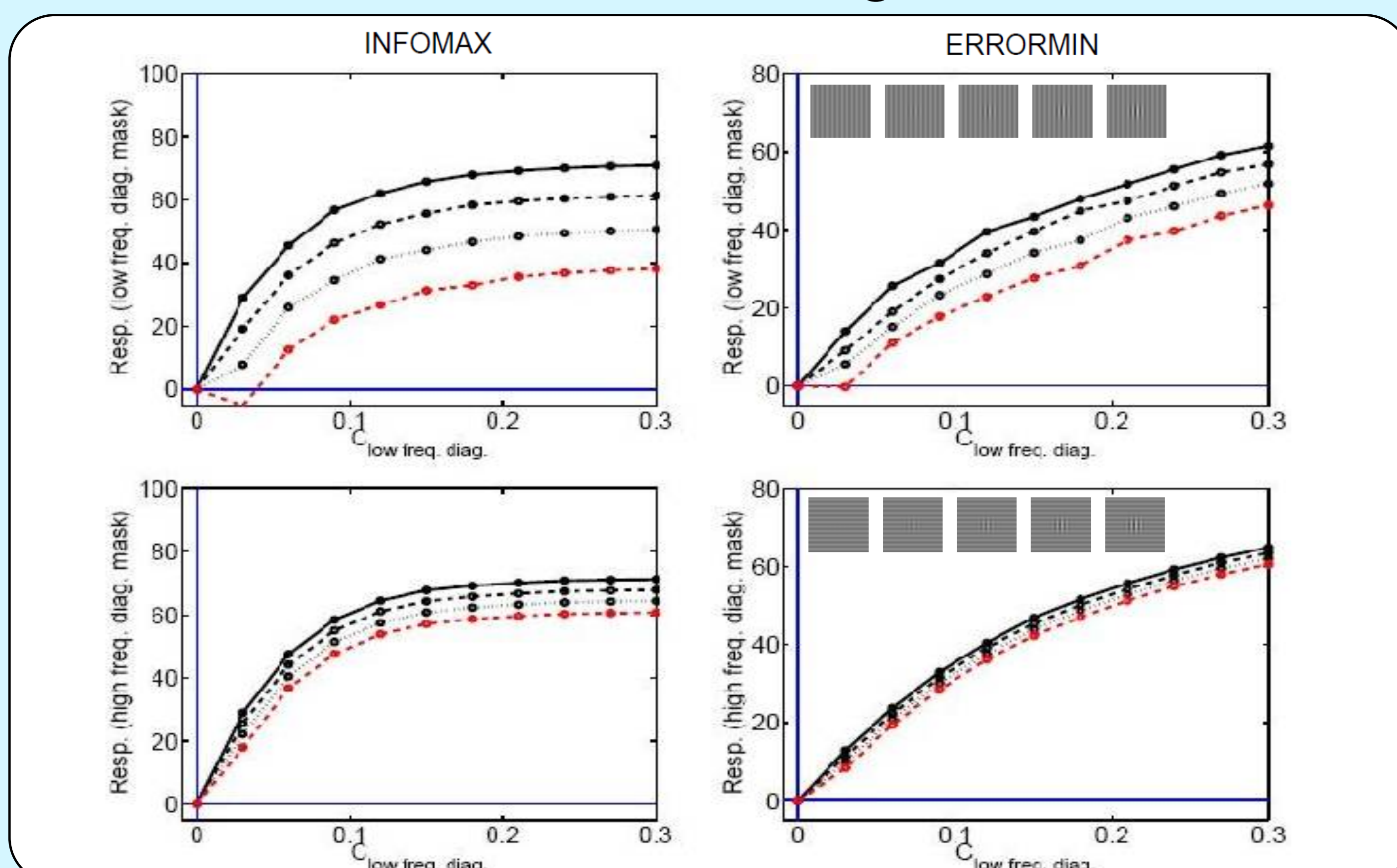
### Color Discrimination<sup>6,7</sup>



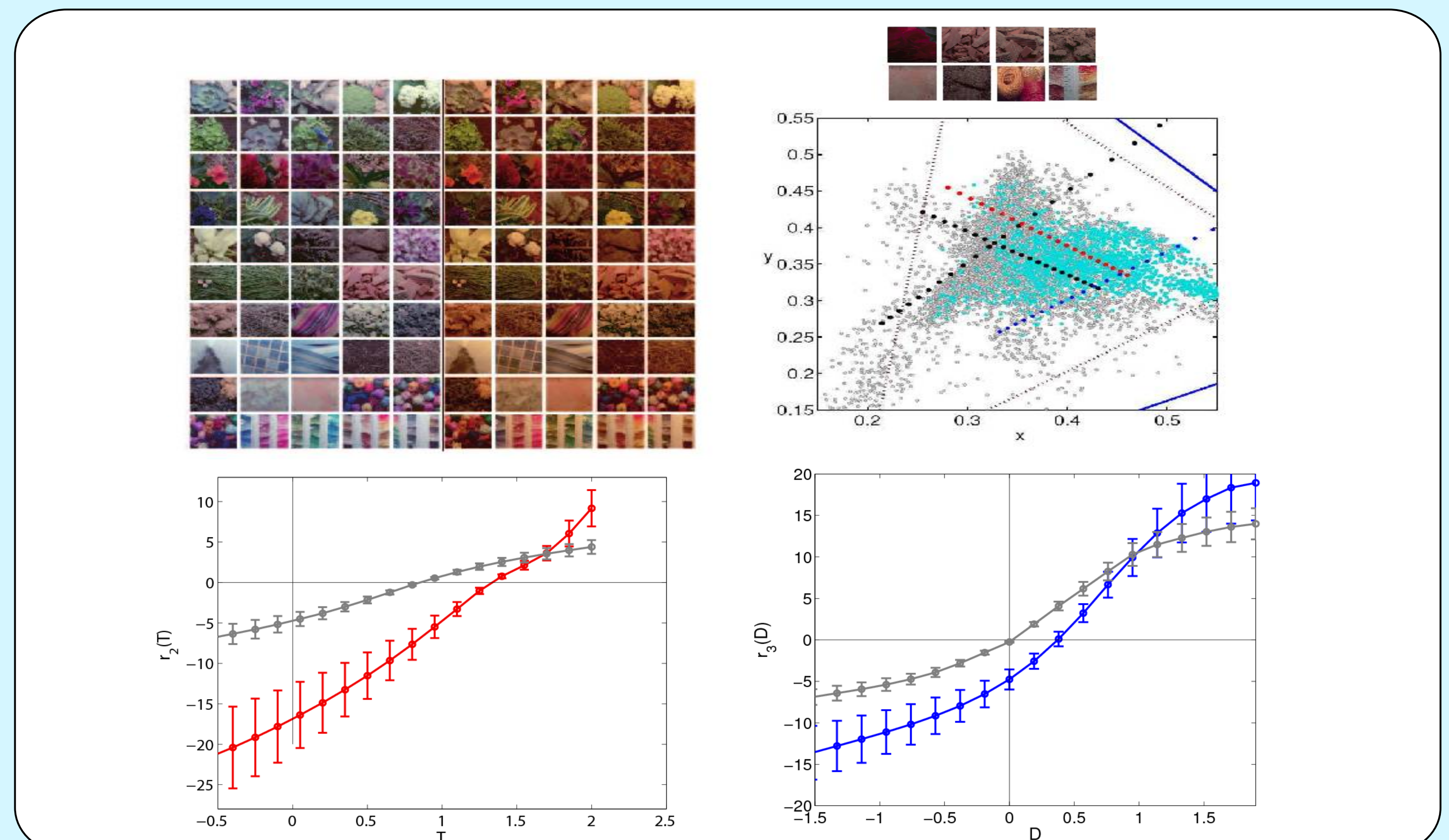
### Non-linear color sensors<sup>9,10</sup>



### Contrast masking<sup>8</sup>



### Color aftereffects<sup>11,12</sup>



## 6. REFERENCES:

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- [3] Laparra, V., Tuia, D., Jimenez, S., Camps, G., and Malo, J., "Nonlinear data description with Principal Polynomial Analysis," in [IEEE Mach. Learn. Sig. Proc.], (2012).
- [4] Laparra, V., Camps, G., and Malo, J., "Iterative gaussianization: from ICA to random rotations," *IEEE Trans. Neur. Nets.* 22(4), 537–549 (2011).
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