# The best constant for the Sobolev trace embedding from $W^{1,1}(\Omega)$ into $L^{1}(\partial \Omega)$ 

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#### Abstract

In this paper we study the best constant, $\lambda_{1}(\Omega)$ for the trace map from $W^{1,1}(\Omega)$ into $L^{1}(\partial \Omega)$. We show that this constant is attained in $B V(\Omega)$ when $\lambda_{1}(\Omega)<1$. Moreover, we prove that this constant can be obtained as limit when $p \searrow 1$ of the best constant of $W^{1, p}(\Omega) \hookrightarrow L^{p}(\partial \Omega)$. To perform the proofs we will look at Neumann problems involving the 1-Laplacian, $\Delta_{1}(u)=\operatorname{div}(D u /|D u|)$. © 2004 Published by Elsevier Ltd.


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## 1. Introduction

Let $\Omega$ be a bounded set in $\mathbb{R}^{N}$ with Lipschitz continuous boundary $\partial \Omega$. Of importance in the study of boundary value problems for differential operators in $\Omega$ are the Sobolev trace inequalities. In particular, $W^{1,1}(\Omega) \hookrightarrow L^{1}(\partial \Omega)$ and hence the following inequality holds:

$$
\lambda\|u\|_{L^{1}(\partial \Omega)} \leqslant\|u\|_{1,1},
$$

[^0]for all $u \in W^{1,1}(\Omega)$. The best constant for this embedding is the largest $\lambda$ such that the above inequality holds, that is,
\[

$$
\begin{equation*}
\lambda_{1}(\Omega)=\inf \left\{\int_{\Omega}|u|+\int_{\Omega}|\nabla u|: u \in W^{1,1}(\Omega), \int_{\partial \Omega}|u|=1\right\} \tag{1}
\end{equation*}
$$

\]

Our main interest in this paper is to study the dependence of the best constant $\lambda_{1}(\Omega)$ and extremals (functions where the constant is attained) on the domain. A related problem was studied by Demengel in [8] (see Remark 2). We remark that the existence of extremals is not trivial, due to the lack of compactness of the embedding.

For $1<p \leqslant N$, let us consider the variational problem

$$
\begin{equation*}
\inf \left\{\int_{\Omega}|u|^{p}+\int_{\Omega}|\nabla u|^{p}: u \in W^{1, p}(\Omega), \int_{\partial \Omega}|u|^{p}=1\right\} \tag{2}
\end{equation*}
$$

If we denote by $\lambda_{p}(\Omega)$ the above infimum, we have that

$$
\begin{equation*}
\lambda_{p}(\Omega)=\inf \left\{\frac{\int_{\Omega}|u|^{p}+\int_{\Omega}|\nabla u|^{p}}{\int_{\partial \Omega}|u|^{p}}: u \not \equiv 0 \text { on } \partial \Omega, u \in W^{1, p}(\Omega)\right\} \tag{3}
\end{equation*}
$$

is the best constant for the trace map from $W^{1, p}(\Omega)$ into $L^{p}(\partial \Omega)$. Due to the compactness of the embedding $W^{1, p}(\Omega) \hookrightarrow L^{p}(\partial \Omega)$, it is well known (see for instance [10]) that problem (3) has a minimizer in $W^{1, p}(\Omega)$. These extremals are weak solutions of the following problem:

$$
\begin{cases}\Delta_{p} u=|u|^{p-2} u & \text { in } \Omega  \tag{4}\\ |\nabla u|^{p-2} \frac{\partial u}{\partial v}=\lambda|u|^{p-2} u & \text { on } \partial \Omega\end{cases}
$$

where $\Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ is the $p$-Laplacian, $\partial / \partial v$ is the outer unit normal derivative and if we use the normalization $\|u\|_{L^{p}(\partial \Omega)}=1$, one can check that $\lambda=\lambda_{p}(\Omega)$, see [11].

Our first result says that $\lambda_{1}(\Omega)$ is the limit as $p \searrow 1$ of $\lambda_{p}(\Omega)$ and provides a bound for $\lambda_{1}(\Omega)$.

Theorem 1. We have that

$$
\lim _{p \searrow 1} \lambda_{p}(\Omega)=\lambda_{1}(\Omega)
$$

and

$$
\lambda_{1}(\Omega) \leqslant \min \left\{\frac{|\Omega|}{P(\Omega)}, 1\right\}
$$

where $P(\Omega)$ stands for the perimeter of $\Omega$.

Therefore, it seems natural to search for an extremal for $\lambda_{1}(\Omega)$ as the limit of extremals for $\lambda_{p}(\Omega)$ when $p \searrow 1$. Formally, if we take limit as $p \searrow 1$ in Eq. (4), we get

$$
\begin{cases}\Delta_{1} u:=\operatorname{div}\left(\frac{D u}{|D u|}\right)=\frac{u}{|u|} & \text { in } \Omega,  \tag{5}\\ \frac{D u}{|D u|} \cdot v=\lambda_{1}(\Omega) \frac{u}{|u|} & \text { on } \partial \Omega\end{cases}
$$

Hence we will look at Neumann problems involving the 1-Laplacian, $\Delta_{1}(u)=\operatorname{div}(D u /|D u|)$ in the context of bounded variation functions (the natural context for this type of problems). To our knowledge the results obtained here have independent interest.

We shall say that $\Omega$ has the trace-property if there exists a vector field $z_{\Omega} \in L^{\infty}\left(\Omega, \mathbb{R}^{N}\right)$, with $\left\|z_{\Omega}\right\|_{\infty} \leqslant 1$ such that $\operatorname{div}\left(z_{\Omega}\right) \in L^{\infty}(\Omega)$ and

$$
\left[z_{\Omega}, v\right]=\lambda_{1}(\Omega) \mathscr{H}^{N-1} \text {-a.e. } \quad \text { on } \partial \Omega
$$

Our main result states that for any domain having the trace property, the best Sobolev trace constant, $\lambda_{1}(\Omega)$, is attained by a function in $L^{1}(\Omega)$ whose derivatives in the sense of distributions are bounded measures on $\Omega$, that is a function with bounded variation.

Theorem 2. Let $\Omega$ be a bounded open set in $\mathbb{R}^{N}$ with the trace-property. Then, there exists a nonnegative function of bounded variation which is a minimizer of the variational problem (1) and a solution of problem (5).

We will see that every bounded domain $\Omega$ with $\lambda_{1}(\Omega)<1$, has the trace-property. Hence we have proved that, if $\lambda_{1}(\Omega)<1$ then there exists an extremal. Moreover, using results from [12], we can find examples of domains (a ball or an annulus) such that $\lambda_{1}(\Omega)=1$ and verify the trace property (and therefore they have extremals). We also prove that every planar domain $\Omega$ with a point of curvature greater than 2 verifies $\lambda_{1}(\Omega)<1$.

Organization of the paper. In Section 2 we collect some preliminary results and prove Theorem 1. In Section 3 we deal with the Neumann problem for the equation $\operatorname{div}(z)=1$. Finally, in Section 4 we use these results to prove the main theorem, Theorem 2. Throughout this paper $C$ and $c$ denote constants that may change from one line to another.

## 2. Preliminary results. Proof of Theorem 1

Let us begin with some notation and definitions. Recall that a function $u \in L^{1}(\Omega)$ whose partial derivatives in the sense of distributions are measures with finite total variation in $\Omega$ is called a function of bounded variation. The class of such functions will be denoted by $B V(\Omega)$. Thus $u \in B V(\Omega)$ if and only if there are Radon measures $\mu_{1}, \ldots, \mu_{N}$ defined in $\Omega$ with finite total mass in $\Omega$ and

$$
\int_{\Omega} u D_{i} \varphi=-\int_{\Omega} \varphi \mathrm{d} \mu_{i}
$$

for all $\varphi \in C_{0}^{\infty}(\Omega), i=1, \ldots, N$. Thus the gradient of $u$ is a vector valued measure with finite total variation

$$
|D u|(\Omega)=\sup \left\{\int_{\Omega} u \operatorname{div} \varphi: \varphi \in C_{0}^{\infty}\left(\Omega, \mathbb{R}^{N}\right),|\varphi(x)| \leqslant 1 \text { for } x \in \Omega\right\}
$$

The set of bounded variation functions, $B V(\Omega)$, is a Banach space endowed with the norm

$$
\|u\|_{B V(\Omega)}:=\|u\|_{1}+|D u|(\Omega)=\int_{\Omega}|u|+\int_{\Omega}|D u| .
$$

A measurable set $E \subset \mathbb{R}^{N}$ is said to be of finite perimeter in $\Omega$ if $\chi_{E} \in B V(\Omega)$, in this case the perimeter of $E$ in $\Omega$ is defined as $P(E, \Omega):=\left|D \chi_{E}\right|$. We shall use the notation $P(E):=P\left(E, \mathbb{R}^{N}\right)$, and $\mathscr{P}_{f}(\Omega)$ shall denote the set of all subset of $\Omega$ of finite perimeter. For a set of finite perimeter $E$ one can define the essential boundary $\partial^{*} E$, which is countably $(N-1)$ rectificable with finite $\mathscr{H}^{N-1}$ measure, and compute the unit normal $v^{E}(x)$ at $\mathscr{H}^{N-1}$ almost all points $x$ of $\partial^{*} E$, where $\mathscr{H}^{N-1}$ is the $(N-1)$ dimensional Hausdorff measure, and $\left|D \chi_{E}\right|$ coincides with the restriction of $\mathscr{H}^{N-1}$ to $\partial^{*} E$.

It is well known (see, [1,9] or [13]) that for a given function $u \in B V(\Omega)$ there exists a sequence $u_{n} \in W^{1,1}(\Omega)$ such that $u_{n}$ strict converges to $u$, i.e.,

$$
u_{n} \rightarrow u \text { in } L^{1}(\Omega) \text { and } \int_{\Omega}\left|\nabla u_{n}\right| \rightarrow \int_{\Omega}|D u| .
$$

Moreover, there is a trace operator $\tau: B V(\Omega) \rightarrow L^{1}(\partial \Omega)$ such that

$$
\begin{equation*}
\|\tau(u)\|_{L^{1}(\partial \Omega)} \leqslant C\|u\|_{B V(\Omega)} \quad \forall u \in B V(\Omega) \tag{6}
\end{equation*}
$$

for some constant $C$ depending only on $\Omega$. The trace operator $\tau$ is continuous between $B V(\Omega)$, endowed with the topology induced by the strict convergence, and $L^{1}(\partial \Omega)$. In the sequel we write $\tau(u)=u$.

From the above results, we get

$$
\lambda_{1}(\Omega)=\inf \left\{\frac{\int_{\Omega}|u|+\int_{\Omega}|D u|}{\int_{\partial \Omega}|u|}: u \not \equiv 0 \text { on } \partial \Omega, u \in B V(\Omega)\right\} .
$$

Let us recall a generalized Green's formula given in [5] (see also [4]). For $1 \leqslant p<\infty$, let

$$
X_{p}(\Omega)=\left\{z \in L^{\infty}\left(\Omega, \mathbb{R}^{N}\right): \operatorname{div}(z) \in L^{p}(\Omega)\right\}
$$

If $z \in X_{p}(\Omega)$ and $w \in B V(\Omega) \cap L^{p^{\prime}}(\Omega)$ the functional $(z, D w): C_{0}^{\infty}(\Omega) \rightarrow \mathbb{R}$ is defined by the formula

$$
\langle(z, D w), \varphi\rangle=-\int_{\Omega} w \varphi \operatorname{div}(z)-\int_{\Omega} w z \cdot \nabla \varphi
$$

Then $(z, D w)$ is a Radon measure in $\Omega$,

$$
\int_{\Omega}(z, D w)=\int_{\Omega} z \cdot \nabla w
$$

for all $w \in W^{1,1}(\Omega) \cap L^{\infty}(\Omega)$ and

$$
\begin{equation*}
\left|\int_{B}(z, D w)\right| \leqslant \int_{B}|(z, D w)| \leqslant\|z\|_{\infty} \int_{B}|D w| \tag{7}
\end{equation*}
$$

for any Borel set $B \subseteq \Omega$.
In [5], a weak trace on $\partial \Omega$ of the normal component of $z \in X_{p}(\Omega)$ is defined. Concretely, it is proved that there exists a linear operator $\gamma: X_{p}(\Omega) \rightarrow L^{\infty}(\partial \Omega)$ such that

$$
\begin{aligned}
& \|\gamma(z)\|_{\infty} \leqslant\|z\|_{\infty}, \\
& \gamma(z)(x)=z(x) \cdot v(x) \quad \text { for all } x \in \partial \Omega \text { if } z \in C^{1}\left(\bar{\Omega}, \mathbb{R}^{N}\right)
\end{aligned}
$$

We shall denote $\gamma(z)(x)$ by $[z, v](x)$. Moreover, the following Green's formula, relating the function $[z, v]$ and the measure $(z, D w)$, for $z \in X_{p}(\Omega)$ and $w \in B V(\Omega) \cap L^{p^{\prime}}(\Omega)$, is established:

$$
\begin{equation*}
\int_{\Omega} w \operatorname{div}(z) \mathrm{d} x+\int_{\Omega}(z, D w)=\int_{\partial \Omega}[z, v] w \mathrm{~d} \mathscr{H}^{N-1} \tag{8}
\end{equation*}
$$

Now we can prove Theorem 1.
Proof of Theorem 1. We have to prove that

$$
\begin{equation*}
\lim _{p \searrow 1} \lambda_{p}(\Omega)=\lambda_{1}(\Omega) \tag{9}
\end{equation*}
$$

and

$$
\begin{equation*}
\lambda_{1}(\Omega) \leqslant \min \left\{\frac{|\Omega|}{P(\Omega)}, 1\right\} \tag{10}
\end{equation*}
$$

Since

$$
\lambda_{p}(\Omega)\|u\|_{L^{p}(\partial \Omega)}^{p} \leqslant\|u\|_{1, p}^{p} \quad \forall u \in W^{1, p}(\Omega)
$$

if we set

$$
\lambda^{*}:=\limsup _{p \searrow 1} \lambda_{p}(\Omega)
$$

we have

$$
\lambda^{*}\|u\|_{L^{1}(\partial \Omega)} \leqslant\|u\|_{1,1} \quad \forall u \in W^{1,1}(\Omega)
$$

from where it follows that $\lambda^{*} \leqslant \lambda_{1}(\Omega)$, that is

$$
\begin{equation*}
\limsup _{p \searrow 1} \lambda_{p}(\Omega) \leqslant \lambda_{1}(\Omega) . \tag{11}
\end{equation*}
$$

Let $v_{p}$ be a minimizer of problem (3). Then, if $u_{p}:=a_{p} v_{p}$, with $a_{p}$ satisfying

$$
a_{p}=\left(\int_{\partial \Omega}\left|v_{p}\right|\right)^{1 /(p-1)}\left(\int_{\partial \Omega}\left|v_{p}\right|^{p}\right)^{1 /(1-p)}
$$

we get

$$
\int_{\partial \Omega}\left|u_{p}\right|=\int_{\partial \Omega}\left|u_{p}\right|^{p}
$$

and consequently

$$
\begin{equation*}
\lambda_{p}(\Omega)=\frac{\int_{\Omega}\left|u_{p}\right|^{p}+\int_{\Omega}\left|\nabla u_{p}\right|^{p}}{\int_{\partial \Omega}\left|u_{p}\right|} \tag{12}
\end{equation*}
$$

Applying Hölder's inequality and (12), we have

$$
\begin{aligned}
\lambda_{1}(\Omega) & \leqslant \frac{\int_{\Omega}\left|u_{p}\right|+\int_{\Omega}\left|\nabla u_{p}\right|}{\int_{\partial \Omega}\left|u_{p}\right|} \leqslant|\Omega|^{1 / p^{\prime}} \frac{\left(\int_{\Omega}\left(\left|u_{p}\right|+\left|\nabla u_{p}\right|\right)^{p}\right)^{1 / p}}{\int_{\partial \Omega}\left|u_{p}\right|} \\
& \leqslant|\Omega|^{1 / p^{\prime}} 2^{(p-1) / p} \frac{\left(\int_{\Omega}\left|u_{p}\right|^{p}+\int_{\Omega}\left|\nabla u_{p}\right|^{p}\right)^{1 / p}}{\int_{\partial \Omega}\left|u_{p}\right|} \\
& =|\Omega|^{1 / p^{\prime}} 2^{(p-1) / p} \frac{\lambda_{p}(\Omega)^{1 / p}}{\left(\int_{\partial \Omega}\left|u_{p}\right|\right)^{1 / p^{\prime}}} .
\end{aligned}
$$

Hence

$$
\lambda_{p}(\Omega) \geqslant \lambda_{1}(\Omega)^{p} \frac{2^{1-p}}{|\Omega|^{p / p^{\prime}}}\left(\int_{\partial \Omega}\left|u_{p}\right|\right)^{p / p^{\prime}}
$$

from where it follows that

$$
\begin{equation*}
\liminf _{p \searrow 1} \lambda_{p}(\Omega) \geqslant \lambda_{1}(\Omega) . \tag{13}
\end{equation*}
$$

Now, (9) follows from (11) and (13).
Taking $u=\chi_{\Omega}$, we obtain that

$$
\lambda_{1}(\Omega) \leqslant \frac{\int_{\Omega}\left|\chi_{\Omega}\right|+\int_{\Omega}\left|D \chi_{\Omega}\right|}{\int_{\partial \Omega}\left|\chi_{\Omega}\right|}=\frac{|\Omega|}{P(\Omega)} .
$$

On the other hand, if $\Omega_{\varepsilon}:=\{x \in \Omega: d(x, \partial \Omega)<\varepsilon\}$, we have

$$
\lambda_{1}(\Omega) \leqslant \frac{\int_{\Omega}\left|\chi_{\Omega_{\varepsilon}}\right|+\int_{\Omega}\left|D \chi_{\Omega_{\varepsilon}}\right|}{\int_{\partial \Omega}\left|\chi_{\Omega_{\varepsilon}}\right|}=\frac{\left|\Omega_{\varepsilon}\right|+P\left(\Omega_{\varepsilon}, \Omega\right)}{P(\Omega)} .
$$

Hence, taking $\varepsilon \rightarrow 0^{+}$, it follows that $\lambda_{1}(\Omega) \leqslant 1$. Therefore, (10) holds.
It is well known (see for instance [11]) that, for every $p>1$, there exist an extremal for the embedding $W^{1, p}(\Omega) \hookrightarrow L^{p}(\partial \Omega)$ (this embedding is compact). This is a solution $0 \leqslant u_{p} \in W^{1, p}(\Omega)$ of the equation

$$
\begin{equation*}
\lambda_{p}(\Omega)=\int_{\Omega}\left|u_{p}\right|^{p}+\int_{\Omega}\left|\nabla u_{p}\right|^{p}, \quad \int_{\partial \Omega}\left|u_{p}\right|=1 \tag{14}
\end{equation*}
$$

such that $u_{p}>0$ and satisfies in the weak sense

$$
\left\{\begin{array}{l}
\Delta_{p} u_{p}:=\operatorname{div}\left(\left|\nabla u_{p}\right|^{p-2} \nabla u_{p}\right)=\left|u_{p}\right|^{p-2} u_{p} \quad \text { in } \Omega,  \tag{15}\\
\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \cdot v=\lambda_{p}(\Omega)\left|u_{p}\right|^{p-2} u_{p} \quad \text { on } \partial \Omega .
\end{array}\right.
$$

Now, by Young's inequality we have

$$
\begin{aligned}
\lambda_{1}(\Omega) & \leqslant \int_{\Omega}\left|u_{p}\right|+\int_{\Omega}\left|\nabla u_{p}\right| \leqslant \frac{1}{p}\left(\int_{\Omega}\left|u_{p}\right|^{p}+\int_{\Omega}\left|\nabla u_{p}\right|^{p}\right)+\frac{2}{p^{\prime}}|\Omega| \\
& =\frac{1}{p} \lambda_{p}(\Omega)+\frac{2}{p^{\prime}}|\Omega| .
\end{aligned}
$$

Then, by (9) it follows that

$$
\begin{equation*}
\lambda_{1}(\Omega)=\lim _{p \downarrow 1} \int_{\Omega}\left|u_{p}\right|+\int_{\Omega}\left|\nabla u_{p}\right| . \tag{16}
\end{equation*}
$$

Moreover, by the compact embedding of $B V(\Omega)$ into $L^{1}(\Omega)$, we can suppose that

$$
\begin{equation*}
u_{p} \rightarrow u \in B V(\Omega) \quad \text { in the } L^{1} \text {-norm and a.e. in } \Omega \tag{17}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla u_{p} \rightarrow D u \quad \text { weakly* as measures. } \tag{18}
\end{equation*}
$$

Then, we have

$$
\begin{equation*}
\exists A:=\lim _{p \downarrow 1} \int_{\Omega}\left|\nabla u_{p}\right|=\lambda_{1}(\Omega)-\int_{\Omega}|u| . \tag{19}
\end{equation*}
$$

On the other hand, by the lower-semi-continuity of the total variation respect the $L^{1}$-norm, we get

$$
\int_{\Omega}|D u| \leqslant \liminf _{p \downarrow 1} \int_{\Omega}\left|\nabla u_{p}\right|=\lambda_{1}(\Omega)-\int_{\Omega}|u| .
$$

Hence,

$$
\begin{equation*}
\int_{\Omega}|D u|+\int_{\Omega}|u| \leqslant \lambda_{1}(\Omega) . \tag{20}
\end{equation*}
$$

We are interested in the problem: When is $u$ a minimizer of the variational problem (1)? In these cases we would find an extremal for our minimization problem (1).

Formally, if we take limit as $p \searrow 1$ in Eq. (15), we get

$$
\left\{\begin{array}{l}
\Delta_{1} u:=\operatorname{div}\left(\frac{D u}{|D u|}\right)=\frac{u}{|u|} \quad \text { in } \Omega,  \tag{21}\\
\frac{D u}{|D u|} \cdot v=\lambda_{1}(\Omega) \frac{u}{|u|} \quad \text { on } \partial \Omega .
\end{array}\right.
$$

Following [2,6] (see also [4]), we give the following definition of solution of problem (21).

Definition 1. A function $u \in B V(\Omega)$ is said to be a solution of problem (21) if there exists $z \in X_{1}(\Omega)$ with $\|z\|_{\infty} \leqslant 1, \tau \in L^{\infty}(\Omega)$ with $\|\tau\|_{\infty} \leqslant 1$ and $\theta \in L^{\infty}(\partial \Omega)$ with $\|\theta\|_{\infty} \leqslant 1$ such that

$$
\begin{align*}
& \operatorname{div}(z)=\tau \quad \text { in } \mathscr{D}^{\prime}(\Omega)  \tag{22}\\
& \tau u=|u| \text { a.e. in } \Omega \quad \text { and } \quad(z, D u)=|D u| \text { as measures, }  \tag{23}\\
& {[z, v]=\lambda_{1}(\Omega) \theta \quad \text { and } \quad \theta u=|u| \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega .} \tag{24}
\end{align*}
$$

Another problem we are interested in is: In what cases is $u$ a solution of problem (21)?
Note that if $v$ is a solution of problem (21) and $\int_{\partial \Omega}|v| \neq 0$, then $w:=v / \int_{\partial \Omega}|v|$ is a minimizer of the variational problem (1). Indeed, multiplying (22) by $v$ and integrating by parts, we have

$$
\begin{aligned}
\int_{\Omega}|v| & =\int_{\Omega} \tau v=\int_{\Omega} \operatorname{div}(z) v=-\int_{\Omega}(z, D v)+\int_{\partial \Omega}[z, v] v \\
& =-\int_{\Omega}|D v|+\lambda_{1}(\Omega) \int_{\partial \Omega}|v|
\end{aligned}
$$

From where it follows that

$$
\lambda_{1}(\Omega)=\int_{\Omega}|w|+\int_{\Omega}|D w| .
$$

Before we solve the above problems, let us study first the equation $\operatorname{div}(z)=1$ with Neumann boundary conditions.

## 3. The equation $\operatorname{div}(z)=1$ with Neumann boundary conditions

Throughout this section we shall denote by $\Omega$ a bounded connected open set in $\mathbb{R}^{N}, N \geqslant 2$, with Lipschitz continuous boundary $\partial \Omega$. Given $g \in L^{\infty}(\partial \Omega)$ with $\|g\|_{\infty}<1$, consider the functional $\left.\left.\mathscr{E}_{g}: L^{2}(\Omega) \rightarrow\right]-\infty,+\infty\right]$ defined by

$$
\mathscr{E}_{g}(u):= \begin{cases}\int_{\Omega}|D u|-\int_{\partial \Omega} g u & \text { if } u \in B V(\Omega) \cap L^{2}(\Omega), \\ +\infty & \text { if } u \notin B V(\Omega)\end{cases}
$$

In [6] it is proved that

$$
\begin{equation*}
\partial \mathscr{E}_{g}=\mathscr{A}_{g}, \tag{25}
\end{equation*}
$$

where $\mathscr{A}_{g}$ is the operator in $L^{2}(\Omega)$ defined by

$$
\begin{aligned}
& (u, v) \in \mathscr{A}_{g} \Longleftrightarrow u \in B V(\Omega) \cap L^{2}(\Omega) \\
& v \in L^{2}(\Omega) \text { and } \exists z \in X_{2}(\Omega),\|z\|_{\infty} \leqslant 1
\end{aligned}
$$

such that

$$
\begin{aligned}
& -\operatorname{div}(z)=v \quad \text { in } \mathscr{D}^{\prime}(\Omega) \\
& (z, D u)=|D u| \quad \text { as measures }
\end{aligned}
$$

and

$$
[z, v]=g \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega .
$$

Let $\psi: L^{2}(\Omega) \rightarrow \mathbb{R}$ the operator defined by

$$
\psi(u):=\frac{1}{2} \int_{\Omega}(u(x)+1)^{2} \mathrm{~d} x .
$$

We have

$$
\begin{aligned}
0=\operatorname{argmin}\left(\mathscr{E}_{g}+\psi\right) & \Longleftrightarrow 0 \in \partial\left(\mathscr{E}_{g}+\psi\right)(0) \\
\Longleftrightarrow-1 \in \partial \mathscr{E}_{g}(0) & \Longleftrightarrow(0,-1) \in \mathscr{A}_{g}
\end{aligned}
$$

Then, by (25), it follows that

$$
\begin{aligned}
& 0=\operatorname{argmin}\left(\mathscr{E}_{g}+\psi\right) \Longleftrightarrow \exists z \in X_{2}(\Omega),\|z\|_{\infty} \leqslant 1, \text { such that } \\
& \operatorname{div}(z)=1 \quad \text { in } \mathscr{D}^{\prime}(\Omega) \\
& {[z, v]=g \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega .}
\end{aligned}
$$

On the other hand, $0=\operatorname{argmin}\left(\mathscr{E}_{g}+\psi\right)$ if and only if

$$
\begin{equation*}
\int_{\Omega}|D u|-\int_{\partial \Omega} g u+\frac{1}{2} \int_{\Omega}(u+1)^{2} \geqslant \frac{1}{2}|\Omega| \quad \forall u \in B V(\Omega) \cap L^{2}(\Omega) . \tag{26}
\end{equation*}
$$

Replacing $u$ by $\varepsilon u$ (where $\varepsilon>0$ ), expanding the $L^{2}$ norm, dividing by $\varepsilon$, and letting $\varepsilon \rightarrow 0^{+}$ we get

$$
\begin{equation*}
\int_{\partial \Omega} g u \leqslant \int_{\Omega}|D u|+\int_{\Omega} u \quad \forall u \in B V(\Omega) \cap L^{2}(\Omega) \tag{27}
\end{equation*}
$$

Consequently we have obtained the following result.
Lemma 1. Let $g \in L^{\infty}(\partial \Omega)$ with $\|g\|_{\infty}<1$. Then the following are equivalent:
(i) there exists $z \in X_{2}(\Omega),\|z\|_{\infty} \leqslant 1$, such that

$$
\begin{aligned}
& \operatorname{div}(z)=1 \quad \text { in } \mathscr{D}^{\prime}(\Omega) \\
& {[z, v]=g \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega .}
\end{aligned}
$$

(ii) Eq. (27) holds.

Working as above but using the functional

$$
\phi(u):=\frac{1}{2} \int_{\Omega}(|u(x)|+1)^{2} \mathrm{~d} x
$$

instead of $\psi$, we obtain the following result.
Lemma 2. Let $g \in L^{\infty}(\partial \Omega)$ with $\|g\|_{\infty}<1$. Then the following are equivalent:
(i) there exist $z \in X_{2}(\Omega),\|z\|_{\infty} \leqslant 1$, and $\tau \in L^{\infty}(\Omega),\|\tau\|_{\infty} \leqslant 1$ such that

$$
\begin{aligned}
& \operatorname{div}(z)=\tau \quad \text { in } \mathscr{D}^{\prime}(\Omega) \\
& {[z, v]=g \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega .}
\end{aligned}
$$

(ii) the following inequality holds

$$
\begin{equation*}
\int_{\partial \Omega} g u \leqslant \int_{\Omega}|D u|+\int_{\Omega}|u| \quad \forall u \in B V(\Omega) \cap L^{2}(\Omega) . \tag{28}
\end{equation*}
$$

We state now the main result of this section.
Theorem 3. Let $\Omega$ be a bounded connected open set in $\mathbb{R}^{N}, N \geqslant 2$, with Lipschitz continuous boundary $\partial \Omega$. Assume that $|\Omega| / P(\Omega) \leqslant \lambda<1$. Then the following are equivalent:
(i) there exist $z \in X_{2}(\Omega),\|z\|_{\infty} \leqslant 1$, such that

$$
\begin{aligned}
& \operatorname{div}(z)=1 \quad \text { in } \mathscr{D}^{\prime}(\Omega), \\
& {[z, v]=\lambda \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega,}
\end{aligned}
$$

(ii)

$$
\begin{equation*}
\lambda \int_{\partial \Omega} u \leqslant \int_{\Omega}|D u|+\int_{\Omega} u \quad \forall u \in B V(\Omega) \cap L^{2}(\Omega), \tag{29}
\end{equation*}
$$

(iii)

$$
\begin{equation*}
\lambda \int_{\partial \Omega} u \leqslant \int_{\Omega}|D u|+\int_{\Omega}|u| \quad \forall u \in B V(\Omega) \cap L^{2}(\Omega), \tag{30}
\end{equation*}
$$

(iv)

$$
\begin{equation*}
\lambda \leqslant \lambda_{1}(\Omega) \tag{31}
\end{equation*}
$$

(v)

$$
\begin{equation*}
\left||E|-\lambda \mathscr{H}^{N-1}\left(\partial^{*} E \cap \partial \Omega\right)\right| \leqslant P(E, \Omega) \quad \forall E \in \mathscr{P}_{f}(\Omega) \tag{32}
\end{equation*}
$$

Proof. By Lemma 1 with $g=\lambda$, (i) and (ii) are equivalent. Obviously, (iii) and (iv) are equivalent, and (ii) implies (iii). Let us see that (iii) implies (v). Taking $u=\chi_{E}$ in (30), with $E \subset \Omega$ a set of finite perimeter, it follows that

$$
-\left[|E|-\lambda \mathscr{H}^{N-1}\left(\partial^{*} E \cap \partial \Omega\right)\right] \leqslant P(E, \Omega)
$$

and taking $u=\chi_{\Omega} \backslash \chi_{E}$, we get

$$
\lambda \mathscr{H}^{N-1}\left(\partial^{*}(\Omega \backslash E) \cap \partial \Omega\right) \leqslant P(\Omega \backslash E, \Omega)+|\Omega \backslash E| .
$$

Now, since $P(\Omega \backslash E, \Omega)=P(E, \Omega)$ and $\mathscr{H}^{N-1}\left(\partial^{*}(\Omega \backslash E) \cap \partial \Omega\right)=P(\Omega)-\mathscr{H}^{N-1}\left(\partial^{*} E \cap \partial \Omega\right)$, we have

$$
\lambda\left[P(\Omega)-\mathscr{H}^{N-1}\left(\partial^{*} E \cap \partial \Omega\right)\right] \leqslant P(E, \Omega)+|\Omega|-|E|
$$

Then, since $\lambda \geqslant|\Omega| / P(\Omega)$, we obtain

$$
|E|-\lambda \mathscr{H}^{N-1}\left(\partial^{*} E \cap \partial \Omega\right) \leqslant P(E, \Omega)
$$

and (v) holds. Finally, let us see that (v) implies (ii). Given $u \in B V(\Omega)$, since for all $x \in \Omega$,

$$
u(x)=\int_{0}^{+\infty} \chi_{\{u>t\}}(x) \mathrm{d} t-\int_{-\infty}^{0} \chi_{\{u \leqslant t\}}(x) \mathrm{d} t
$$

using (32) and the coarea formula we get

$$
\begin{aligned}
\int_{\Omega} u(x) \mathrm{d} x= & \int_{0}^{+\infty} \int_{\Omega} \chi_{\{u>t\}}(x) \mathrm{d} x \mathrm{~d} t-\int_{-\infty}^{0} \int_{\Omega} \chi_{\{u \leqslant t\}}(x) \mathrm{d} x \mathrm{~d} t \\
= & \int_{0}^{+\infty}|\{u>t\}| \mathrm{d} t-\int_{-\infty}^{0}|\{u \leqslant t\}| \mathrm{d} t \\
\geqslant & \int_{0}^{+\infty}\left(\lambda \mathscr{H}^{N-1}\left(\partial^{*}\{u>t\} \cap \partial \Omega\right)-P(\{u>t\}, \Omega)\right) \mathrm{d} t \\
& -\int_{-\infty}^{0}\left(\lambda \mathscr{H}^{N-1}\left(\partial^{*}\{u \leqslant t\} \cap \partial \Omega\right)+P(\{u \leqslant t\}, \Omega)\right) \mathrm{d} t \\
= & \lambda \int_{\partial \Omega} u \mathrm{~d} \mathscr{H}^{N-1}-\int_{-\infty}^{+\infty} P(\{u>t\}, \Omega) \mathrm{d} t \\
= & \lambda \int_{\partial \Omega} u \mathrm{~d} \mathscr{H}^{N-1}-\int_{\Omega}|D u|
\end{aligned}
$$

and (29) holds.
Taking $\lambda=|\Omega| / P(\Omega)$ in the above theorem we obtain the following result.
Corollary 1. Let $\Omega$ be a bounded connected open set in $\mathbb{R}^{N}, N \geqslant 2$, with Lipschitz continuous boundary $\partial \Omega$. If $|\Omega| / P(\Omega)<1$, then the following are equivalent:
(i)

$$
\begin{align*}
& \exists z \in X_{2}(\Omega), \quad\|z\|_{\infty} \leqslant 1, \text { such that } \\
& \operatorname{div}(z)=1 \text { in } \mathscr{D}^{\prime}(\Omega), \\
& {[z, v]=\frac{|\Omega|}{P(\Omega)} \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega,} \tag{33}
\end{align*}
$$

(ii)

$$
\lambda_{1}(\Omega)=\frac{|\Omega|}{P(\Omega)}
$$

(iii)

$$
\left||E|-\frac{|\Omega|}{P(\Omega)} \mathscr{H}^{N-1}\left(\partial^{*} E \cap \partial \Omega\right)\right| \leqslant P(E, \Omega) \quad \forall E \in \mathscr{P}_{f}(\Omega)
$$

We do not know if the assumption $\Omega$ connected in Corollary 1 is necessary. So, a natural question is the following: Is there a nonconnected open bounded set $\Omega$ such that $|\Omega| / P(\Omega)<1$, verifying (33) and $\lambda_{1}(\Omega)<|\Omega| / P(\Omega)$ ?

There are open sets $\Omega$ for which (33) holds and $|\Omega| / P(\Omega)=1$, as the following examples show.

Example 1. Let $\Omega=B_{R}(0) \subset \mathbb{R}^{N}$ the ball in $\mathbb{R}^{N}$ centered in 0 of radius $R$. Then, if $z(x):=x / N$, we have

$$
\operatorname{div}(z)=1 \quad \text { in } \mathscr{D}^{\prime}(\Omega)
$$

and

$$
[z, v]=\frac{R}{N}=\frac{|\Omega|}{P(\Omega)} \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega .
$$

Moreover,

$$
\|z\|_{\infty}=\frac{R}{N} \leqslant 1 \Longleftrightarrow \frac{|\Omega|}{P(\Omega)} \leqslant 1
$$

Example 2. Let $\Omega=B_{R}(0) \backslash \overline{B_{r}(0)} \subset \mathbb{R}^{N}$ the annulus in $\mathbb{R}^{N}$ centered in 0 of radius $R$ and $r$. Then, it is easy to see that if

$$
z(x):=\left[\left(R^{N-1}+r^{N-1}\right)-(R+r) \frac{r^{N-1} R^{N-1}}{\|x\|^{N}}\right] \frac{x}{N\left(R^{N-1}+r^{N-1}\right)}
$$

we have

$$
\operatorname{div}(z)=1 \quad \text { in } \mathscr{D}^{\prime}(\Omega)
$$

and

$$
[z, v]=\frac{|\Omega|}{P(\Omega)} \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega
$$

Moreover,

$$
\|z\|_{\infty} \leqslant 1 \Longleftrightarrow \frac{|\Omega|}{P(\Omega)} \leqslant 1
$$

Remark 1. Motron in [12] proves that if $\Omega=B_{R}(0)$ is the ball in $\mathbb{R}^{N}$ centered in 0 of radius $R$ or $\Omega=B_{R}(0) \backslash \overline{B_{r}(0)}$ the annulus in $\mathbb{R}^{N}$ centered in 0 of radius $R$ and $r$, then

$$
\begin{equation*}
\int_{\partial \Omega}|u| \leqslant \frac{P(\Omega)}{|\Omega|} \int_{\Omega}|u|+\int_{\Omega}|\nabla u| \quad \forall u \in W^{1,1}(\Omega) \tag{34}
\end{equation*}
$$

and equality holds in (34) if and only if $u$ is constant.
From (10) and (34), it follows that if $\Omega=B_{R}(0) \subset \mathbb{R}^{N}$ or $\Omega=B_{R}(0) \backslash \overline{B_{r}(0)} \subset \mathbb{R}^{N}$, then

$$
\lambda_{1}(\Omega)= \begin{cases}\frac{|\Omega|}{P(\Omega)} & \text { if } \frac{|\Omega|}{P(\Omega)} \leqslant 1 \\ 1 & \text { if } \frac{|\Omega|}{P(\Omega)} \geqslant 1\end{cases}
$$

Moreover, if $|\Omega| / P(\Omega) \leqslant 1$, then $u=(1 / P(\Omega)) \chi_{\Omega}$ is a minimizer of the variational problem (1), being the only minimizer in the case $|\Omega| / P(\Omega)=1$, and if $|\Omega| / P(\Omega)>1$, the variational problem (1) does not have minimizer.

In the following example we show that there exists bounded connected open sets $\Omega$, with $|\Omega| / P(\Omega)<1$, for which $\lambda_{1}(\Omega)<|\Omega| / P(\Omega)$.

Example 3. For $\delta>0$ and $0<\alpha \leqslant \pi / 2$, let

$$
\begin{aligned}
\Omega_{\delta, \alpha}:= & B_{1}(0) \cup\left(B_{2+\delta}(0) \backslash \overline{B_{2}(0)}\right) \\
& \cup\left\{(x, y) \in \mathbb{R}^{+} \times \mathbb{R}^{+}: x^{2}+y^{2} \leqslant 2, \operatorname{arctg}\left(\frac{y}{x}\right)<\alpha\right\} .
\end{aligned}
$$

We have

$$
\frac{\left|\Omega_{\delta, \alpha}\right|}{P\left(\Omega_{\delta, \alpha}\right)}=\frac{\pi+\pi\left(\delta^{2}+4 \delta\right)+\frac{3}{2} \alpha}{10 \pi+2 \pi \delta+2-3 \alpha} .
$$

Thus, for $0<\delta \leqslant 1$ and $0<\alpha \leqslant \pi / 2$, we have

$$
\frac{\left|\Omega_{\delta, \alpha}\right|}{P\left(\Omega_{\delta, \alpha}\right)}<1
$$

Now, if we take $u:=\chi_{B_{2+\delta}(0) \backslash \overline{B_{2}(0)}}$,

$$
\lambda_{1}\left(\Omega_{\delta, \alpha}\right) \leqslant \frac{\int_{\Omega_{\delta, \alpha}}|D u|+\int_{\Omega_{\delta, \alpha}}|u|}{\int_{\partial \Omega_{\delta, \alpha}}|u|}=\frac{2 \alpha+\pi\left(\delta^{2}+4 \delta\right)}{8 \pi+2 \delta \pi-2 \alpha} .
$$

Then, it is easy to see that for $\delta$ and $\alpha$ small enough, we get

$$
\lambda_{1}\left(\Omega_{\delta, \alpha}\right)<\frac{\left|\Omega_{\delta, \alpha}\right|}{P\left(\Omega_{\delta, \alpha}\right)}<1
$$

In the next example we will see that even we can take $\Omega$ convex.


Fig. 1. Triangle.

Example 4. Let $\Omega$ be the set in $\mathbb{R}^{2}$ with the boundary isosceles triangle with height $k$, base of length $2 a$ and the two equal sides of length $l$. Let $t$ the angle between the height and one of the equal side (see Fig. 1). Then,

$$
\frac{|\Omega|}{P(\Omega)}=\frac{a k}{2(a+l)}=\frac{a k}{a 2(a+a / \sin t)}=\frac{k \sin t}{2(1+\sin t)}
$$

Let $E \subset \Omega$ the set with boundary the isosceles triangle with height $k-r$, base of length $2 b$ and the two equal sides of length $\tilde{l}$. Then, if $u:=\chi_{E}$, we have

$$
\lambda_{1}(\Omega) \leqslant \frac{\int_{\Omega}|D u|+\int_{\Omega}|u|}{\int_{\partial \Omega}|u|}=\frac{2 b+b(k-r)}{2 \tilde{l}}=\frac{b(k+2-r)}{2 b / \sin t}=\frac{\sin t}{2}(k+2-r) .
$$

Hence,

$$
\lambda_{1}(\Omega)<\frac{|\Omega|}{P(\Omega)}<1
$$

if

$$
k<\min \left\{(r-2) \frac{1+\sin t}{\sin t}, 2 \frac{1+\sin t}{\sin t}\right\} .
$$

Now, obviously, we can find $k, r$, and $t$ satisfying the above inequality, and consequently, we can obtain a convex, bounded open set $\Omega$ satisfying

$$
\lambda_{1}(\Omega)<\frac{|\Omega|}{P(\Omega)}<1
$$

The next example show the necessity of the assumption $\Omega$ connected in Lemma 2.
Example 5. For $0<\rho<r$ and $\delta>0$, let

$$
\Omega_{\rho, r, \delta}:=B_{\rho}(0) \cup\left(B_{r+\delta}(0) \backslash B_{r}(0)\right) \subset \mathbb{R}^{2}
$$

We have

$$
\frac{\left|\Omega_{\rho, r, \delta}\right|}{P\left(\Omega_{\rho, r, \delta}\right)}=\frac{\delta^{2}+\rho^{2}+2 r \delta}{2(2 r+\delta+\rho)}
$$

If we take $u:=\chi_{B_{\rho}(0)}$ and $v:=\chi_{B_{r+\delta}(0) \backslash \overline{B_{r}(0)}}$, then

$$
\Phi(u):=\frac{\int_{\Omega_{\rho, r, \delta}}|D u|+\int_{\Omega_{\rho, r, \delta}}|u|}{\int \partial \Omega_{\rho, r, \delta}|u|}=\frac{\rho}{2}
$$

and

$$
\Phi(v):=\frac{\int_{\Omega_{\rho, r, \delta}}|D v|+\int_{\Omega_{\rho, r, \delta}}|v|}{\int_{\partial \Omega_{\rho, r, \delta}}|v|}=\frac{\delta}{2} .
$$

Suppose that $0<\rho<\delta \leqslant 2$. If we consider the vector field $z$ in $\Omega_{\rho, r, \delta}$ defined by

$$
z(x, y):=\left\{\begin{array}{l}
\frac{\delta(x, y)}{2 \rho} \quad \text { if }(x, y) \in B_{\rho}(0) \\
{\left[\delta-(\delta+2 r) \frac{r(r+\delta)}{\|(x, y)\|}\right] \frac{(x, y)}{2(2 r+\delta)} \quad \text { if }(x, y) \in B_{r+\delta}(0) \backslash B_{r}(0),}
\end{array}\right.
$$

we have $\|z\|_{\infty} \leqslant 1$,

$$
\operatorname{div}(z)=\tau \quad \text { in } \mathscr{D}^{\prime}\left(\Omega_{\rho, r, \delta}\right)
$$

with

$$
\tau=\frac{\delta}{\rho} \chi_{\partial B_{\rho}(0)}+\chi_{B_{r+\rho}(0) \backslash B_{r}(0)}
$$

and

$$
[z, v]=\frac{\delta}{2} \mathscr{H}^{1} \text {-a.e. on } \partial \Omega_{\rho, r, \rho}
$$

Now,

$$
\lambda_{1}(\Omega) \leqslant \Phi(u)=\frac{\rho}{2} .
$$

Hence,

$$
\lambda_{1}(\Omega)<\frac{\delta}{2} .
$$

Consequently, in general, Lemma 2 it is not true if $\Omega$ is not connected.
If $\delta=\rho$, we have

$$
\lambda_{1}\left(\Omega_{\rho, r, \rho}\right) \leqslant \Phi(u)=\Phi(v)=\Phi\left(\chi_{\Omega_{\rho, r, \rho}}\right)=\frac{\left|\Omega_{\rho, r, \rho}\right|}{P\left(\Omega_{\rho, r, \rho}\right)}=\frac{\rho}{2}
$$

Suppose that $\rho \leqslant 1$. Then, if we consider the vector field $z$ in $\Omega_{\rho, r, \rho}$ defined by

$$
z(x, y):= \begin{cases}\frac{(x, y)}{2} & \text { if }(x, y) \in B_{\rho}(0) \\ 0 & \text { if }(x, y) \in B_{r+\rho}(0) \backslash B_{r}(0),\end{cases}
$$

we have

$$
\operatorname{div}(z)=\chi_{B_{\rho}(0)} \quad \text { in } \mathscr{D}^{\prime}\left(\Omega_{\rho, r, \rho}\right)
$$

and

$$
[z, v]=\frac{\rho}{2} \chi_{\partial B_{\rho}(0)} \mathscr{H}^{1} \text {-a.e. on } \partial \Omega_{\rho, r, \rho} .
$$

Therefore, $u$ is a solution of the problem

$$
\left\{\begin{array}{l}
\Delta_{1} w:=\operatorname{div}\left(\frac{D w}{|D u|}\right)=\frac{w}{|w|} \quad \text { in } \Omega_{\rho, r, \rho}  \tag{35}\\
\frac{D w}{|D w|} \cdot v=\frac{\rho}{2} \frac{w}{|w|} \quad \text { on } \partial \Omega_{\rho, r, \rho}
\end{array}\right.
$$

Now, if we consider the vector field $z$ in $\Omega_{\rho, r, \rho}$ defined by

$$
z(x, y):=\left\{\begin{array}{l}
0 \quad \text { if }(x, y) \in B_{\rho}(0) \\
{\left[\rho-(\rho+2 r) \frac{r(r+\rho)}{\|(x, y)\|}\right] \frac{(x, y)}{2(2 r+\rho)} \quad \text { if }(x, y) \in B_{r+\rho}(0) \backslash B_{r}(0),}
\end{array}\right.
$$

we have

$$
\operatorname{div}(z)=\chi_{B_{r+\rho}(0) \backslash B_{r}(0)} \quad \text { in } \mathscr{D}^{\prime}\left(\Omega_{\rho, r, \rho}\right)
$$

and

$$
[z, v]=\frac{\rho}{2} \chi_{\partial\left(B_{r+\rho}(0) \backslash B_{r}(0)\right)} \mathscr{H}^{1} \text {-a.e. on } \partial \Omega_{\rho, r, \rho} .
$$

Therefore, $v$ is also a solution of problem (35). Moreover, in this case also $\chi_{\Omega_{\rho, r, \rho}}$ is a solution of problem (35).

Problem. Is $\lambda_{1}\left(\Omega_{\rho, r, \rho}\right)=\rho / 2$ ?
The next example shows that there are bounded connected open sets, $\Omega$ for which $\lambda_{1}(\Omega)<1$ and $|\Omega| / P(\Omega)>1$.

Example 6. Let $\Omega:=]-k, 0[\times] 0, k[\cup\{0\} \times] 0, \delta[\cup] 0,1[\times] 0, \delta\left[\subset \mathbb{R}^{2}\right.$ be. Then

$$
\frac{|\Omega|}{P(\Omega)}=\frac{k^{2}+\delta}{4 k+2}>1 \quad \text { if } k>2+\sqrt{6-\delta}
$$

Now, if we take $u:=\chi_{] 0,1[\times] 0, \delta[ }$, we have

$$
\lambda_{1}(\Omega) \leqslant \frac{\int_{\Omega}|D u|+\int_{\Omega}|u|}{\int_{\partial \Omega}|u|}=\frac{2 \delta}{2+\delta}<1 \Longleftrightarrow 0<\delta<2 .
$$

Therefore, for instance, if $\delta=1$ and $k=5$, we have $|\Omega| / P(\Omega)>1$ and $\lambda_{1}(\Omega)<1$.

## 4. Proof of Theorem 2

Let $\Omega$ be a bounded connected open set in $\mathbb{R}^{N}, N \geqslant 2$, with Lipschitz continuous boundary $\partial \Omega$. By Lemma 2, if we assume that $\lambda_{1}(\Omega)<1$, there exist $\bar{z} \in X_{2}(\Omega),\|\bar{z}\|_{\infty} \leqslant 1$, and $\|\operatorname{div}(\bar{z})\|_{\infty} \leqslant 1$ such that

$$
[\bar{z}, v]=\lambda_{1}(\Omega) \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega
$$

We recall the following definition.
Definition 2. Let $\Omega$ be a bounded open set in $\mathbb{R}^{N}$ with Lipschitz continuous boundary $\partial \Omega$. We shall say that $\Omega$ has the trace-property if there exists a vector field $z \Omega \in L^{\infty}\left(\Omega, \mathbb{R}^{N}\right)$, with $\left\|z_{\Omega}\right\|_{\infty} \leqslant 1$ such that $\operatorname{div}\left(z_{\Omega}\right) \in L^{\infty}(\Omega)$ and

$$
\left[z_{\Omega}, v\right]=\lambda_{1}(\Omega) \mathscr{H}^{N-1} \text {-a.e.on } \partial \Omega
$$

By the above, we have that every bounded connected open set $\Omega$ in $\mathbb{R}^{N}, N \geqslant 2$, with Lipschitz continuous boundary and $\lambda_{1}(\Omega)<1$, has the trace-property. Also, as a consequence of Examples 1, 2, and Remark 1, we have that if $\Omega=B_{R}(0) \subset \mathbb{R}^{N}$ or $\Omega=B_{R}(0) \backslash \overline{B_{r}(0)} \subset \mathbb{R}^{N}$, and $|\Omega| / P(\Omega) \leqslant 1$, then $\Omega$ has the trace-property. Therefore there exists $\Omega$ with $\lambda_{1}(\Omega)=1$ satisfying the trace-property.

Let us present some examples of planar domains that verify $\lambda_{1}(\Omega)<1$.
Example 7. Assume that $\Omega \subset \mathbb{R}^{2}$ is a bounded open set such that there exists some point, $x_{0} \in \partial \Omega$ (we may assume $x_{0}=0$ ), with curvature of the boundary at that point greater than 2 , we will show that in this case $\lambda_{1}(\Omega)<1$. So, let us assume that locally near the origin $\Omega$ can be described as $\Omega \cap B_{r}(0)=\left\{(x, y): y>a x^{2}\right\}$. As we are assuming that the curvature at the origin is greater than 2 we have $a>1$. Let us consider the function $u_{\varepsilon}=\chi_{\Omega \cap\{y<\varepsilon\}}$ as a test function to estimate $\lambda_{1}$. We have

$$
\begin{aligned}
\lambda_{1}(\Omega) & \leqslant \frac{\int_{\Omega}\left|D u_{\varepsilon}\right|+\int_{\Omega}\left|u_{\varepsilon}\right|}{\int_{\partial \Omega}\left|u_{\varepsilon}\right|}=\frac{\sqrt{\varepsilon / a}+\int_{0}^{\sqrt{\varepsilon / a}}\left(\varepsilon-a s^{2}\right) \mathrm{d} s}{\int_{0}^{\sqrt{\varepsilon / a}} \sqrt{1+(2 a)^{2} s^{2}} \mathrm{~d} s} \\
& =\frac{\sqrt{\varepsilon / a}+\frac{2}{3} \varepsilon \sqrt{\varepsilon / a}}{\int_{0}^{\sqrt{\varepsilon / a}}\left(1+2 a^{2} s^{2}+O\left(s^{3}\right)\right) \mathrm{d} s}<1
\end{aligned}
$$

if $\varepsilon$ is small enough.
Remark that if $\Omega=B_{R}(0)$ we have that the curvature is $1 / R$ and, by Example 1 , we have $\lambda_{1}\left(B_{R}(0)\right)<1$ if and only if $R<2$. Hence, some restriction on the curvature must be imposed.

Next we prove that on every domain that enjoys the trace-property the best Sobolev trace constant is attained, Theorem 2.

Proof of Theorem 2. First let us see that the function $u$ obtained in (17) is a minimizer of the variational problem (1). Let $z_{\Omega}$ be the vector field given in Definition 2. Then, by (18),
we have

$$
\begin{aligned}
\int_{\Omega}\left(z_{\Omega}, D u\right) & =\lim _{p \searrow 1} \int_{\Omega}\left(z_{\Omega}, \nabla u_{p}\right)=\lim _{p \searrow 1}\left(-\int_{\Omega} \operatorname{div}\left(z_{\Omega}\right) u_{p}+\int_{\partial \Omega}\left[z_{\Omega}, v\right] u_{p}\right) \\
& =-\int_{\Omega} \operatorname{div}\left(z_{\Omega}\right) u+\lambda_{1}(\Omega)=\int_{\Omega}\left(z_{\Omega}, D u\right)-\lambda_{1}(\Omega) \int_{\partial \Omega} u+\lambda_{1}(\Omega)
\end{aligned}
$$

from where it follows that

$$
\begin{equation*}
\int_{\partial \Omega}|u|=1 \tag{36}
\end{equation*}
$$

Therefore, by (20) we get that $u$ is a minimizer of (1). Moreover, by (19), it follows that

$$
\begin{equation*}
\lim _{p \searrow 1} \int_{\Omega}\left|\nabla u_{p}\right|=\lambda_{1}(\Omega)-\int_{\Omega}|u|=\int_{\Omega}|D u| . \tag{37}
\end{equation*}
$$

Hence $u_{p} \rightarrow u$ respect to the strict convergence, and consequently

$$
\begin{equation*}
u_{p} \rightarrow u \quad \text { in } L^{1}(\partial \Omega) \text { as } p \searrow 1 . \tag{38}
\end{equation*}
$$

Let us see now that the function $u$ is a solution of problem (21). By Hölder's inequality, we have

$$
\begin{equation*}
\int_{\Omega}\left|u_{p}\right|^{p-1} \leqslant|\Omega|^{1 / p}\left(\int_{\Omega}\left|u_{p}\right|^{p}\right)^{(p-1) / p} \leqslant|\Omega|^{1 / p} \lambda_{p}(\Omega)^{(p-1) / p} \leqslant M_{1} . \tag{39}
\end{equation*}
$$

On the other hand, if $E$ is a measurable subset of $\Omega$ with $|E|<1$, we have

$$
\begin{equation*}
\left.\left.\left|\int_{E}\right| u_{p}\right|^{p-2} u_{p}\left|\leqslant \int_{E}\right| u_{p}\right|^{p-1} \leqslant M_{2}|E|^{1 / p} . \tag{40}
\end{equation*}
$$

By (39) and (40), it follows that $\left\{\left|u_{p}\right|^{p-2} u_{p}: 1<p \leqslant 2\right\}$ is a weakly relatively compact subset of $L^{1}(\Omega)$. Hence, we can assume that there exists $\tau \in L^{1}(\Omega)$ such that

$$
\begin{equation*}
\left|u_{p}\right|^{p-2} u_{p} \rightarrow \tau \quad \text { weakly in } L^{1}(\Omega) \text { as } p \searrow 1 \tag{41}
\end{equation*}
$$

In a similar way, it is easy to see that there exists $z \in L^{1}\left(\Omega, \mathbb{R}^{N}\right)$ such that

$$
\begin{equation*}
\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \rightarrow z \quad \text { weakly in } L^{1}\left(\Omega, \mathbb{R}^{N}\right) \text { as } p \searrow 1 . \tag{42}
\end{equation*}
$$

Now, given $\varphi \in \mathscr{D}(\Omega)$, from (41) and (42), it follows that

$$
\begin{aligned}
\langle\operatorname{div}(z), \varphi\rangle & =-\int_{\Omega} z \cdot \nabla \varphi=-\lim _{p \searrow 1} \int_{\Omega}\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \cdot \nabla \varphi \\
& =\lim _{p \searrow 1} \int_{\Omega} \operatorname{div}\left(\left|\nabla u_{p}\right|^{p-2} \nabla u_{p}\right) \varphi=\lim _{p \searrow 1} \int_{\Omega}\left|u_{p}\right|^{p-2} u_{p} \varphi=\int_{\Omega} \tau \varphi .
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\operatorname{div}(z)=\tau \quad \text { in } \mathscr{D}^{\prime}(\Omega) \tag{43}
\end{equation*}
$$

We claim now that

$$
\begin{equation*}
\|z\|_{\infty} \leqslant 1 \tag{44}
\end{equation*}
$$

In fact, for any $k>0$, let

$$
B_{p, k}:=\left\{x \in \Omega:\left|\nabla u_{p}(x)\right|>k\right\} .
$$

As above, there exists some $g_{k} \in L^{1}\left(\Omega, \mathbb{R}^{N}\right)$ such that

$$
\begin{equation*}
\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \chi_{B_{p, k}} \rightarrow g_{k} \quad \text { weakly in } L^{1}\left(\Omega, \mathbb{R}^{N}\right) \text { as } p \searrow 1 . \tag{45}
\end{equation*}
$$

Now, since

$$
\left|B_{p, k}\right|=\int_{\Omega} \chi_{B_{p, k}}(x) \mathrm{d} x \leqslant \int_{\Omega} \frac{\left|\nabla u_{p}(x)\right|^{p}}{k^{p}} \mathrm{~d} x \leqslant \frac{\lambda_{p}(\Omega)}{k^{p}}
$$

for any $\phi \in L^{\infty}(\Omega)$ with $\|\phi\|_{\infty} \leqslant 1$, we have

$$
\begin{aligned}
\left.\left|\int_{\Omega}\right| \nabla u_{p}\right|^{p-2} \nabla u_{p} \cdot \phi \chi_{B_{p, k}} \mid & \leqslant\left(\int_{\Omega}\left|\nabla u_{p}\right|^{p}\right)^{(p-1) / p}\left|B_{p, k}\right|^{1 / p} \\
& \leqslant \lambda_{p}(\Omega)^{(p-1) / p}\left(\frac{\lambda_{p}(\Omega)}{k^{p}}\right)^{1 / p}=\frac{\lambda_{p}(\Omega)}{k} .
\end{aligned}
$$

Letting $p \searrow 1$, we get that

$$
\begin{equation*}
\int_{\Omega}\left|g_{k}\right| \leqslant \frac{\lambda_{1}(\Omega)}{k} \quad \text { for every } k>0 \tag{46}
\end{equation*}
$$

On the other hand, since we have

$$
\left|\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \chi_{\Omega \backslash B_{p, k}}\right| \leqslant k^{p-1} \quad \text { for any } p>1,
$$

letting $p \searrow 1$, we obtain that there exists some $f_{k} \in L^{1}\left(\Omega, \mathbb{R}^{N}\right)$ with $\left\|f_{k}\right\|_{\infty} \leqslant 1$ such that

$$
\begin{equation*}
\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \chi_{\Omega \backslash B_{p, k}} \rightarrow f_{k} \quad \text { weakly in } L^{1}\left(\Omega, \mathbb{R}^{N}\right) \text { as } p \searrow 1 . \tag{47}
\end{equation*}
$$

Hence, for any $k>0$, we may write $z=f_{k}+g_{k}$, with $\left\|f_{k}\right\|_{\infty} \leqslant 1$ and $g_{k}$ satisfying (46). From where (44) follows.

Since $u_{p} \rightarrow u$ a.e. in $\Omega$, by (41) it follows that

$$
\tau u=|u| \text { a.e. in } \Omega \quad \text { and } \quad\|\tau\|_{\infty} \leqslant 1
$$

On the other hand, given a measurable subset $E \subset \partial \Omega$, by Hölder's inequality we have

$$
\int_{E} u_{p}^{p-1} \mathrm{~d} \mathscr{H}^{N-1} \leqslant\left(\int_{\partial \Omega} u_{p} \mathrm{~d} \mathscr{H}^{N-1}\right)^{p-1} \mathscr{H}^{N-1}(E)^{2-p} \leqslant \mathscr{H}^{N-1}(E)^{2-p}
$$

from where it follows that $\left\{u_{p}^{p-1}: 1<p \leqslant 2\right\}$ is a weakly relatively compact subset of $L^{1}(\partial \Omega)$. Hence, we can assume that there exists $\theta \in L^{1}(\partial \Omega)$, such that

$$
\begin{equation*}
u_{p}^{p-1} \rightarrow \theta \quad \text { weakly in } L^{1}(\partial \Omega) \tag{48}
\end{equation*}
$$

Moreover, by (48), (14) and applying Fatou's Lemma, it is easy to see that

$$
\begin{equation*}
\|\theta\|_{\infty} \leqslant 1 \tag{49}
\end{equation*}
$$

On the other hand, by (38) and (48), we get

$$
\begin{equation*}
\theta u=|u| \mathscr{H}^{N-1} \text {-a.e. on } \partial \Omega . \tag{50}
\end{equation*}
$$

Now, since $u_{p}$ is a weak solution of (15), having in mind (41), (9) and (48), if $w \in W^{1,1}(\Omega) \cap$ $C(\Omega) \cap L^{\infty}(\Omega)$, we have

$$
\begin{aligned}
\langle z, w\rangle_{\partial \Omega} & :=\int_{\Omega} \operatorname{div}(z) w+\int_{\Omega} z \cdot \nabla w=\int_{\Omega} \tau w+\int_{\Omega} z \cdot \nabla w \\
& =\lim _{p \searrow 1} \int_{\Omega} u_{p}^{p-1} w+\int_{\Omega}\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \cdot \nabla w \\
& =\lim _{p \searrow 1} \int_{\Omega} u_{p}^{p-1} w-\int_{\Omega} \operatorname{div}\left(\left|\nabla u_{p}\right|^{p-2} \nabla u_{p}\right) w+\int_{\partial \Omega}\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \cdot v w \\
& =\lim _{p \searrow 1} \lambda_{p}(\Omega) \int_{\partial \Omega} u_{p}^{p-1} w=\lambda_{1}(\Omega) \int_{\partial \Omega} \theta w
\end{aligned}
$$

Thus, having in mind the definition of the weak trace on $\partial \Omega$ of the normal component of $z$ given in [5], we get

$$
\begin{equation*}
[z, v]=\lambda_{1}(\Omega) \theta \tag{51}
\end{equation*}
$$

Finally, since

$$
\begin{aligned}
\int_{\Omega}|D u| & =\lambda_{1}(\Omega)-\int_{\Omega}|u|=\lambda_{1}(\Omega)-\int_{\Omega} \tau u \\
& =\lambda_{1}(\Omega)-\int_{\Omega} \operatorname{div}(z) u=\lambda_{1}(\Omega)+\int_{\Omega}(z, D u)-\int_{\partial \Omega}[z, v] u \\
& =\lambda_{1}(\Omega)+\int_{\Omega}(z, D u)-\lambda_{1}(\Omega) \int_{\partial \Omega} \theta u=\int_{\Omega}(z, D u),
\end{aligned}
$$

we have $(z, D u)=|D u|$ as measures.
Remark 2. Let us remark that as a consequence of Theorem 1 in [8] it is obtained the above theorem in the particular case that $\Omega$ is a bounded open subset of $\mathbb{R}^{N}$, whose boundary $\partial \Omega$ is at least piecewise $\mathscr{C}^{2}$ and $\lambda_{1}(\Omega)<1$.

Remark 3. Note that in the above theorem we have proved that if $u$ is the limit as $p \searrow 1$ of the minimizers $u_{p}$ of the variational problem

$$
\begin{equation*}
\inf \left\{\int_{\Omega}|u|^{p}+\int_{\Omega}|\nabla u|^{p}: u \in W^{1, p}(\Omega), \int_{\partial \Omega}|u|=1,\right\} \tag{52}
\end{equation*}
$$

then, if $\int_{\partial \Omega}|u|=1$, we have that $u$ is a minimizer of the variational problem (1) and a solution of problem (21).

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