

Existence and nonexistence of solutions for singular quadratic quasilinear equations

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Abstract

We study both existence and nonexistence of nonnegative solutions for nonlinear elliptic problems with singular lower order terms that have natural growth with respect to the gradient, whose model is

$$\begin{cases} -\Delta u + \frac{|\nabla u|^2}{u^\gamma} = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where Ω is an open bounded subset of \mathbb{R}^N , $\gamma > 0$ and f is a function which is strictly positive on every compactly contained subset of Ω . As a consequence of our main results, we prove that the condition $\gamma < 2$ is necessary and sufficient for the existence of solutions in $H_0^1(\Omega)$ for every sufficiently regular f as above.

Key words: Nonlinear elliptic equations, singular natural growth gradient terms, large solutions.

1. Introduction

In this paper we are going to study existence and nonexistence of nonnegative solutions for the following boundary value problem

$$\begin{cases} -\operatorname{div}(M(x, u)\nabla u) + g(x, u)|\nabla u|^2 = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (1.1)$$

Here Ω is a bounded, open subset of \mathbb{R}^N , $N \geq 3$, $M(x, s) \stackrel{\text{def}}{=} (m_{ij}(x, s))$, $i, j = 1, \dots, N$ is a matrix whose coefficients $m_{ij} : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are Carathéodory

functions (i.e., $m_{ij}(\cdot, s)$ is measurable on Ω for every $s \in \mathbb{R}$, and $m_{ij}(x, \cdot)$ is continuous on \mathbb{R} for a.e. $x \in \Omega$) such that there exist constants $0 < \alpha \leq \beta$ satisfying

$$\alpha|\varsigma|^2 \leq M(x, s)\varsigma \cdot \varsigma \text{ and } |M(x, s)| \leq \beta, \quad \text{for a.e. } x \in \Omega, \forall (s, \varsigma) \in \mathbb{R} \times \mathbb{R}^N. \quad (1.2)$$

The function $g : \Omega \times (0, +\infty) \rightarrow \mathbb{R}$ is a Carathéodory function (i.e., $g(\cdot, s)$ is measurable on Ω for every $s \in (0, +\infty)$, and $g(x, \cdot)$ is continuous on $(0, +\infty)$ for a.e. $x \in \Omega$) such that

$$g(x, s) \geq 0, \quad \text{for a.e. } x \in \Omega, \forall s > 0. \quad (1.3)$$

We will be mainly interested to the case of a function g which is singular near $s = 0$, such as, for example, $g(x, s) = 1/s^\gamma$, $\gamma > 0$. On the datum f , we first suppose that it belongs to $L^{\frac{2N}{N+2}}(\Omega)$ and that it satisfies

$$m_\omega(f) \stackrel{\text{def}}{=} \text{ess inf}\{f(x) : x \in \omega\} > 0, \quad \forall \omega \subset\subset \Omega. \quad (1.4)$$

Note that (1.4) implies that $f \geq 0$ in Ω and that $f \not\equiv 0$ in Ω .

There are several papers concerned with existence and nonexistence of solutions for (1.1). If g is nonsingular, that is if g is a Carathéodory function on $\Omega \times [0, \infty)$, problem (1.1) has been exhaustively studied by Boccardo, Murat and Puel [15], Bensoussan, Boccardo and Murat [7] and Boccardo, Gallouët [11] with data f in suitable Lebesgue spaces.

On the contrary, as stated before, in this paper we shall focus our attention on problem (1.1) with $g(x, s)$ having a singularity at $s = 0$ (uniformly with respect to x). More precisely, we look for a *distributional solution* of problem (1.1), i.e. a function $u \in W_0^{1,1}(\Omega)$ which solves the equation in the sense of distributions, $u > 0$ almost everywhere in Ω , and such that $g(x, u)|\nabla u|^2$ in $L^1(\Omega)$. If moreover $u \in H_0^1(\Omega)$, we say that u is a *finite energy solution* for problem (1.1). A possible motivation for the study of these problems arises from the Calculus of Variations. If $0 \leq f \in L^q(\Omega)$, $q > \frac{N}{2}$ and $\gamma \in (0, 1)$, a purely formal computation shows that the Euler-Lagrange equation associated to the functional

$$J(v) = \frac{1}{2} \int_{\Omega} (1 + |v|^{1-\gamma}) |\nabla v|^2 - \int_{\Omega} f v,$$

is

$$-\text{div}((1 + |u|^{1-\gamma})\nabla u) + \frac{1-\gamma}{2} \frac{u}{|u|^{1+\gamma}} |\nabla u|^2 = f.$$

Observe that this is a nonlinear elliptic equation that involves a singular natural-growth gradient term.

Therefore, it is natural to wonder whether we can handle general not necessarily variational problems whose simplest model is

$$\begin{cases} -\Delta u + \frac{|\nabla u|^2}{u^\gamma} = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.5)$$

and to determine the optimal range of $\gamma > 0$ for which solutions exist.

Recently, existence of solutions for (1.5) has been proved in [1, 2, 3] for $0 < \gamma \leq 1$. We also quote the even more recent papers [8] and [20]. Specifically, the existence of positive solutions of (1.1) is proved in [8] provided $0 \neq f \in L^q(\Omega)$ ($q > 2N/(N+2)$) with $f \geq 0$ and provided $g(x, s) = 1/s^\gamma$ with $\gamma \leq 1$. On the other hand, a related different problem is studied in [20]. Namely, if $\chi_{\{u>0\}}$ denotes the characteristic function of the set $\{x \in \Omega : u(x) > 0\}$, $0 \leq f \in L^\infty(\Omega)$, $\mu \in \mathbb{R}$ and $\lambda, \gamma > 0$, the differential equation

$$-\operatorname{div}(M(x, u)\nabla u) + \lambda u + \mu \frac{|\nabla u|^2}{u^\gamma} \chi_{\{u>0\}} = f$$

is considered. The given results about existence of nonnegative solutions in $H_0^1(\Omega)$ depend on γ . Indeed, existence is proved for every $\mu \in \mathbb{R}$ if $\gamma < 1$, while the case $\gamma \geq 1$ requires that $\mu < 0$. Thus, if $\gamma \geq 1$ the term with quadratic dependence in ∇u is negative (i.e., the opposite assumption with respect to (1.3)). In this direction, result for similar equations can be also found in [21] and [34] (see also references cited therein).

The purpose of this paper is twofold. First of all, we will extend the above results to a more general class of nonlinearities both in the principal part of the operator and in the lower order term, as well as to general, possibly $L^1(\Omega)$, data. Then, we will give a sharp range of nonlinearities $g(x, s)$ for which these problems admit a solution for every datum $f \in L^q(\Omega)$, with $q > N/2$, satisfying (1.4).

In order to prove our results, we will have to strengthen assumption (1.3). Specifically, for the results of existence of solutions, we will suppose that the function $g(x, s)$ satisfies

$$0 \leq g(x, s) \leq h(s), \quad \text{for a.e. } x \in \Omega, \forall s > 0, \quad (1.6)$$

where $h : (0, +\infty) \rightarrow [0, +\infty)$ is a continuous nonnegative function such that

$$\lim_{s \rightarrow 0^+} \int_s^1 \sqrt{h(t)} dt < +\infty, \quad (1.7)$$

$h(s)$ is nonincreasing in a neighborhood of zero.

Our result of existence of finite energy solutions (proved in Section 2) is the following.

Theorem 1.1. *Let f in $L^{\frac{2N}{N+2}}(\Omega)$ be such that (1.4) holds, and suppose that (1.2), (1.6) and (1.7) hold. Then there exists a finite energy solution u for problem (1.1). Furthermore, $u g(x, u) |\nabla u|^2 \in L^1(\Omega)$.*

Note that the fact $u g(x, u) |\nabla u|^2 \in L^1(\Omega)$ implies that the solution u itself is allowed as test function (since $f \in H^{-1}(\Omega)$) in the weak formulation of (1.1) (see (2.1) in Section 2). With respect to the proof, due to the fact that the

lower order term $g(x, u)|\nabla u|^2$ is (possibly) singular as the solution is near 0, we will approximate the function $g(x, s)$ by nonsingular ones $g_n(x, s)$ in such a way that the corresponding approximated problems have finite energy solutions u_n for every n in \mathbb{N} . The main difficulty in the proof of Theorem 1.1 relies on a suitable local uniform estimate from below of these solutions. To do it, it suffices by (1.6) to prove that any supersolution $z > 0$ for the equation

$$-\operatorname{div}(M(x, z)\nabla z) + h(z)|\nabla z|^2 = f \quad \text{in } \Omega$$

is above some positive constant in every $\omega \subset\subset \Omega$, i.e.

$$\forall \omega \subset\subset \Omega \quad \exists c_\omega > 0 : \quad z(x) \geq c_\omega > 0. \quad (1.8)$$

This is proved in Proposition 2.3 via a suitable change of variable which turns the goal into a local L^∞ estimate for solutions of quasilinear problems. The local L^∞ estimate is then obtained using a result of [27] (see also the pioneering paper [17] and also [13, 19]) on an equation whose model is

$$-\operatorname{div}(\widetilde{M}(x, v)\nabla v) + f(x)b(v) = 0 \quad \text{in } \Omega, \quad (1.9)$$

where \widetilde{M} satisfies (1.2) and $b(s)$ is a function with $b(s)/s$ increasing for large $s > 0$ and satisfying the Keller-Osserman condition

$$\int^{+\infty} \frac{dt}{\sqrt{2 \int_0^t b(\tau) d\tau}} < +\infty.$$

For the convenience of the reader, the exact result that we need is proved in the appendix (see Theorem A.1). For such type of L^∞ estimates we refer to the ‘‘classical’’ literature on the so-called large solutions (see, among others, [5, 31, 32, 38]) and on local estimates (see, among others, [13, 17, 19, 27, 37]).

Section 3 of this paper will be concerned with some extensions of the existence result. First of all, combining the above ideas with those in [35] (see also [26]), we handle the case of data f in $L^1(\Omega)$, proving the existence of distributional solutions u of (1.1), with u in $W_0^{1,q}(\Omega)$ for every $q < \frac{N}{N-1}$. More precisely, in Section 3.1, we shall prove the following result.

Theorem 1.2. *Let f in $L^1(\Omega)$ be such that (1.4) holds and suppose that (1.2), (1.6) and (1.7) hold. Then there exists a distributional solution u of (1.1), with u in $W_0^{1,q}(\Omega)$, for every $q < \frac{N}{N-1}$. If, in addition, there exist $s_0 > 0$ and $\mu > 0$ such that*

$$g(x, s) \geq \mu \quad \text{for a.e. } x \in \Omega, \quad \forall s \geq s_0, \quad (1.10)$$

then $u \in H_0^1(\Omega)$ (i.e., it is a finite energy solution).

On the other hand, in Section 3.2, we will also provide an analogous of Theorem 1.1 involving more general differential operators whose principal part

is not in divergence form and data in $L^q(\Omega)$ with $q > \frac{N}{2}$. Namely, we consider the following problem

$$\begin{cases} -\sum_{i,j=1}^N a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j}(x) + \sum_{i=1}^N b_i(x) \frac{\partial u}{\partial x_i}(x) + g(x, u) |\nabla u|^2 = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.11)$$

where the coefficients $a_{ij}(x)$ satisfy the ellipticity condition

$$0 < \alpha |\zeta|^2 \leq \sum_{i,j=1}^N a_{ij}(x) \zeta_i \zeta_j \leq \beta |\zeta|^2, \quad \forall \zeta \in \mathbb{R}^N, \quad (1.12)$$

for some $0 < \alpha \leq \beta$. We prove the following result.

Theorem 1.3. *Suppose that $a_{ij} \in W^{1,\infty}(\Omega)$ satisfy (1.12), and that $b_i \in L^\infty(\Omega)$. Assume that $f(x)$ satisfies (1.4) and belongs to $L^q(\Omega)$ with $q > \frac{N}{2}$. Suppose moreover that $g(x, s)$ satisfies (1.3), (1.6) (with h such that (1.7) holds). Then there exists a solution $u \in H_0^1(\Omega) \cap L^\infty(\Omega)$ for (1.11). Furthermore, $g(x, u) |\nabla u|^2 \in L^1(\Omega)$.*

We are also concerned with nonexistence of positive solutions for problem (1.1) for data f in $L^q(\Omega)$ for some $q > \frac{N}{2}$, with $f \geq 0$ and $f \not\equiv 0$. In contrast with the previous existence results, we will assume in this case that the nonlinearity $g(x, s)$ is above a function $h(s)$ whose square root is not integrable in $(0, 1)$. Specifically, we assume that

$$0 \leq h(s) \leq g(x, s), \quad \text{for a.e. } x \in \Omega, \quad \forall s > 0, \quad (1.13)$$

where $h : (0, +\infty) \rightarrow [0, +\infty)$ is a nonnegative continuous function such that

$$\lim_{s \rightarrow 0^+} h(s) = +\infty, \quad \lim_{s \rightarrow 0^+} \int_s^1 \sqrt{h(t)} dt = +\infty, \quad (1.14)$$

and

$$\lim_{s \rightarrow 0^+} \sqrt{h(s)} e^{\int_1^s \sqrt{h(t)} dt} = h_0 \geq 0. \quad (1.15)$$

Among others, we are going to prove in Section 4 that if $\lambda_1(f)$ denotes the first positive eigenvalue of the laplacian operator $-\Delta$ with zero Dirichlet boundary conditions and weight $f \in L^q(\Omega)$, ($q > N/2$), then the following result holds.

Theorem 1.4. *Let f in $L^q(\Omega)$, with $q > \frac{N}{2}$, be such that $f \geq 0$ and $f \not\equiv 0$, and assume that (1.2), (1.13), (1.14), (1.15) hold. If $\lambda_1(f) > \frac{\beta}{\alpha}$, then (1.1) does not have any finite energy solution.*

As an easy consequence of Theorem 1.4, we will prove (see Corollary 4.5) that the model problem (1.5) does not have any finite energy solution provided

$\gamma \geq 2$. By gathering together this nonexistence result and Theorem 1.1 we conclude immediately that, in the case of the model problem (1.5), we have a sharp range of values of γ for which there exist solutions. In addition, if γ is not in this range, we prove also what happens if we try to approximate problem (1.5) with a sequence of problems for which solutions exist.

Theorem 1.5. *Problem (1.5) has a finite energy solution for every $f \in L^q(\Omega)$ ($q > \frac{N}{2}$) satisfying (1.4) if and only if $\gamma < 2$. Moreover, let λ_1 be the first eigenvalue of the laplacian in the N -dimensional unit ball (i.e. the first positive zero of the Bessel function J_m with $m = N/2 - 1$), assume $f \in L^\infty(\Omega)$, and either*

$$\gamma > 2 \quad \text{or} \quad \gamma = 2 \quad \text{and} \quad \|f\|_{L^\infty(\Omega)} < \frac{\lambda_1}{\text{diam}(\Omega)^2}. \quad (1.16)$$

Then the sequence $\{u_n\}$ of solutions of

$$\begin{cases} -\Delta u_n + \frac{|\nabla u_n|^2}{(u_n + \frac{1}{n})^\gamma} = f & \text{in } \Omega, \\ u_n = 0 & \text{on } \partial\Omega, \end{cases}$$

tends to 0 in $H_0^1(\Omega)$, and the sequence $\frac{|\nabla u_n|^2}{(u_n + \frac{1}{n})^\gamma}$ converges to f in the weak* topology of measures.

To conclude this introduction, some remarks are in order. First, we have to mention that uniqueness of solutions for (1.5) is proved in [4] for the case $0 < \gamma < 1$. Secondly, let us explicitly state that we have chosen to present the results and to perform the proofs in the case $N \geq 3$. However, all the results but Theorem 1.1 hold true also in the case $N = 2$ (with easier proofs). In addition, if $N = 2$ (which implies $\frac{2N}{N+2} = 1$), Theorem 1.1 is also true provided we replace the assumption $f \in L^{\frac{2N}{N+2}}(\Omega)$ with $f \in L^m(\Omega)$, and assume $m > 1$.

The plan of the paper is the following: in Section 2 we will prove a local estimate from below for the solutions, together with Theorem 1.1. Section 3 is devoted to provide further existence results for L^1 data (Theorem 1.2) and operators in non divergence form (Theorem 1.3). In Section 4 we prove the nonexistence result (both theorems 1.4 and 1.5). Finally we present in the Appendix some results related to the local estimate (1.8). For instance, we show in detail how to get the lower bound for solutions of (1.1), through a suitable change of variable, proving a local bound from above for solutions of a semilinear equation whose model is (1.9) (Theorem A.1). Such topic is strictly related to the possibility of constructing estimates for solutions of (1.9) that do not depend on the behavior at the boundary: and indeed in Theorem A.8 we prove the existence of solutions that blow-up at the boundary (i.e., the so-called “large solutions”) for such equations.

Notation. For any $k > 0$ we set $T_k(s) = \min(k, \max(s, -k))$ and $G_k(s) = s - T_k(s)$. Moreover, for any $q > 1$, $q' = \frac{q}{q-1}$ will be the Hölder conjugate

exponent of q , while for any $1 < p < N$, $p^* = \frac{Np}{N-p}$ is the Sobolev conjugate exponent of p . As usual, \mathcal{S} denotes the best Sobolev constant, i.e.,

$$\mathcal{S} = \sup\{\|u\|_{L^{2^*}(\Omega)} : \|u\|_{H_0^1(\Omega)} = 1\}.$$

In Section 3 we will use some ideas related to Marcinkiewicz spaces; for the convenience of the reader we recall here their definition and some properties. For $s > 1$, we denote by $\mathcal{M}^s(\Omega)$ the space of measurable functions $v : \Omega \rightarrow \mathbb{R}$ such that there exists $c > 0$, with

$$\text{meas}\{x \in \Omega : |v(x)| \geq k\} \leq \frac{c}{k^s}, \quad \forall k > 0. \quad (1.17)$$

The space $\mathcal{M}^s(\Omega)$ is a Banach space, and on it can be defined the pseudo-norm

$$\|v\|_{\mathcal{M}^s(\Omega)}^s = \inf\{c > 0 : (1.17) \text{ holds}\}.$$

We also recall that, since Ω is bounded, for every $\varepsilon \in (0, s - 1]$, there exists a positive constant C such that

$$\begin{aligned} \|v\|_{\mathcal{M}^s(\Omega)} &\leq \|v\|_{L^s(\Omega)}, \quad \forall v \in L^s(\Omega) \\ \|w\|_{L^{s-\varepsilon}(\Omega)} &\leq C \|w\|_{\mathcal{M}^s(\Omega)}, \quad \forall w \in \mathcal{M}^s(\Omega). \end{aligned} \quad (1.18)$$

Finally, following [15], we set $\varphi_\lambda(s) = se^{\lambda s^2}$, $\lambda > 0$; in what follows we will use that for every $a, b > 0$ we have

$$a\varphi'_\lambda(s) - b|\varphi_\lambda(s)| \geq \frac{a}{2}, \quad (1.19)$$

if $\lambda > \frac{b^2}{4a^2}$. We will also denote by $\varepsilon(n)$ any quantity that tends to 0 as n diverges.

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2. Finite energy solutions

In this section we will prove the existence of finite energy solutions for problem (1.1). Let us recall its definition.

Definition 2.1. A *supersolution* (resp. *subsolution*) for problem (1.1) is a function $u \in W_{\text{loc}}^{1,1}(\Omega)$ such that

- 1) $u > 0$ almost everywhere in Ω ,
- 2) $g(x, u)|\nabla u|^2$ belongs to $L_{\text{loc}}^1(\Omega)$,
- 3) for every $0 \leq \phi \in C_c^\infty(\Omega)$, it holds

$$\int_{\Omega} M(x, u)\nabla u \cdot \nabla \phi + \int_{\Omega} g(x, u)|\nabla u|^2 \phi \underset{(\leq)}{\geq} \int_{\Omega} f \phi.$$

A function $u \in W_0^{1,1}(\Omega)$ is a *distributional solution* for (1.1) if $g(x, u)|\nabla u|^2$ belongs to $L^1(\Omega)$, and u is both a supersolution and a subsolution for such a problem.

If moreover $u \in H_0^1(\Omega)$, we say that u is a *finite energy solution* for problem (1.1). In this case, we have

$$\int_{\Omega} M(x, u) \nabla u \cdot \nabla \psi + \int_{\Omega} g(x, u) |\nabla u|^2 \psi = \int_{\Omega} f \psi, \quad \forall \psi \in H_0^1(\Omega) \cap L^\infty(\Omega). \quad (2.1)$$

The proof of Theorem 1.1 relies on approximating the datum $f \in L^{\frac{2N}{N+2}}(\Omega)$ by its truncature $f_n = T_n(f)$ and the nonlinearity g by a suitable sequence of Carathéodory functions g_n (for $n \in \mathbb{N}$). Specifically, we define

$$g_n(x, s) \stackrel{\text{def}}{=} \begin{cases} g(x, s) & s \geq \frac{1}{n}, \\ nh \left(\frac{1}{n} \right) \frac{s}{h(s)} g(x, s) & 0 < s \leq \frac{1}{n}, \\ 0 & s \leq 0. \end{cases}$$

Since h is nonincreasing in a neighborhood of zero, we observe that there exists $n_0 \in \mathbb{N}$, such that g_n satisfies, for a.e. $x \in \Omega$, $\forall s > 0$,

$$\begin{cases} \lim_{n \rightarrow +\infty} g_n(x, s) = g(x, s), \\ g_n(x, s) \leq g(x, s), \forall n \geq n_0, \\ g_n(x, s) \geq 0. \end{cases} \quad (2.2)$$

Since for fixed n both functions $f_n(x)$ ($x \in \Omega$) and $\frac{|\varsigma|^2}{1 + \frac{1}{n}|\varsigma|^2}$ ($\varsigma \in \mathbb{R}^N$) are bounded, classical results allow us to deduce that problem

$$\begin{cases} -\operatorname{div}(M(x, u_n) \nabla u_n) + g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} = f_n & \text{in } \Omega, \\ u_n = 0 & \text{on } \partial\Omega, \end{cases} \quad (2.3)$$

has a solution u_n that belongs to $H_0^1(\Omega)$ (see [30]) and to $L^\infty(\Omega)$ (see [36]).

We are going to prove now some properties of the sequence u_n that we will use in the sequel.

Lemma 2.2. *Assume that $0 \not\equiv f \in L^{\frac{2N}{N+2}}(\Omega)$ satisfies $f \geq 0$ and that $M(x, s)$ satisfies (1.2). If, for every $n \in \mathbb{N}$, the function $u_n \in H_0^1(\Omega)$ is a solution of problem (2.3), then:*

1. The sequence $\{u_n\}$ is bounded in $H_0^1(\Omega)$ and

$$u_n g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \text{ is bounded in } L^1(\Omega).$$

2. The functions u_n are continuous in Ω and $u_n(x) > 0$ for every $x \in \Omega$ and $n \in \mathbb{N}$.

Proof. 1. Taking u_n as test function in (2.3) and using Hölder and Sobolev inequalities we obtain that

$$\begin{aligned} \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla u_n + \int_{\Omega} g_n(x, u_n) u_n \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} &= \int_{\Omega} f_n u_n \\ &\leq \mathcal{S} \|f\|_{L^{\frac{2N}{N+2}}(\Omega)} \|\nabla u_n\|_{L^2(\Omega)}. \end{aligned}$$

By the ellipticity condition (1.2) and the nonnegativeness of $g_n(x, s)s$, we conclude that the sequences u_n and $u_n g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2}$ are bounded, respectively, in $H_0^1(\Omega)$ and in $L^1(\Omega)$.

2. We take $u_n^- \stackrel{\text{def}}{=} \min(u_n, 0)$ as test function in (2.3), so that, by (1.2),

$$\alpha \int_{\Omega} |\nabla u_n^-|^2 + \int_{\Omega} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} u_n^- \leq \int_{\Omega} f_n u_n^-.$$

Using that $f_n \geq 0$ and $g_n(x, s)$ is zero for every $s \leq 0$, we obtain

$$\alpha \int_{\Omega} |\nabla u_n^-|^2 \leq \int_{\Omega} f_n u_n^- \leq 0.$$

Thus $u_n^- \equiv 0$ and so $u_n \geq 0$. Moreover,

$$-\operatorname{div}(M(x, u_n) \nabla u_n) = f_n - g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} \in L^\infty(\Omega).$$

Hence u_n belongs to the space of the Hölder continuous functions in Ω (see for instance [25], Theorem 1.1 in Chapter 4).

We are now going to prove that $u_n > 0$ in Ω . Let $C_n > 0$ be such that $g_n(x, s) \leq C_n s$, for $s \in [0, \|u_n\|_{L^\infty(\Omega)}]$. Thus the nonnegative function u_n satisfies in the sense of distributions in Ω

$$\begin{aligned} -\operatorname{div}(M(x, u_n) \nabla u_n) + n C_n u_n &\geq -\operatorname{div}(M(x, u_n) \nabla u_n) + \frac{g_n(x, u_n) |\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} \\ &= f_n. \end{aligned}$$

Observing that f_n is nonnegative and not identically zero (since $f \not\equiv 0$), by the strong maximum principle (see [23] for instance) we deduce that $u_n > 0$ in Ω . \square

In the next proposition we will prove that the sequence $\{u_n\}$ is uniformly bounded from below, away from zero, in every compact set in Ω . This result will be crucial in order to prove the existence of a solution for (1.1).

Proposition 2.3. Suppose that $f \in L_{loc}^\infty(\Omega)$ satisfies (1.4), and that h is such that (1.7) holds. Let ω be a compactly contained open subset of Ω . Then there exists a constant $c_\omega > 0$ such that every supersolution $0 < z \in H_{loc}^1(\Omega) \cap C(\Omega)$ of the equation

$$-\operatorname{div}(M(x, z)\nabla z) + h(z)|\nabla z|^2 = f \quad \text{in } \Omega, \quad (2.4)$$

satisfies

$$z \geq c_\omega \quad \text{in } \omega.$$

Remark 2.4. The above proposition will be crucial in the proofs of both Theorem 1.1 and 1.2. In fact, we will use the following consequences:

- (i) Let u_n be a solution of (2.3) with $n \geq n_0$ (n_0 given by (2.2)). By Lemma 2.2, $u_n > 0$ in Ω and it is continuous. In particular $h(u_n)|\nabla u_n|^2 \in L_{loc}^1(\Omega)$. Thus, from the inequalities $g_n(x, s) \leq g(x, s) \leq h(s)$ for every $s > 0$ and $f_n \geq f_1$ we obtain that u_n is a supersolution for

$$-\operatorname{div}(M(x, z)\nabla z) + h(z)|\nabla z|^2 = f_1 \quad \text{in } \Omega.$$

Therefore, by the above proposition (with $f = f_1$ and $z = u_n \in H_0^1(\Omega) \cap C(\bar{\Omega})$ (Lemma 2.2-2.)) for any $\omega \subset\subset \Omega$ we get the existence of a positive constant c_ω such that $u_n \geq c_\omega$ in ω . Taking $k > 0$ and $m_0 > \max\{n_0, \frac{1}{c_\omega}\}$, we deduce, by the definition of g_n , that for all $n \geq m_0$

$$g_n(x, u_n(x)) = g(x, u_n(x)) \leq c_k(\omega) \stackrel{\text{def}}{=} \max_{s \in [c_\omega, k]} h(s),$$

for every $x \in \omega$ such that $u_n(x) \leq k$.

- (ii) If $0 < u_n \in H_0^1(\Omega) \cap C(\Omega)$ is a finite energy solution of

$$-\operatorname{div}(M(x, u_n)\nabla u_n) + g(x, u_n)|\nabla u_n|^2 = f_n \quad \text{in } \Omega,$$

then, using again that $g(x, s) \leq h(s)$, $f_n \geq f_1$ and $h(u_n)|\nabla u_n|^2 \in L_{loc}^1(\Omega)$, we derive that u_n is also a supersolution of

$$-\operatorname{div}(M(x, z)\nabla z) + h(z)|\nabla z|^2 = f_1 \quad \text{in } \Omega.$$

Consequently, if $\omega \subset\subset \Omega$ and c_ω has been defined above (with $f = f_1$), then $u_n \geq c_\omega$ in ω . Therefore,

$$g(x, u_n(x)) \leq c_k(\omega) \stackrel{\text{def}}{=} \max_{s \in [c_\omega, k]} h(s),$$

for every $x \in \omega$ such that $u_n(x) \leq k$.

Proof of Proposition 2.3. Let $z > 0$ be a supersolution of (2.4). We are going to consider a suitable change of variable. In order to make it, since in general

the function h may be integrable in $(0, 1)$, we set $\tilde{h}(s) = h(s) + \frac{\alpha}{s}$, and define, for $s > 0$, the nondecreasing function

$$H(s) = \int_1^s \tilde{h}(t) dt = \int_1^s h(t) dt + \log s^\alpha, \quad (2.5)$$

and the nonincreasing function

$$\psi(s) = \int_s^1 e^{-\frac{H(t)}{\alpha}} dt = \int_s^1 t^{-1} e^{-\frac{\int_1^t h(\tau) d\tau}{\alpha}} dt. \quad (2.6)$$

Observing that

$$\lim_{s \rightarrow 0^+} \psi(s) = +\infty, \quad \lim_{s \rightarrow +\infty} \psi(s) = \psi_\infty \in [-\infty, 0),$$

we can define

$$v \stackrel{\text{def}}{=} \psi(z). \quad (2.7)$$

Since z is continuous and strictly positive in Ω , we get that z is bounded away from zero (with the bound depending on z) in every open set ω compactly contained in Ω . Consequently, by the chain rule, we have

$$\nabla v = -e^{-\frac{H(z)}{\alpha}} \nabla z \in L^2(\omega), \quad \forall \omega \subset\subset \Omega, \quad (2.8)$$

and thus $v \in H^1(\omega)$ for every $\omega \subset\subset \Omega$, i.e., $v \in H_{\text{loc}}^1(\Omega)$.

Let $0 \leq \phi \in C_c^\infty(\Omega)$, and take (as in [8]) $e^{-\frac{H(z)}{\alpha}} \phi$ as test function in (2.4) to deduce from the inequality $h(s) \leq \tilde{h}(s)$ that

$$\begin{aligned} - \int_{\Omega} M(x, z) \nabla z \cdot \nabla z \frac{\tilde{h}(z)}{\alpha} e^{-\frac{H(z)}{\alpha}} \phi + \int_{\Omega} M(x, z) \nabla z \cdot \nabla \phi e^{-\frac{H(z)}{\alpha}} \\ + \int_{\Omega} \tilde{h}(z) |\nabla z|^2 e^{-\frac{H(z)}{\alpha}} \phi \geq \int_{\Omega} f e^{-\frac{H(z)}{\alpha}} \phi. \end{aligned}$$

Using (1.2) together with (2.8) we get,

$$- \int_{\Omega} M(x, z) \nabla \psi(z) \cdot \nabla \phi \geq \int_{\Omega} f e^{-\frac{H(z)}{\alpha}} \phi \geq \int_{\Omega} \left(e^{-\frac{H(z)}{\alpha}} - 1 \right) f \phi.$$

If we define $\tilde{M}(x, s) = M(x, \psi^{-1}(s))$ and

$$b(s) = e^{-\frac{H(\psi^{-1}(s))}{\alpha}} - 1 \quad \text{for every } s \in (\psi_\infty, +\infty), \quad (2.9)$$

then v is subsolution of

$$-\text{div}(\tilde{M}(x, v) \nabla v) + f(x) b(v) = 0 \quad \text{in } \Omega.$$

Observe that $\frac{b(s)}{s}$ is nondecreasing for large $s > 0$; indeed, this is equivalent to prove that $\Upsilon(t) = \frac{e^{-\frac{H(t)}{\alpha}} - 1}{\psi(t)}$ is nonincreasing in a neighborhood of $t = 0$. To

show this, let $w_0 \in (0, 1)$ be such that $\tilde{h}(t)$ is nonincreasing in $(0, w_0]$, and, note that

$$\begin{aligned} -e^{\frac{H(t)}{\alpha}} \psi^2(t) \Upsilon'(t) &= \frac{\tilde{h}(t)}{\alpha} \psi(t) - (e^{-\frac{H(t)}{\alpha}} - 1) = \int_t^1 \frac{[\tilde{h}(t) - \tilde{h}(s)]}{\alpha} e^{-\frac{H(s)}{\alpha}} ds \\ &\geq \int_{w_0}^1 \frac{[\tilde{h}(t) - \tilde{h}(s)]}{\alpha} e^{-\frac{H(s)}{\alpha}} ds = \tilde{h}(t) M_1 - M_2 \end{aligned}$$

where

$$M_1 = \frac{1}{\alpha} \int_{w_0}^1 e^{-\frac{H(s)}{\alpha}} ds \quad \text{and} \quad M_2 = \frac{1}{\alpha} \int_{w_0}^1 \tilde{h}(s) e^{-\frac{H(s)}{\alpha}} ds.$$

Thus, if t belongs to the interval $(0, \tilde{h}^{-1}(\min\{w_0, M_2/M_1\}))$, then the right hand side of the above inequality is positive, and consequently $\Upsilon(t)$ is nonincreasing in this interval.

We also claim now that since $\int_0^1 \sqrt{h(s)} ds < +\infty$ and h is nonincreasing in a neighborhood of zero, then the function $b(s)$ satisfies the well-known Keller-Osserman condition (see [24] and [33] for instance), i.e., there exists $t_0 > 0$ such that

$$\int_{t_0}^{+\infty} \frac{dt}{\sqrt{2 \int_0^t b(s) ds}} < +\infty. \quad (2.10)$$

We postpone the proof of the claim for the moment, and we show how to conclude the proof by using the claim. Indeed, by applying [27, Theorem 7] (see also Theorem A.1 in the Appendix where, for the convenience of the reader, we have also included a proof of the precise result that we need here) we derive that for every $\omega \subset\subset \Omega$, there exists $C_\omega > 0$ such that

$$v \leq C_\omega \quad \text{in } \omega.$$

Therefore, undoing the change

$$z \geq \psi^{-1}(C_\omega) = c_\omega > 0 \quad \text{in } \omega,$$

as desired.

Consequently, to conclude the proof it suffices to show (2.10) or, equivalently, that

$$\int_{t_0}^{+\infty} \frac{dt}{\sqrt{2 \int_0^t e^{-\frac{H(\psi^{-1}(s))}{\alpha}} ds}} < +\infty.$$

Using the change $\tau = \psi^{-1}(s)$, we obtain

$$\int_{t_0}^{+\infty} \frac{dt}{\sqrt{2 \int_0^t e^{-\frac{H(\psi^{-1}(s))}{\alpha}} ds}} = \int_{t_0}^{+\infty} \frac{dt}{\sqrt{2 \int_{\psi^{-1}(t)}^{\psi^{-1}(0)} e^{-2\frac{H(\tau)}{\alpha}} d\tau}}.$$

Now we apply the change $w = \psi^{-1}(t)$ to deduce that

$$\int_{t_0}^{+\infty} \frac{dt}{\sqrt{2 \int_0^t e^{-\frac{H(\psi^{-1}(s))}{\alpha}} ds}} \leq \int_0^{w_0} \frac{dw}{\sqrt{2 \int_w^{w_0} e^{\frac{2}{\alpha}[H(w)-H(\tau)]} d\tau}},$$

with $0 < w_0 = \psi^{-1}(t_0) < 1 = \psi^{-1}(0)$ since ψ is nonincreasing, and we choose $t_0 \gg 1$ such that h is nonincreasing in $(0, w_0]$.

Since h satisfies (1.7), also \tilde{h} satisfies it, so that we conclude the proof if we show that there exists a positive constant c_0 such that

$$\tilde{h}(w) \int_w^{w_0} e^{\frac{2}{\alpha}[H(w)-H(\tau)]} d\tau \geq c_0 > 0, \quad \forall w \in (0, w_0). \quad (2.11)$$

Indeed, the only difficulty is near zero. To overcome it, we use that h (hence \tilde{h}) is nonincreasing in $(0, w_0]$, to obtain

$$\begin{aligned} \tilde{h}(w) \int_w^{w_0} e^{\frac{2}{\alpha}[H(w)-H(\tau)]} d\tau &\geq \int_w^{w_0} \tilde{h}(\tau) e^{\frac{2}{\alpha}[H(w)-H(\tau)]} d\tau \\ &= -\frac{\alpha e^{\frac{2}{\alpha}H(w)}}{2} \int_w^{w_0} -\frac{2}{\alpha} \tilde{h}(\tau) e^{-\frac{2}{\alpha}H(\tau)} d\tau \\ &= -\frac{\alpha e^{\frac{2}{\alpha}H(w)}}{2} \left[e^{-\frac{2}{\alpha}H(\tau)} \right]_w^{w_0} = -\frac{\alpha}{2} \frac{e^{\frac{2}{\alpha}H(w)}}{e^{\frac{2}{\alpha}H(w_0)}} + \frac{\alpha}{2}. \end{aligned}$$

Using the above inequality and the fact that $e^{\frac{2}{\alpha}H(w)}$ is close to zero for w small enough, we can choose $\bar{w} \in (0, w_0)$ such that

$$\tilde{h}(w) \int_w^{w_0} e^{\frac{2}{\alpha}[H(w)-H(\tau)]} d\tau \geq \frac{\alpha}{4},$$

for $0 < w < \bar{w}$. Thus the existence of c_0 such that (2.11) holds is deduced. \square

Remark 2.5. If h is such that

$$\lim_{s \rightarrow 0^+} \int_s^1 h(t) dt = +\infty,$$

there is no need to define the above function \tilde{h} . Indeed, in this case, the proof of the above theorem works by using directly h instead of \tilde{h} .

Proof of Theorem 1.1. We are going to prove that, up to a subsequence, the sequence $\{u_n\}$ of finite energy solutions of (2.3) converges to a finite energy solution of (1.1).

By Case 1. of Lemma 2.2, we obtain the existence of constants $C_1, C_2 > 0$ such that

$$\|u_n\|_{H_0^1(\Omega)} \leq C_1 \text{ and } \int_{\Omega} u_n g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} \leq C_2. \quad (2.12)$$

Thus, up to a subsequence, we can assume that u_n converges to some $u \in H_0^1(\Omega)$ weakly in $H_0^1(\Omega)$ and, by Rellich's Theorem, strongly in $L^2(\Omega)$ and a.e. in Ω .

Choosing $\frac{1}{\varepsilon}T_\varepsilon(u_n)$ as test function in (2.3) and taking into account that $f_n \leq f$ in Ω , we deduce that

$$\int_{\Omega} \frac{T_\varepsilon(u_n)}{\varepsilon} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \leq \int_{\Omega} f_n \leq \int_{\Omega} f.$$

If we take the limit as ε tends to zero, and we use that, by Lemma 2.2, $u_n > 0$ in Ω , we get

$$\int_{\Omega} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} = \int_{\{u_n > 0\}} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \leq \int_{\Omega} f. \quad (2.13)$$

The proof will be concluded by proving the following steps:

Step 1. For every $k > 0$, $T_k(u_n) \rightarrow T_k(u)$ strongly in $H_{\text{loc}}^1(\Omega)$.

Step 2. u_n is strongly convergent in $H_{\text{loc}}^1(\Omega)$.

Step 3. We pass to the limit in (2.3).

Step 1. Here we want to prove that

$$\lim_{n \rightarrow +\infty} \int_{\Omega} |\nabla(T_k(u_n) - T_k(u))|^2 \phi = 0, \quad \forall \phi \in C_c^\infty(\Omega) \text{ with } \phi \geq 0. \quad (2.14)$$

Reasoning as in [12], we consider the function $\varphi_\lambda(s)$ defined in (1.19) and we choose $\varphi_\lambda(T_k(u_n) - T_k(u))\phi$ as test function in (2.3): we have

$$\begin{aligned} & \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla(T_k(u_n) - T_k(u)) \varphi'_\lambda(T_k(u_n) - T_k(u)) \phi \\ & \quad + \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi \varphi_\lambda(T_k(u_n) - T_k(u)) \\ & + \int_{\Omega} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \varphi_\lambda(T_k(u_n) - T_k(u)) \phi = \int_{\Omega} f_n \varphi_\lambda(T_k(u_n) - T_k(u)) \phi. \end{aligned}$$

Since $T_k(u_n) \rightarrow T_k(u)$ weakly in $H_0^1(\Omega)$ and strongly in $L^2(\Omega)$, we note that

$$\int_{\Omega} f_n \varphi_\lambda(T_k(u_n) - T_k(u)) \phi - \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi \varphi_\lambda(T_k(u_n) - T_k(u)) = \varepsilon(n).$$

Moreover, choosing $\omega_\phi \subset\subset \Omega$ with $\text{supp } \phi \subset \omega_\phi$, we deduce, by Case (i) of Remark 2.4 and by the nonnegativeness of both g_n and $\varphi_\lambda(k - T_k(u))$, that

$$\begin{aligned} & \int_{\Omega} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \varphi_\lambda(T_k(u_n) - T_k(u)) \phi \\ & \geq \int_{\{u_n \leq k\}} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \varphi_\lambda(T_k(u_n) - T_k(u)) \phi \end{aligned}$$

$$\geq -c_k(\omega_\phi) \int_{\Omega} |\nabla T_k(u_n)|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi.$$

Thus

$$\begin{aligned} & \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla (T_k(u_n) - T_k(u)) \varphi'_\lambda(T_k(u_n) - T_k(u)) \phi \\ & - c_k(\omega_\phi) \int_{\Omega} |\nabla T_k(u_n)|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi \leq \varepsilon(n). \end{aligned} \quad (2.15)$$

Note that

$$\begin{aligned} & \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla (T_k(u_n) - T_k(u)) \varphi'_\lambda(T_k(u_n) - T_k(u)) \phi \chi_{\{u_n \geq k\}} \\ & = - \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla T_k(u) \varphi'_\lambda(k - T_k(u)) \phi \chi_{\{u_n \geq k\}} = \varepsilon(n), \end{aligned}$$

so that, adding

$$- \int_{\Omega} M(x, u_n) \nabla T_k(u) \cdot \nabla (T_k(u_n) - T_k(u)) \varphi'_\lambda(T_k(u_n) - T_k(u)) \phi = \varepsilon(n)$$

in both sides of (2.15) and since

$$\begin{aligned} & \int_{\Omega} |\nabla T_k(u_n)|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi \\ & \leq 2 \int_{\Omega} |\nabla (T_k(u_n) - T_k(u))|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi \\ & \quad + 2 \int_{\Omega} |\nabla T_k(u)|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi \\ & = 2 \int_{\Omega} |\nabla (T_k(u_n) - T_k(u))|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi + \varepsilon(n), \end{aligned}$$

we find, using also (1.2) (for the sake of brevity, we omit writing the argument $T_k(u_n) - T_k(u)$ for φ_λ and φ'_λ),

$$\int_{\Omega} |\nabla (T_k(u_n) - T_k(u))|^2 \left[\alpha \varphi'_\lambda - 2c_k(\omega_\phi) |\varphi_\lambda| \right] \phi \leq \varepsilon(n).$$

Choosing λ such that (1.19) holds with $a = \alpha$ and $b = 2c_k(\omega_\phi)$, we obtain (2.14).

Step 2. We prove now that the sequence u_n is strongly convergent in $H_{\text{loc}}^1(\Omega)$.

Let us choose $G_k(u_n)$ as test function in (2.3) and drop the positive integral involving the lower order term. By using (1.2), and Hölder and Sobolev inequalities, we have

$$\int_{\Omega} |\nabla G_k(u_n)|^2 \leq \frac{\mathcal{S}^2}{\alpha^2} \left(\int_{\{u_n \geq k\}} f^{\frac{2N}{N+2}} \right)^{1 + \frac{2}{N}},$$

and the right hand side of the previous inequality is arbitrarily small if k is large enough. This and the convergence proved in Step 1 of $T_k(u_n)$ in $H_0^1(\Omega)$ implies that $|\nabla u_n|^2$ is equiintegrable in every $\omega \subset\subset \Omega$.

Moreover, since

$$-\operatorname{div}(M(x, u_n)\nabla u_n) = f_n - g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2},$$

and the right hand side is bounded in $L^1(\Omega)$ by the assumptions on f and by (2.13), we can apply Lemma 1 of [9] (see also [14]) to deduce that, up to (not relabeled) subsequences, ∇u_n converges to ∇u a.e. in Ω . Hence, by Vitali theorem

$$u_n \rightarrow u \quad \text{in } H_{\text{loc}}^1(\Omega).$$

Step 3. Let us observe that, by applying Fatou lemma in (2.12) and (2.13), we deduce that

$$\int_{\Omega} u g(x, u) |\nabla u|^2 \leq C_2 \quad \text{and} \quad \int_{\Omega} g(x, u) |\nabla u|^2 \leq \int_{\Omega} f,$$

respectively. Therefore, to conclude the proof we only have to prove that u is a distributional solution of the problem (1.1). We begin by passing to the limit on n in the equation satisfied by u_n , i.e., in

$$\int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi + \int_{\Omega} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \phi = \int_{\Omega} f_n \phi, \quad \forall \phi \in C_c^\infty(\Omega).$$

First of all, the weak convergence of u_n to u and the weak-* convergence of $M(x, u_n)$ to $M(x, u)$ in $L^\infty(\Omega)$ implies that

$$\lim_{n \rightarrow +\infty} \int_{\Omega} M(x, u_n) \nabla u_n \nabla \phi = \int_{\Omega} M(x, u) \nabla u \nabla \phi, \quad \forall \phi \in C_c^\infty(\Omega). \quad (2.16)$$

On the other hand, if we fix $\omega \subset\subset \Omega$, then, by Remark 2.4,

$$g_n(x, u_n(x)) \leq c_k(\omega), \quad \forall n \gg 1, \quad \text{and} \quad \forall x \in \omega \text{ satisfying } u_n(x) \leq k.$$

Consequently, if $E \subset\subset \omega$ we have

$$\begin{aligned} & \int_E |g_n(x, u_n(x))| \frac{|\nabla u_n(x)|^2}{1 + \frac{1}{n}|\nabla u_n(x)|^2} \\ & \leq \int_{E \cap \{u_n \leq k\}} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} + \int_{E \cap \{u_n \geq k\}} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2} \\ & \leq c_k(\omega) \int_{E \cap \{u_n \leq k\}} |\nabla T_k(u_n)|^2 + \int_{\{u_n \geq k\}} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n}|\nabla u_n|^2}. \end{aligned} \quad (2.17)$$

Let $\varepsilon > 0$ be fixed. Observe that if, for $k > 1$, we use $T_1(G_{k-1}(u_n))$ as test function in (2.3) and drop positive terms, we deduce that

$$\int_{\{u_n \geq k\}} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} \leq \int_{\{u_n \geq k-1\}} f_n \leq \int_{\{u_n \geq k-1\}} f.$$

Thus, since the right hand side tends to 0 uniformly in n as k diverges, we obtain the existence of $k_0 > 1$ such that

$$\int_{\{u_n \geq k\}} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} \leq \frac{\varepsilon}{2}, \quad \forall k \geq k_0, \forall n \in \mathbb{N}.$$

Moreover, since $T_k(u_n)$ is strongly compact in $H_{\text{loc}}^1(\Omega)$, there exist $n_\varepsilon, \delta_\varepsilon$ such that for every $E \subset\subset \Omega$ with $\text{meas}(E) < \delta_\varepsilon$ we have

$$\int_{E \cap \{u_n \leq k\}} |\nabla T_k(u_n)|^2 < \frac{\varepsilon}{2c_k(\omega)}, \quad \forall n \geq n_\varepsilon.$$

In conclusion, by (2.17), taking $k \geq k_0$ we see that $\text{meas}(E) < \delta_\varepsilon$ implies

$$\int_E |g_n(x, u_n(x))| \frac{|\nabla u_n(x)|^2}{1 + \frac{1}{n} |\nabla u_n(x)|^2} \leq \varepsilon, \quad \forall n \geq n_\varepsilon,$$

i.e., the sequence $g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2}$ is equiintegrable. This, together with its a.e. convergence to $g(x, u) |\nabla u|^2$, implies by Vitali theorem that

$$\lim_{n \rightarrow +\infty} \int_{\Omega} g_n(x, u_n) \frac{|\nabla u_n|^2}{1 + \frac{1}{n} |\nabla u_n|^2} \phi = \int_{\Omega} g(x, u) |\nabla u|^2 \phi, \quad \forall \phi \in C_c^\infty(\Omega).$$

Therefore, using the above limit, (2.16) and since f_n tends to f strongly in $L^1(\Omega)$ we conclude that

$$\int_{\Omega} M(x, u) \nabla u \nabla \phi + \int_{\Omega} g(x, u) |\nabla u|^2 \phi = \int_{\Omega} f \phi, \quad \forall \phi \in C_c^\infty(\Omega).$$

□

Remark 2.6. In addition, if $f \in L^q(\Omega)$ with $q > N/2$, then the solution u given by Theorem 1.1 is continuous in Ω . Indeed, by using $\psi = T_m(G_k(u))$, with $m > k$, as test function in (2.1), it is easy to adapt the idea of Stampacchia ([36]) in order to obtain that $u \in L^\infty(\Omega)$. Now, consider a function $\zeta \in C^\infty(\Omega)$ with $0 \leq \zeta(x) \leq 1$, for every $x \in \Omega$ and compact support in a ball B_ρ of radius $\rho > 0$, and set $A_{k,\rho} = \{x \in B_\rho \cap \Omega : u(x) > k\}$. Following the idea of the proof of Theorem 1.1 of Chapter 4 in [25], take $\phi = G_k(u) \zeta^2$ as test function in (2.1) to deduce by (1.2) and Hölder's inequality that

$$\alpha \int_{A_{k,\rho}} |\nabla u|^2 \zeta^2 \leq \|f\|_{L^q(\Omega)} \|u\|_{L^\infty(\Omega)} (\text{meas } A_{k,\rho})^{1-\frac{1}{q}} + 2\beta \int_{A_{k,\rho}} |\nabla u| |\nabla \zeta| \zeta G_k(u).$$

Using again Young's inequality we get

$$\int_{A_{k,\rho}} |\nabla u|^2 \zeta^2 \leq \frac{2\|f\|_{L^q(\Omega)}\|u\|_{L^\infty(\Omega)}}{\alpha} (\text{meas } A_{k,\rho})^{1-\frac{1}{q}} + \frac{4\beta}{\alpha^2} \int_{A_{k,\rho}} |\nabla \zeta|^2 G_k^2(u).$$

In particular, if for $\sigma \in (0, 1)$ we choose ζ such that it is constantly equal to 1 in the concentric ball $B_{\rho-\sigma\rho}$ (to B_ρ) of radius $\rho - \sigma\rho$ and $|\nabla \zeta| < \frac{1}{\sigma\rho}$, we obtain

$$\int_{A_{k,\rho-\sigma\rho}} |\nabla u|^2 \leq \gamma \left(1 + \frac{1}{\sigma^2 \rho^{2(1-\frac{N}{2q})}} \max_{A_{k,\rho}}(u-k)^2 \right) (\text{meas } A_{k,\rho})^{1-\frac{1}{q}},$$

where $\gamma = \max \left\{ \frac{2\|f\|_{L^q(\Omega)}\|u\|_{L^\infty(\Omega)}}{\alpha}, \frac{4\beta}{\alpha^2} \omega_N^{\frac{1}{q}} \right\}$ with ω_N denoting the measure of the unit ball of \mathbb{R}^N .

This means that for $\delta > 0$ small enough and every $M \geq \|u\|_{L^\infty(\Omega)}$, the function u belongs to the class $\mathcal{B}_2(\Omega, M, \gamma, \delta, \frac{1}{2q})$ with $2q > N$ (see [25], pag. 81). Applying Theorem 6.1 of [25] we deduce that u is Hölder continuous in Ω .

3. Further Existence Results

3.1. Existence for data in $L^1(\Omega)$

In this section we prove Theorem 1.2. In this case, taking advantage of Theorem 1.1, we approximate problem (1.1) by

$$\begin{cases} -\text{div}(M(x, u_n)\nabla u_n) + g(x, u_n)|\nabla u_n|^2 = f_n & \text{in } \Omega, \\ u_n = 0 & \text{on } \partial\Omega, \end{cases} \quad (3.1)$$

where $f_n = T_n(f)$.

Note that the existence of a nonnegative finite energy solution $u_n \in H_0^1(\Omega) \cap C(\Omega)$ such that $g(x, u_n)|\nabla u_n|^2 \in L^1(\Omega)$ follows from Theorem 1.1 and Remark 2.6.

Lemma 3.1. *If $f \in L^1(\Omega)$ satisfies (1.4), $g(x, s)$ satisfies (1.6) (with $h(s)$ satisfying (1.7)), and u_n is a solution of (3.1), then*

- (i) u_n is bounded in $\mathcal{M}^{\frac{N}{N-2}}(\Omega)$ and $|\nabla u_n|$ is bounded in $\mathcal{M}^{\frac{N}{N-1}}(\Omega)$;
- (ii) up to subsequences, the sequence u_n is weakly convergent to some u in $W_0^{1,q}(\Omega)$ for every $q \in [1, \frac{N}{N-1})$;
- (iii) for any $k > 0$ and for any $\omega \subset\subset \Omega$,

$$T_k(u_n) \rightarrow T_k(u) \quad \text{in } H^1(\omega).$$

Proof. (i) Taking $T_k(u_n)$ as test function in (3.1) and using (1.2), we have

$$\alpha \int_{\Omega} |\nabla T_k(u_n)|^2 + \int_{\Omega} g(x, u_n) T_k(u_n) |\nabla u_n|^2 \leq k \|f_n\|_{L^1(\Omega)}.$$

Since $0 \leq f_n \leq f$ and $g(x, u_n) \geq 0$, we have

$$\alpha \int_{\Omega} |\nabla T_k(u_n)|^2 \leq k \|f\|_{L^1(\Omega)}. \quad (3.2)$$

Standard estimates (see [6, Lemmas 4.1 and 4.2]) imply that u_n is bounded in $\mathcal{M}^{\frac{N}{N-2}}(\Omega)$ and that $|\nabla u_n|$ is bounded in $\mathcal{M}^{\frac{N}{N-1}}(\Omega)$.

(ii) Let $1 \leq q < \frac{N}{N-1}$. By the preceding case and by the embedding (1.18), we deduce that u_n is bounded in $W_0^{1,q}(\Omega)$ and thus, passing to a subsequence if necessary, there exists u such that $u_n \rightharpoonup u$ weakly in $W_0^{1,q}(\Omega)$.

(iii) Our aim is to show that

$$\lim_{n \rightarrow +\infty} \int_{\Omega} |\nabla(T_k(u_n) - T_k(u))|^2 \phi = 0, \quad \forall \phi \in C_c^\infty(\Omega), \phi \geq 0.$$

Here we adapt to our case a technique to obtain the strong convergence of truncations first introduced in [26] (see also [35]). Let us choose $\varphi_\lambda(w_n)\phi$ as test function in (3.1) where $\varphi_\lambda(s)$ has been defined in (1.19) and

$$w_n = T_{2k}[u_n - T_l(u_n) + T_k(u_n) - T_k(u)], \quad 0 < k < l.$$

Thus we have

$$\begin{aligned} & \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla w_n \varphi'_\lambda(w_n) \phi + \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi \varphi_\lambda(w_n) \\ & + \int_{\Omega} g(x, u_n) |\nabla u_n|^2 \varphi_\lambda(w_n) \phi = \int_{\Omega} f_n \phi \varphi_\lambda(w_n). \end{aligned} \quad (3.3)$$

Observing that $\nabla T_k(u_n) = 0$ if $u_n > k$ and $\nabla w_n \equiv 0$ if $u_n \geq 2k + l \equiv \mathcal{K}$ (we recall that $l > k$), we have

$$\begin{aligned} & \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla w_n \varphi'_\lambda(w_n) \phi \\ & = \int_{\Omega} M(x, u_n) \nabla T_k(u_n) \cdot \nabla(T_k(u_n) - T_k(u)) \varphi'_\lambda(w_n) \phi \\ & + \int_{\{u_n \geq k\}} M(x, u_n) \nabla T_{\mathcal{K}}(u_n) \cdot \nabla T_{2k}(G_l(u_n) + k - T_k(u)) \varphi'_\lambda(w_n) \phi. \end{aligned}$$

Moreover, using that

$$\begin{aligned} \nabla T_{\mathcal{K}}(u_n) \cdot \nabla(G_l(u_n) - T_k(u)) &= \nabla T_{\mathcal{K}}(u_n) \cdot \nabla G_l(u_n) - \nabla T_{\mathcal{K}}(u_n) \nabla T_k(u) \\ &\geq -\nabla T_{\mathcal{K}}(u_n) \cdot \nabla T_k(u), \end{aligned}$$

we have

$$\begin{aligned} & \int_{\{u_n > k\} \cap \{G_l(u_n) - T_k(u) \leq k\}} M(x, u_n) \nabla T_{\mathcal{K}}(u_n) \cdot \nabla(G_l(u_n) - T_k(u)) \varphi'_\lambda(w_n) \phi \\ & \geq - \int_{\{G_l(u_n) + k - T_k(u) \leq 2k\}} |M(x, u_n) \nabla T_{\mathcal{K}}(u_n) \cdot \nabla T_k(u)| \varphi'_\lambda(w_n) \phi \chi_{\{u_n > k\}}, \end{aligned}$$

and thus, since the above integral tends to zero as n diverges,

$$\begin{aligned} & \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla w_n \varphi'_\lambda(w_n) \phi \\ & \geq \int_{\Omega} M(x, u_n) \nabla T_k(u_n) \cdot \nabla (T_k(u_n) - T_k(u)) \varphi'_\lambda(w_n) \phi + \varepsilon(n). \end{aligned} \quad (3.4)$$

On the other hand, since $G_l(u_n) + k - T_k(u) \geq 0$,

$$\int_{\Omega} g(x, u_n) |\nabla u_n|^2 \varphi_\lambda(w_n) \phi \geq \int_{\{u_n \leq k\}} g(x, u_n) |\nabla u_n|^2 \varphi_\lambda(w_n) \phi.$$

Thanks to Case (ii) of Remark 2.4 applied to a subset $\omega_\phi \subset\subset \Omega$ with $\text{supp } \phi \subset \omega_\phi$, we have $g(x, u_n(x)) \leq c_k(\omega_\phi)$ for every $x \in \omega$ with $u_n(x) \leq k$. Then, we get

$$\begin{aligned} & \left| \int_{\{u_n \leq k\}} g(x, u_n) |\nabla u_n|^2 \varphi_\lambda(T_k(u_n) - T_k(u)) \phi \right| \\ & \leq c_k(\omega_\phi) \int_{\Omega} |\nabla T_k(u_n)|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi \\ & \leq 2c_k(\omega_\phi) \int_{\Omega} |\nabla (T_k(u_n) - T_k(u))|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi \\ & \quad + 2c_k(\omega_\phi) \int_{\Omega} |\nabla T_k(u)|^2 |\varphi_\lambda(T_k(u_n) - T_k(u))| \phi. \end{aligned}$$

Note that the last integral tends to 0 as n diverges since $\varphi_\lambda(T_k(u_n) - T_k(u))$ converges to zero in the weak-* topology of $L^\infty(\Omega)$ and $T_k(u) \in H_0^1(\Omega)$. Therefore, we deduce from this, (3.3) and (3.4) that

$$\begin{aligned} & \int_{\Omega} M(x, u_n) \nabla T_k(u_n) \cdot \nabla (T_k(u_n) - T_k(u)) \varphi'_\lambda(w_n) \phi \\ & - 2c_k(\omega_\phi) \int_{\Omega} |\nabla (T_k(u_n) - T_k(u))|^2 |\varphi_\lambda(w_n)| \phi \\ & \leq \int_{\Omega} f_n \phi \varphi_\lambda(w_n) - \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi \varphi_\lambda(w_n) + \varepsilon(n), \end{aligned}$$

and adding to both sides of the previous inequality

$$- \int_{\Omega} M(x, u_n) \nabla T_k(u) \cdot \nabla (T_k(u_n) - T_k(u)) \varphi'_\lambda(w_n) \phi = \varepsilon(n),$$

we find from (1.2),

$$\begin{aligned} & \int_{\Omega} |\nabla (T_k(u_n) - T_k(u))|^2 \left[\alpha \varphi'_\lambda(w_n) - 2c_k(\omega_\phi) |\varphi_\lambda(w_n)| \right] \phi \\ & \leq \int_{\Omega} f_n \phi \varphi_\lambda(w_n) - \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi \varphi_\lambda(w_n) + \varepsilon(n). \end{aligned}$$

Choosing λ such that φ_λ satisfies (1.19) with $a = \alpha$ and $b = 2c_k(\omega_\phi)$, we get

$$\begin{aligned} & \frac{\alpha}{2} \int_{\Omega} |\nabla(T_k(u_n) - T_k(u))|^2 \phi \\ & \leq \int_{\Omega} f_n \phi \varphi_\lambda(w_n) - \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi \varphi_\lambda(w_n) + \varepsilon(n). \end{aligned}$$

Moreover, w_n a.e. (and weakly-* in $L^\infty(\Omega)$) converges towards $w = T_{2k}(G_l(u))$ and thus, recalling that $\nabla u_n \rightarrow \nabla u$ weakly in $(L^q(\Omega))^N$, $q < N/(N-1)$,

$$\begin{aligned} & \lim_{n \rightarrow +\infty} \int_{\Omega} f_n \phi \varphi_\lambda(w_n) - \int_{\Omega} M(x, u_n) \nabla u_n \cdot \nabla \phi \varphi_\lambda(w_n) \\ & = \int_{\Omega} f \phi \varphi_\lambda(w) - \int_{\Omega} M(x, u) \nabla u \cdot \nabla \phi \varphi_\lambda(w). \end{aligned}$$

Consequently, using (1.2)

$$\begin{aligned} \frac{\alpha}{2} \int_{\Omega} |\nabla(T_k(u_n) - T_k(u))|^2 \phi & \leq \int_{\Omega} f \phi \varphi_\lambda(w) - \int_{\Omega} M(x, u) \nabla u \cdot \nabla \phi \varphi_\lambda(w) + \varepsilon(n) \\ & \leq \varphi_\lambda(2k) \int_{\{u \geq l\}} (f + \beta |\nabla u| |\nabla \phi|) + \varepsilon(n). \end{aligned}$$

Since the last integral tends to zero as l diverges, (iii) is proved. \square

Now, we prove our main result concerning $L^1(\Omega)$ data:

Proof of Theorem 1.2. We begin by proving the first part of the theorem, i.e. that there exists a solution $u \in W_0^{1,q}(\Omega)$, for every $q < \frac{N}{N-1}$, of problem (1.1). We first observe that we deduce from the results of [14] that $\nabla u_n \rightarrow \nabla u$ a.e., and from Lemma 3.1 the estimates on u_n and $|\nabla u_n|$ in $\mathcal{M}^{\frac{N}{N-2}}(\Omega)$ and $\mathcal{M}^{\frac{N}{N-1}}(\Omega)$ respectively. Thus $u_n \rightarrow u$ strongly in $W_0^{1,q}(\Omega)$, for every $q < \frac{N}{N-1}$. Arguing as in the proof of Theorem 1.1, we can show that, choosing $\frac{1}{\varepsilon} T_\varepsilon(u_n)$ as test function in (3.1) and applying Fatou lemma, we have $g(x, u) |\nabla u|^2 \in L^1(\Omega)$.

In order to prove that for all $\omega \subset\subset \Omega$, $\{g(x, u_n) |\nabla u_n|^2\}$ is strongly convergent in $L^1(\omega)$ to $g(x, u) |\nabla u|^2$, it suffices to show the local uniform equiintegrability of such sequence. To prove the claim, we choose $T_1(G_{k-1}(u_n))$ (for $k > 1$) as test function in the equation (3.1) and we deduce, by dropping the first positive term (in virtue of (1.2)), and since $f_n \leq f$, that

$$\int_{\{u_n \geq k\}} g(x, u_n) |\nabla u_n|^2 \leq \int_{\{u_n \geq k-1\}} f. \quad (3.5)$$

By a similar argument to the one used in Step 3 of the proof of Theorem 1.1, we prove the claim. Indeed, let $E \subset \omega \subset\subset \Omega$ be a measurable set. By Remark 2.4-

(ii) and (3.5), we have, $\forall k1$,

$$\begin{aligned} \int_E g(x, u_n) |\nabla u_n|^2 &= \int_{E \cap \{u_n \leq k\}} g(x, u_n) |\nabla u_n|^2 \\ &+ \int_{E \cap \{u_n \geq k\}} g(x, u_n) |\nabla u_n|^2 \leq c_k(\omega) \int_{E \cap \{u_n \leq k\}} |\nabla T_k(u_n)|^2 \\ &+ \int_{\{u_n \geq k\}} g(x, u_n) |\nabla u_n|^2 \leq c_k(\omega) \int_E |\nabla T_k(u_n)|^2 + \int_{\{u_n \geq k-1\}} f. \end{aligned}$$

Since $\text{meas}(\{x \in \Omega : u_n \geq k-1\})$ tends to zero (uniformly with respect to n) as k tends to $+\infty$ (because of the boundedness of $\{u_n\}$ in the space $\mathcal{M}^{N/(N-2)}(\Omega)$ by Lemma 3.1-(ii)), we obtain that the last integral in the above inequalities tends to zero as k goes to $+\infty$. This, and the local equiintegrability of $|\nabla T_k(u_n)|^2$ (by Lemma 3.1-(iii)), then show the local equiintegrability of $\{g(x, u_n) |\nabla u_n|^2\}$.

Using moreover that $\nabla u_n \rightarrow \nabla u$ a.e., we conclude by Vitali theorem that

$$g(x, u_n) |\nabla u_n|^2 \rightarrow g(x, u) |\nabla u|^2 \quad \text{in } L^1(\omega), \quad \forall \omega \subset\subset \Omega. \quad (3.6)$$

Now, using (3.6) and the strong convergence of ∇u_n to ∇u in $(L^q(\Omega))^N$, for every $q < \frac{N}{N-1}$, we can pass to the limit in (3.1) to show that u is a solution for (1.1).

In order to prove the second part of the theorem, we simply note that we can fix $k \geq \max\{s_0, 1\}$ so that (1.10) and (3.5) imply

$$\mu \int_{\Omega} |\nabla G_k(u_n)|^2 = \mu \int_{\{u_n \geq k\}} |\nabla u_n|^2 \leq \int_{\{u_n \geq k-1\}} f \leq \|f\|_{L^1(\Omega)}. \quad (3.7)$$

Hence, taking into account both (3.2) and (3.7), we have

$$\int_{\Omega} |\nabla u_n|^2 = \int_{\Omega} |\nabla T_k(u_n)|^2 + \int_{\Omega} |\nabla G_k(u_n)|^2 \leq \left(\frac{k}{\alpha} + \frac{1}{\mu} \right) \|f\|_{L^1(\Omega)},$$

i.e., the boundedness of the sequence $\{u_n\}$ in $H_0^1(\Omega)$. This implies that the solution u , which is the limit of (a subsequence of) $\{u_n\}$, belongs to $H_0^1(\Omega)$. \square

Remark 3.2. Actually, if (1.10) holds, it is possible to prove, in this latter case, that the approximate sequence u_n is strongly convergent to u in $H^1(\omega)$, for every $\omega \subset\subset \Omega$. Indeed, due to the a.e. convergence of ∇u_n to ∇u in Ω , it suffices to check the equiintegrability of $|\nabla u_n|^2$ in every $\omega \subset\subset \Omega$. To do that, we take a measurable set $E \subset \omega \subset\subset \Omega$, and we observe that, thanks to (3.7), for any $k \geq \max\{s_0, 1\}$, we can write

$$\begin{aligned} \int_E |\nabla u_n|^2 &= \int_E |\nabla T_k(u_n)|^2 + \int_E |\nabla G_k(u_n)|^2 \\ &\leq \int_E |\nabla T_k(u_n)|^2 + \frac{1}{\mu} \int_{\{u_n \geq k-1\}} f. \end{aligned} \quad (3.8)$$

Therefore, using again both the boundedness of u_n in $\mathcal{M}^{\frac{N}{N-2}}(\Omega)$ and the equi-integrability of $|\nabla T_k(u_n)|^2$ in ω given by Lemma 3.1, we see that (3.8) yields the desired result.

3.2. Non-divergence operators

In this section we sketch the proof of Theorem 1.3 without giving all the details since they are straightforward adaptations of the applied arguments in the proof of Theorem 1.1.

Proof of Theorem 1.3. We denote by $P(x)$ the vector field whose i^{th} component is

$P_i(x) = b_i(x) + \sum_{j=1}^N \frac{\partial a_{ij}}{\partial x_j}(x)$ ($i = 1, \dots, N$) and by $M(x)$ the transpose of the matrix $(a_{ij}(x))_{i,j=1,\dots,N}$. Let $g_n(x, s)$ also be given by (2.2). Consider the sequence $u_n \in H_0^1(\Omega) \cap L^\infty(\Omega)$ of solutions for the problem

$$\begin{cases} -\operatorname{div}(M(x)\nabla u_n) + P(x) \cdot \nabla u_n + g_n(x, u_n)|\nabla u_n|^2 = f & \text{in } \Omega, \\ u_n = 0 & \text{on } \partial\Omega. \end{cases} \quad (3.9)$$

The proof is divided into several steps.

Step 1. $L^\infty(\Omega)$ estimate. Using the ideas of [16], we choose $v = e^{2\lambda G_k(u_n)} - 1$, with $\lambda \gg 1$ as test function in the weak formulation of (3.9) to prove that the sequence $\{u_n\}$ is bounded in $L^\infty(\Omega)$.

Step 2. $H_0^1(\Omega)$ estimate. By the previous $L^\infty(\Omega)$ estimate, it is easy to see that $\{u_n\}$ is bounded in $H_0^1(\Omega)$, and so u_n weakly converges in $H_0^1(\Omega)$ to a function u in $H_0^1(\Omega) \cap L^\infty(\Omega)$. Moreover, arguing as in Remark 2.6, it is clear that both u_n (for every $n \in \mathbb{N}$) and u are continuous in Ω .

Step 3. Estimate on the lower order term. Choosing $\frac{T_\varepsilon(u_n)}{\varepsilon}$ as test function in (3.9) and taking limit as ε tends to zero, we deduce, for some $C_1 > 0$, that

$$\int_{\Omega} g_n(x, u_n)|\nabla u_n|^2 \leq \int_{\Omega} |f| + C_1.$$

Step 4. Uniform bound from below for u_n in compact sets. Observe that u_n are supersolutions of the equation

$$-\operatorname{div}(M(x)\nabla u) + P(x) \cdot \nabla u + h(u)|\nabla u|^2 = f \quad \text{in } \Omega. \quad (3.10)$$

If, for $H(s)$ defined in (2.5) and $\phi \in C_c^\infty(\Omega)$, we take $e^{-\frac{H(u)}{\alpha}}\phi$ as test function in (3.10), we see that $v_n = \psi(u_n)$ are subsolutions of

$$-\operatorname{div}(M(x)\nabla v) + P(x) \cdot \nabla v + b(v)f(x) = 0 \quad \text{in } \Omega, \quad (3.11)$$

where $b(s)$ has been defined in (2.9) and we recall that it satisfies the Keller-Osserman condition (see (2.10)). Hence, by Theorem A.1 in the Appendix, we conclude that for every $\omega \subset\subset \Omega$, there exists C_ω such that $v_n = \psi(u_n) \leq C_\omega$ in ω . Therefore, $u_n \geq c_\omega > 0$ in ω , with $c_\omega = \psi^{-1}(C_\omega)$.

Step 5. Compactness of $\{u_n\}$ in $H_{\text{loc}}^1(\Omega)$. For $\varphi_\lambda(s)$ defined in (1.19) and $\phi \in C_c^\infty(\Omega)$, we choose $\varphi_\lambda(u_n - u)\phi$ as test function in the weak formulation of (3.12) and we note that the ideas of Theorem 1.1 works since the *new term* that appears in the equation does not lead to any further difficulty because it is linear with respect to ∇u . Thus we conclude that, up to a subsequence,

$$u_n \rightarrow u \quad \text{in } H_{\text{loc}}^1(\Omega).$$

Step 6. Passing to the limit. By Step 5, we pass to the limit in the weak formulation of (3.9) to deduce that u is a solution for

$$\begin{cases} -\operatorname{div}(M(x)\nabla u) + P(x) \cdot \nabla u + g(x, u)|\nabla u|^2 = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (3.12)$$

Since the coefficients a_{ij} are Lipschitz continuous on Ω , we see that u solves (1.11). Finally, by Step 3 we conclude that $g(x, u)|\nabla u|^2 \in L^1(\Omega)$. \square

4. Nonexistence results

This section is devoted to study nonexistence of solutions for (1.1). We begin by observing that if the function $g(x, s)$ satisfies condition (1.13) with h such that (1.14) and (1.15) hold, then we can change h by a smaller function \bar{h} which, in addition to (1.14) and (1.15), also satisfies $\bar{h}(s) = 0$ for every $s > 1$. Indeed, if s_0 is the point where h attains its minimum value in $[\frac{1}{2}, 1]$, then it suffices to define

$$\bar{h}(s) = \begin{cases} (h(s) - h(s_0))^+ & \text{if } s \in (0, s_0], \\ 0 & \text{if } s > s_0. \end{cases}$$

Consequently, without loss of generality, we will assume in the following that condition (1.13) holds with h satisfying (1.14), (1.15), and

$$h(s) = 0, \quad \forall s \geq 1. \quad (4.1)$$

Let us consider the function $G : (0, +\infty) \rightarrow (0, +\infty)$ given by

$$G(s) = e \int_1^s \frac{h(t)}{\beta} dt \quad \text{for every } s > 0,$$

where β is given by (1.2). Observe that, by (1.14), the function G can be continuously extended to $[0, +\infty)$ setting $G(0) = 0$. Moreover, we also define the function $\sigma : [0, +\infty) \rightarrow [0, +\infty)$ by setting $\sigma(0) = 0$ and

$$\sigma(s) = e \int_1^s \sqrt{h(t)} dt \quad \text{for every } s > 0.$$

Observe that, thanks to (1.14) and (1.15), we have that $\sigma \in C^1([0, +\infty))$, $\sigma'(0) = h_0$ and $\sigma(s) = 0$ if and only if $s = 0$. As a consequence of (4.1), $\sigma(s) = 1$ for every $s > 1$ and $\sigma(s) \leq 1$ for every $s \geq 0$. The next lemma is the key for the proof of Theorem 1.4.

Lemma 4.1. Assume (1.14) and (1.15). Then the function

$$\varphi(s) = \begin{cases} \frac{\int_0^s G(t)[\sigma'(t)]^2 dt}{G(s)} & \text{if } s > 0, \\ 0 & \text{if } s = 0, \end{cases} \quad (4.2)$$

is a continuously differentiable function on $[0, +\infty)$ that satisfies the ordinary differential equation

$$\begin{cases} \varphi'(s) + \frac{h(s)}{\beta}\varphi(s) = [\sigma'(s)]^2, & \text{on } [0, +\infty), \\ \varphi(0) = 0. \end{cases} \quad (4.3)$$

Moreover, the following inequality holds:

$$\varphi(s) \leq \beta[\sigma(s)]^2, \quad \forall s > 0. \quad (4.4)$$

Proof. The first part of the proof is straightforward except for checking that φ is differentiable at zero and φ' is continuous at zero. In order to do it, we note firstly that φ is continuous at zero. Indeed, since G is nondecreasing and $[\sigma']^2$ is continuous in $[0, +\infty)$ we have

$$0 \leq \lim_{s \rightarrow 0^+} \varphi(s) = \lim_{s \rightarrow 0^+} \frac{\int_0^s G(t)[\sigma'(t)]^2 dt}{G(s)} \leq \lim_{s \rightarrow 0^+} \int_0^s [\sigma'(t)]^2 dt = 0.$$

Now we observe that, using the L'Hôpital Rule, (1.14) and (1.15),

$$\begin{aligned} \varphi'(0) &= h_0^2 - \lim_{s \rightarrow 0^+} \frac{h(s) \int_0^s G(t) [\sigma'(t)]^2 dt}{\beta G(s)} \\ &= h_0^2 - h_0^2 \lim_{s \rightarrow 0^+} \frac{G(s)[\sigma'(s)]^2}{2\beta\sigma(s)\sigma'(s)G(s) + h(s)[\sigma(s)]^2 G(s)} \\ &= h_0^2 - h_0^2 \lim_{s \rightarrow 0^+} \frac{1}{2\beta \frac{1}{\sqrt{h(s)}} + 1} = h_0^2 - h_0^2 = 0. \end{aligned}$$

Hence φ is differentiable at zero and φ' is continuous at zero.

In order to prove inequality (4.4), we observe that since $[\sigma'(s)]^2 = [\sigma(s)]^2 h(s)$, then

$$\varphi(s) = \frac{\beta}{G(s)} \int_0^s G(t) \frac{h(t)}{\beta} [\sigma(t)]^2 dt.$$

Since

$$G(t) \frac{h(t)}{\beta} = \frac{d}{dt} G(t),$$

we can integrate by parts to find (recall that $G(0) = \sigma(0) = 0$)

$$\begin{aligned}\varphi(s) &= \frac{\beta}{G(s)} [G(t) [\sigma(t)]^2]_{t=0}^{t=s} - \frac{2\beta}{G(s)} \int_0^s G(t) \sigma(t) \sigma'(t) dt \\ &= \beta [\sigma(s)]^2 - \frac{2\beta}{G(s)} \int_0^s G(t) [\sigma(t)]^2 \sqrt{h(t)} dt \\ &\leq \beta [\sigma(s)]^2,\end{aligned}$$

since all the functions in the last integral are nonnegative. \square

Proof of Theorem 1.4. Let $u \in H_0^1(\Omega)$ be a positive solution for (1.1) and $\varphi \in C^1([0, +\infty))$ be given by (4.2). Observing that $\varphi(0) = 0$, that φ' is bounded and that, by (4.4) and since $\sigma(s) \leq 1$, we have $\varphi(s) \leq \beta$, we derive that $\varphi(u) \in H_0^1(\Omega) \cap L^\infty(\Omega)$. Therefore, we can take $v = \varphi(u)$ as test function in (2.1) to obtain, by using (1.13), that

$$\int_{\Omega} M(x, u) \nabla u \cdot \nabla u \varphi'(u) + \int_{\Omega} h(u) |\nabla u|^2 \varphi(u) \leq \int_{\Omega} f \varphi(u).$$

Thus, adding and subtracting $\frac{1}{\beta} \int_{\Omega} M(x, u) \nabla u \cdot \nabla u h(u) \varphi(u)$, we derive from (1.2) and (4.3) that

$$\begin{aligned}\int_{\Omega} M(x, u) \nabla u \cdot \nabla u [\sigma'(u)]^2 &\leq \int_{\Omega} M(x, u) \nabla u \cdot \nabla u \left[\varphi'(u) + \frac{h(u)}{\beta} \varphi(u) \right] \\ &\quad + \int_{\Omega} \left[I - \frac{M(x, u)}{\beta} \right] \nabla u \cdot \nabla u h(u) \varphi(u) \\ &\leq \int_{\Omega} f \varphi(u).\end{aligned}$$

Using now (1.2), (4.4) and the fact that $f \geq 0$, we have

$$\alpha \int_{\Omega} |\nabla \sigma(u)|^2 = \alpha \int_{\Omega} |\nabla u|^2 [\sigma'(u)]^2 \leq \int_{\Omega} f \varphi(u) \leq \beta \int_{\Omega} f [\sigma(u)]^2. \quad (4.5)$$

Hence, recalling (see [18]) that, since f belongs to $L^q(\Omega)$ with $q > \frac{N}{2}$, and $f^+ \not\equiv 0$, the first positive eigenvalue $\lambda_1(f)$ of the eigenvalue boundary value problem

$$\begin{cases} -\Delta u = \lambda f u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

is such that

$$\lambda_1(f) \int_{\Omega} f v^2 \leq \int_{\Omega} |\nabla v|^2, \quad \forall v \in H_0^1(\Omega),$$

we deduce from (4.5) that

$$\alpha \int_{\Omega} |\nabla \sigma(u)|^2 \leq \frac{\beta}{\lambda_1(f)} \int_{\Omega} |\nabla \sigma(u)|^2.$$

Recalling the assumption $\frac{\beta}{\alpha} < \lambda_1(f)$, this implies that

$$\int_{\Omega} |\nabla \sigma(u)|^2 = 0,$$

which yields

$$\sigma(u) = 0 \quad \text{for a.e. } x \in \Omega.$$

Therefore, recalling that $\sigma(s) = 0$ if and only if $s = 0$, we have $u \equiv 0$, contradicting $u > 0$ in Ω : therefore, there are no positive solutions of (1.1). \square

Remark 4.2. Theorem 1.4 can be extended to more general operators. Specifically, if $a(x, s, \varsigma)$ is a Carathéodory function such that

$$\exists \alpha > 0 : a(x, s, \varsigma) \cdot \varsigma \geq \alpha |\varsigma|^2 \quad \text{for a.e. } x \in \Omega, \forall s \in \mathbb{R}, \forall \varsigma \in \mathbb{R}^N,$$

$$\exists \beta > 0 : |a(x, s, \varsigma)| \leq \beta |\varsigma| \quad \text{for a.e. } x \in \Omega, \forall s \in \mathbb{R}, \forall \varsigma \in \mathbb{R}^N,$$

and $0 \leq f \in L^q(\Omega)$ with $q > \frac{N}{2}$ and $f \not\equiv 0$, then problem

$$\begin{cases} -\operatorname{div}(a(x, u, \nabla u)) + g(x, u)|\nabla u|^2 = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

has no finite energy solutions provided $\lambda_1(f) > \frac{\beta}{\alpha}$ and conditions (1.13), (1.14) and (1.15) hold.

Remark 4.3. Let $0 \leq f \in L^q(\Omega)$ with $q > \frac{N}{2}$ and $f \not\equiv 0$. Assume (1.2) and that $g(s)$ satisfies (1.13). Observe that if $u \in H_0^1(\Omega)$ is a solution of (1.1), and $R > 0$, then $v = Ru$ is a solution of

$$\begin{cases} -\operatorname{div}\left(M\left(x, \frac{v}{R}\right) \nabla v\right) + \frac{1}{R}g\left(x, \frac{v}{R}\right) |\nabla v|^2 = Rf & \text{in } \Omega, \\ v = 0 & \text{on } \partial\Omega, \end{cases}$$

with

$$\frac{g\left(x, \frac{s}{R}\right)}{R} \geq h_R(s) \stackrel{\text{def}}{=} \frac{1}{R}h\left(\frac{s}{R}\right).$$

Therefore, by Theorem 1.4, and since $\lambda_1(Rf) = \lambda_1(f)/R$, if $h_R(s)$ satisfies conditions (1.14) and (1.15), then a necessary condition for the existence of finite energy solutions of (1.1) is that $\lambda_1(f) \leq R\beta/\alpha$.

In the following result, as a consequence of Theorem 1.4 (and Remark 4.3), we give conditions to assure the nonexistence of solutions of (1.1) for every datum f .

Corollary 4.4. *Let $0 \leq f \in L^q(\Omega)$ with $q > \frac{N}{2}$ and $f \not\equiv 0$. Assume (1.2) and that $g(s)$ satisfies (1.13). If there exists $R_0 > 0$ such that the function $h_R(s) = \frac{1}{R}h\left(\frac{s}{R}\right)$ satisfies (1.14) and (1.15) for every $R \in (0, R_0)$, then (1.1) does not have any finite energy solution. \square*

As a consequence of the above results we also have the following.

Corollary 4.5. *Let $0 \leq f \in L^q(\Omega)$ with $q > \frac{N}{2}$ and $f \not\equiv 0$. Suppose that (1.2) holds and that for some constants $s_0, \Lambda > 0$ and $\gamma \geq 2$ we have*

$$\frac{\Lambda}{s^\gamma} \leq g(x, s), \quad \text{for a.e. } x \in \Omega, \forall s \in (0, s_0].$$

If either

(i) $\gamma > 2$,

or

(ii) $\gamma = 2$ and $\lambda_1(f) > \frac{\beta}{\Lambda\alpha}$,

then (1.1) does not have any finite energy solution.

Proof. Consider a continuous function $h(s)$ such that

$$h(s) = \begin{cases} \frac{\Lambda}{s^\gamma} & \text{if } 0 < s \leq \frac{s_0}{2}, \\ \leq \frac{\Lambda}{s^\gamma} & \text{if } \frac{s_0}{2} < s < s_0, \\ 0 & \text{if } s_0 \leq s. \end{cases}$$

Observing that $h_R(s) = \frac{\Lambda R^{\gamma-1}}{s^\gamma}$ for every $s \in (0, \frac{s_0}{2})$, and using that $\gamma \geq 2$, we have that $h_R(s)$ is not integrable in $(0, \frac{s_0}{2})$, i.e., it satisfies (1.14).

In addition, if $\gamma > 2$, then $h_R(s)$ satisfies (1.15) for every $R > 0$, so that Corollary 4.4 concludes the proof in this case.

On the other hand, if we assume that $\gamma = 2$, then

$$\sqrt{h_R(s)} e^{\int_1^s \sqrt{h_R(t)} dt} = \frac{\sqrt{\Lambda R}}{s} e^{\int_{s_0/2}^s \frac{\sqrt{\Lambda R}}{s} dt} + \int_1^{s_0/2} \sqrt{h_R(t)} dt = C s^{\sqrt{\Lambda R}-1},$$

for some $C > 0$. Thus, $h_R(s)$ satisfies (1.15) if and only if

$$\lim_{s \rightarrow 0^+} s^{\sqrt{\Lambda R}-1} \geq 0,$$

i.e., $R \geq \frac{1}{\Lambda}$. Therefore, Remark 4.3 implies the nonexistence of solutions provided that $\lambda_1(f) > \frac{\beta}{\Lambda\alpha}$. \square

As a consequence of this result, we have that the first part of Theorem 1.5 is proved. We are now going to prove the second part of it.

Proof of Theorem 1.5. We first note that if $\gamma < 2$, then Theorem 1.2 guarantees the existence of a solution. Conversely, if $\gamma > 2$ or if $\gamma = 2$ and $\|f\|_{L^\infty(\Omega)}$ is large enough, Theorem 1.4 applies and no solutions exist for (1.5).

On the other hand, if $f \in L^\infty(\Omega)$ and (1.16) holds, we recall that existence and uniqueness of a solution u_n in $H_0^1(\Omega) \cap C(\overline{\Omega})$ for

$$\begin{cases} -\Delta u_n + \frac{|\nabla u_n|^2}{(u_n + \frac{1}{n})^\gamma} = f & \text{in } \Omega, \\ u_n = 0 & \text{on } \partial\Omega, \end{cases} \quad (4.6)$$

(with $\gamma \geq 2$) follows by the results of [16] (existence) and [4] (uniqueness). Taking u_n , $G_k(u_n)$, and $T_\varepsilon(u_n)/\varepsilon$ as test functions and working as in Lemma 2.2 (1.), it is easy to see that u_n is bounded in $H_0^1(\Omega)$ and in $L^\infty(\Omega)$, and that there exists $C > 0$ (independent on n) satisfying

$$\int_\Omega \frac{|\nabla u_n|^2}{(u_n + \frac{1}{n})^\gamma} \leq C.$$

Therefore, up to subsequences, there exists a nonnegative bounded Radon measure ν such that

$$\frac{|\nabla u_n|^2}{(u_n + \frac{1}{n})^\gamma} \text{ converges to } \nu \text{ in the weak-}^* \text{ topology of measures.}$$

Since u_n is bounded in $H_0^1(\Omega)$ then it converges, up to subsequences, to some function u weakly in $H_0^1(\Omega)$, strongly in $L^2(\Omega)$, and almost everywhere in Ω . Moreover, since $f - \frac{|\nabla u_n|^2}{(u_n + \frac{1}{n})^\gamma}$ is bounded in $L^1(\Omega)$, the result of [14] yields that (up again to subsequences) ∇u_n converges to ∇u almost everywhere in Ω . Then we have, by Fatou lemma, that $\frac{|\nabla u|^2}{u^\gamma} \chi_{\{u>0\}}$ belongs to $L^1(\Omega)$, and that

$$\nu = \frac{|\nabla u|^2}{u^\gamma} \chi_{\{u>0\}} + \nu_0,$$

where ν_0 is a nonnegative bounded Radon measure on Ω . Therefore, $u \in H_0^1(\Omega)$ is a finite energy solution of

$$\begin{cases} -\Delta u + \frac{|\nabla u|^2}{u^\gamma} \chi_{\{u>0\}} = f - \nu_0 & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

Note also that since u_{n+1} is a subsolution for (4.6), we can apply the comparison principle of [4] so that, for every $x \in \Omega$, we have

$$u_n(x) \geq u_{n+1}(x) \geq \dots \geq u(x),$$

and thus we can assume that $u_n(x)$ is converging to $u(x)$ for every $x \in \Omega$. We claim that $u \equiv 0$, so that u_n converges to zero in $L^2(\Omega)$. Indeed, we divide the proof of this assertion in two steps:

Step 1. The case in which Ω is a ball of radius $R > 0$, $\Omega = B_R$, and $f = T > 0$ is a constant.

Step 2. The general case.

Step 1. Assume that $\Omega = B_R$ and $f = T > 0$ is a constant. In this case, (1.16) means that, if $\gamma = 2$, then the first eigenvalue $\lambda_1^{B_R}(T)$ of the Laplacian operator with weight T in B_R is greater than one, i.e., $\lambda_1^{B_R}(T) > 1$. We first observe that u is radially symmetric (and thus continuous for $|x| \neq 0$). Indeed, if we define

$$\psi_n(s) = \int_0^s e^{-H_n(t)} dt, \quad \text{where} \quad H_n(t) = \frac{n^{\gamma-1}}{\gamma-1} [1 - (1+nt)^{1-\gamma}]$$

and we set $v_n = \psi_n(u_n)$, it is easy to check that v_n is the unique solution of

$$\begin{cases} -\Delta v_n = T e^{-H_n(\psi_n^{-1}(v_n))} & \text{in } B_R \\ v_n = 0 & \text{on } \partial B_R. \end{cases}$$

Since the nonlinearity $0 \leq e^{-H_n(\psi_n^{-1}(s))}$ is C^1 , we can apply the result of Gidas, Ni and Nirenberg (see [22]) in order to deduce that v_n is radially symmetric (hence $v_n = v_n(r)$), monotone decreasing with respect to r and such that $v_n'(0) = 0$. Since ψ_n and H_n are smooth and increasing, the functions u_n have the same properties as v_n . Passing to the limit with respect to n we deduce that u is radially symmetric and monotone nonincreasing.

We argue by contradiction assuming that u is not identically zero. In this case, using that $u(r)$ is nonincreasing in $(0, R)$,

$$r_1 = \inf\{0 < r \leq R : u(r) = 0\} > 0,$$

and then

$$u \geq c_\varepsilon := u(r_1 - \varepsilon) \quad \text{in } B_{r_1 - \varepsilon}.$$

Therefore, repeating the proof of Theorem 1.1, we prove that

$$\lim_{n \rightarrow +\infty} \frac{|\nabla u_n|^2}{(u_n + \frac{1}{n})^\gamma} = \frac{|\nabla u|^2}{u^\gamma} \quad \text{strongly in } L^1_{\text{loc}}(B_{r_1}),$$

so that ν_0 is zero on B_{r_1} and, by the continuity of u for $r \neq 0$, u is a solution of

$$\begin{cases} -\Delta u + \frac{|\nabla u|^2}{u^\gamma} = T & \text{in } B_{r_1}, \\ u = 0 & \text{on } \partial B_{r_1}, \end{cases}$$

and this contradicts the result of Theorem 1.4 (note that, if $\gamma = 2$, we have $\lambda_1^{B_{r_1}}(T) > \lambda_1^{B_R}(T) > 1$). Therefore $u \equiv 0$.

Step 2. Ω is an open set and f is nonnegative and belongs to $L^\infty(\Omega)$.

By (1.16), we can fix $R > \text{diam } \Omega$ with $\lambda_1 > \|f\|_{L^\infty(\Omega)} R^2$ provided that $\gamma = 2$. Let v_n be also the solution of

$$\begin{cases} -\Delta v_n + \frac{|\nabla v_n|^2}{(v_n + \frac{1}{n})^\gamma} = \|f\|_{L^\infty(\Omega)} & \text{in } B_R \\ v_n = 0 & \text{on } \partial B_R. \end{cases}$$

By definition of $\text{diam } \Omega$, we have $\bar{\Omega} \subset B_R$. Our aim is to prove that v_n is a supersolution for (4.6). Indeed, let $0 \leq \psi \in C_0^\infty(\Omega)$ and we use it as test function in the formulation of v_n . Thus

$$\int_{B_R} \nabla v_n \cdot \nabla \psi + \int_{B_R} \frac{|\nabla v_n|^2}{(\frac{1}{n} + u_n)^\gamma} \psi = \int_{B_R} \|f\|_{L^\infty(B_R)} \psi,$$

and since the support of ψ is contained in Ω we deduce

$$\int_{\Omega} \nabla v_n \cdot \nabla \psi + \int_{\Omega} \frac{|\nabla v_n|^2}{(\frac{1}{n} + u_n)^\gamma} \psi = \int_{\Omega} \|f\|_{L^\infty(B_R)} \psi \geq \int_{\Omega} f \psi$$

for every nonnegative ψ in $H_0^1(\Omega) \cap L^\infty(\Omega)$ (by an easy density argument). Using again the comparison principle of [4], $u_n \leq v_n$ in Ω . Now, observing that by the choice of R , if $\gamma = 2$, we have

$$\lambda_1^{B_R}(\|f\|_{L^\infty(\Omega)}) = \frac{\lambda_1}{R^2 \|f\|_{L^\infty(\Omega)}} > 1, \quad (4.7)$$

we are able to apply the previous Step 1, so that v_n tends to 0 strongly in $L^2(B_R)$, which implies that u_n tends to zero in $L^2(\Omega)$ and the claim has been proved.

Finally, we conclude the proof by taking u_n as test function in (4.6) and dropping the nonnegative quadratic term to deduce that the convergence to zero is strong in $H_0^1(\Omega)$; using this fact in the weak formulation of (4.6) then yields that $\nu = f$, as desired. \square

Remark 4.6. Let us emphasize that the condition $\|f\|_{L^\infty(\Omega)} \leq \frac{\lambda_1}{(\text{diam } \Omega)^2}$ imposed in assumption (1.16) for the case $\gamma = 2$ is not optimal. We use it for the sake of simplicity. However, as shown in the proof of Theorem 1.5 (see (4.7)), a sharper condition can be used in this case.

More precisely, if we consider the Chebyshev radius $R(\Omega)$ of $\bar{\Omega}$, i.e. the greatest lower bound of the radii of all balls containing $\bar{\Omega}$, then the result of Theorem 1.5 with $\gamma = 2$ holds provided that

$$\|f\|_{L^\infty(\Omega)} < \frac{\lambda_1}{R(\Omega)^2}.$$

A. Local a priori estimates and large solutions

We devote this appendix to recall some results concerning the following equation

$$-\text{div}(a(x, u, \nabla u)) + B(x, u) = F(x, \nabla u), \quad x \in \Omega, \quad (\text{A.1})$$

where $F(x, \varsigma)$ and $a(x, s, \varsigma), B(x, s)$ are Carathéodory functions. Suppose that there exist constants $\beta \geq \alpha > 0$ such that

$$a(x, s, \varsigma) \cdot \varsigma \geq \alpha |\varsigma|^2, \quad (\text{A.2})$$

$$|a(x, s, \varsigma)| \leq \beta|\varsigma|, \quad (\text{A.3})$$

$$(a(x, s, \varsigma) - a(x, s, \eta)) \cdot (\varsigma - \eta) > 0, \quad (\text{A.4})$$

for a.e. $x \in \Omega$, for every $s \in \mathbb{R}$ and for every $\varsigma, \eta \in \mathbb{R}^N$, $\varsigma \neq \eta$.

We suppose that $F(x, \varsigma)$ satisfies

$$|F(x, \varsigma)| \leq F_0(x) + p_0|\varsigma|, \text{ a.e. } x \in \Omega, \forall \varsigma \in \mathbb{R}^N, \quad (\text{A.5})$$

where F_0 belongs to $L^q_{\text{loc}}(\Omega)$ with $q > \frac{N}{2}$ and $p_0 > 0$. We also suppose that there exists a continuous nonnegative function $b : [0, +\infty) \rightarrow [0, +\infty)$ such that

$$\begin{aligned} & b(s) \text{ is increasing and satisfies the Keller-Osserman condition (2.10),} \\ & b(s)/s \text{ is nondecreasing for large } s, \\ & \text{and for every } \omega \subset\subset \Omega \text{ there exists } m_\omega > 0 \text{ such that} \\ & B(x, s) \geq m_\omega b(s) \geq 0, \text{ for a.e. } x \in \omega, \text{ for every } s \in \mathbb{R}^+. \end{aligned} \quad (\text{A.6})$$

Then the subsolutions of equation (A.1) are uniformly bounded from above in $\omega \subset\subset \Omega$. This result is essentially contained in [27].

Theorem A.1. *Suppose that $a(x, s, \varsigma)$ satisfies (A.2)–(A.4), $B(x, s)$ satisfies (A.6) and assume that $F_0 \in L^q_{\text{loc}}(\Omega)$, $q > \frac{N}{2}$. Then, for every $\omega \subset\subset \Omega$ there exists $C_\omega > 0$ such that any distributional subsolution $u \in H^1_{\text{loc}}(\Omega)$ of (A.1) such that $u^+ \in L^\infty_{\text{loc}}(\Omega)$ and $B(x, u^+) \in L^1_{\text{loc}}(\Omega)$ satisfies*

$$u(x) \leq C_\omega, \quad \forall x \in \omega.$$

In order to prove this theorem, we need the following two lemmas.

Lemma A.2 (Lemma 3.3 of [28]). *Let $b : [0, +\infty) \rightarrow [0, +\infty)$ be a continuous function, satisfying the Keller-Osserman condition (2.10), such that $\frac{b(s)}{s}$ is nondecreasing for large s . Then, for any $C > 0$ and $\gamma \geq 0$, there exist a positive constant Γ and a smooth function $\varphi : [0, 1] \rightarrow [0, 1]$ (Γ and φ depending only on b , C and γ), with $\varphi(0) = \varphi'(0) = 0$, $\varphi(1) = 1$ and $\varphi(s) > 0$ for every $s > 0$, satisfying*

$$t^{\gamma+1} \frac{\varphi'(\tau)^2}{\varphi(\tau)} \leq \frac{1}{C} t^\gamma b(t) \varphi(\tau) + \Gamma, \quad \forall \tau \in (0, 1], \forall t \geq 0.$$

Remarks A.3. 1. In Lemma 3.3 of [28] it is imposed that $b(s)$ is increasing, $b(0) = 0$, and the function $\frac{b(s)}{s}$ is nondecreasing in \mathbb{R}^+ . However, it is easy to see that the proof (see also [27]) works by using the weaker assumptions of Lemma A.2.

2. In addition, also in [27], the Keller-Osserman condition is replaced by the following one:

$$\int^{+\infty} \frac{ds}{\sqrt{sb(s)}} < +\infty.$$

Note that, as a consequence of the monotonicity of $b(s)$ for large s , the above assumption is equivalent to (2.10).

Let us recall a local version of a classical result by Stampacchia we will use in the following.

Lemma A.4 ([36]). *Let $\tau(j, \rho) : [0, +\infty) \times [0, R_0) \rightarrow \mathbb{R}$ be a function such that $\tau(\cdot, \rho)$ is nonincreasing and $\tau(j, \cdot)$ is nondecreasing. Moreover, suppose that there exist $K_0 > 0$, $\mu > 1$, and $C, \nu, \gamma > 0$ satisfying*

$$\tau(j, \rho) \leq C \frac{\tau(k, R)^\mu}{(j-k)^\nu (R-\rho)^\gamma}, \quad \forall j > k > K_0, \forall 0 < \rho < R < R_0.$$

Then for every $\delta \in (0, 1)$, there exists $d > 0$ such that:

$$\tau(K_0 + d, (1 - \delta)R_0) = 0,$$

where $d^\nu = 2^{(\nu+\gamma)\frac{\mu}{\mu-1}} C \frac{(\tau(K_0, R_0))^{\mu-1}}{\delta^\gamma R_0^\gamma}$.

Idea of the Proof of Theorem A.1. The proof of this result is essentially contained in [27], but for the convenience of the reader, we include here the proof of the exact result that we have used in the proof of Proposition 2.3 and in the proof of Theorem 1.3.

Actually we deal with equation

$$-\operatorname{div}(\widetilde{M}(x, u)\nabla u) + P(x) \cdot \nabla u + f(x)b(u) = 0, \quad \text{in } \Omega,$$

where $\widetilde{M}(x, s)$ satisfies (1.2), $P(x)$ is a bounded vector field, $b(s)$ is increasing and satisfies the Keller-Osserman condition (2.10), $\frac{b(s)}{s}$ is nondecreasing for s large, and f satisfies (1.4). Consequently all the assumptions of the theorem are satisfied. We remind that the above assumptions are satisfied by the functions $\widetilde{M}(x, s)$, $b(s)$ and $f(x)$, appearing in Proposition 2.3 as well as by the functions $M(x)$, $P(x)$, $b(s)$ and $f(x)$ appearing in Theorem 1.3.

Suppose now that $u^+ \in L^\infty_{\text{loc}}(\Omega)$ and $b(u^+) \in L^1_{\text{loc}}(\Omega)$. We set $\omega \subset\subset \omega' \subset\subset \Omega$ and a cut-off function $\eta(x)$ such that $0 \leq \eta \leq 1$ and

$$\eta(x) = \begin{cases} 1, & x \in \omega, \\ 0, & x \in \Omega \setminus \omega'. \end{cases} \quad (\text{A.7})$$

We denote $p_0 = \|P(x)\|_{(L^\infty(\Omega))^N}$ and we fix $\sigma > \frac{2p_0}{\alpha}$ and the constants C, k_0 such that

$$\frac{\|\nabla \eta\|_{L^\infty(\Omega)}^2}{8\sigma^2} \left[\frac{\beta^2}{\alpha} + \left(\alpha - \frac{p_0}{\sigma} \right) \right] \frac{1}{C} + \frac{p_0}{4\sigma b(k_0)} \leq \frac{m_{\omega'}(f)}{2\sigma},$$

and we also consider the function φ given by Lemma A.2 with $\gamma = 1$ and this constant C . Note that if $\xi = \sqrt{\varphi(\eta)}$, then $u\xi^2 = u\varphi(\eta) \in H^1_0(\Omega)$ and

$$\nabla(u\xi^2) = \begin{cases} \xi^2 \nabla u + 2\xi u \nabla \xi, & \text{if } \xi(x) > 0, \\ 0, & \text{if } \xi(x) = 0, \end{cases} \quad (\text{A.8})$$

a.e. in Ω . Moreover $f(x)(e^{2\sigma G_k(u^+)} - 1)b(u^+) \in L^1_{\text{loc}}(\Omega)$ and consequently $v = \frac{1}{2\sigma}(e^{2\sigma G_k(u^+)} - 1)\xi^2$, $\sigma > \frac{2p_0}{\alpha}$ is an admissible test function. Using this test function as well as (1.2), (1.4) and Young's inequality we deduce that

$$\begin{aligned}
& \alpha \int_{\omega'} |\nabla G_k(u^+)|^2 e^{2\sigma G_k(u^+)} \xi^2 + \frac{m_{\omega'}(f)}{2\sigma} \int_{\omega'} b(u^+)(e^{2\sigma G_k(u^+)} - 1)\xi^2 \\
& \leq \frac{\beta}{\sigma} \int_{\omega'} |\nabla \xi| |\nabla G_k(u^+)| (e^{2\sigma G_k(u^+)} - 1)\xi + p_0 \int_{\omega'} |\nabla G_k(u^+)| v \\
& \leq \frac{\alpha}{2} \int_{\omega'} |\nabla G_k(u^+)|^2 e^{2\sigma G_k(u^+)} \xi^2 + \frac{\beta^2}{2\alpha\sigma^2} \int_{\omega'} \frac{|\nabla \xi|^2 (e^{2\sigma G_k(u^+)} - 1)^2}{e^{2\sigma G_k(u^+)}} \\
& \quad + \frac{p_0}{2\sigma} \int_{\omega'} |\nabla G_k(u^+)|^2 (e^{2\sigma G_k(u^+)} - 1)\xi^2 + \frac{p_0}{4\sigma} \int_{\omega'} (e^{2\sigma G_k(u^+)} - 1)\xi^2 \\
& \leq \frac{\sigma\alpha + p_0}{2\sigma} \int_{\omega'} |\nabla G_k(u^+)|^2 e^{2\sigma G_k(u^+)} \xi^2 + \frac{\beta^2}{2\alpha\sigma^2} \int_{\omega'} |\nabla \xi|^2 (e^{2\sigma G_k(u^+)} - 1)^2 \\
& \quad + \frac{p_0}{4\sigma} \int_{\omega'} (e^{2\sigma G_k(u^+)} - 1)\xi^2.
\end{aligned}$$

In other words,

$$\begin{aligned}
& \frac{1}{4\sigma^2} \left(\alpha - \frac{p_0}{\sigma} \right) \int_{\omega'} |\nabla[(e^{\sigma G_k(u^+)} - 1)\xi]|^2 + \frac{m_{\omega'}(f)}{2\sigma} \int_{\omega'} b(u^+)(e^{2\sigma G_k(u^+)} - 1)\xi^2 \\
& \leq \left[\frac{\beta^2}{2\alpha\sigma^2} + \frac{1}{2\sigma^2} \left(\alpha - \frac{p_0}{\sigma} \right) \right] \int_{\omega'} |\nabla \xi|^2 (e^{2\sigma G_k(u^+)} - 1)^2 + \frac{p_0}{2} \int_{\omega'} v.
\end{aligned}$$

Applying Lemma A.2 with $\gamma = 1$, together with the monotonicity of $b(s)$ we get

$$\begin{aligned}
& \frac{1}{4\sigma^2} \left(\alpha - \frac{p_0}{\sigma} \right) \int_{\omega'} |\nabla[(e^{\sigma G_k(u^+)} - 1)\xi]|^2 \\
& \leq \Gamma \frac{\|\nabla \eta\|_{L^\infty(\Omega)}^2}{8\sigma^2} \left[\frac{\beta^2}{\alpha} + \left(\alpha - \frac{p_0}{\sigma} \right) \right] \text{meas} \{x \in \omega' : u(x) \geq k\},
\end{aligned}$$

for every $k > k_0(m_{\omega'}(f), p_0)$. We deduce by Sobolev's inequality that

$$\left(\int_{\omega'} |(e^{\sigma G_k(u^+)} - 1)\xi|^{2^*} \right)^{\frac{2}{2^*}} \leq C_0 \text{meas} \{x \in \omega' : u(x) \geq k\},$$

where $C_0 = \mathcal{S}^2 \Gamma \frac{\|\nabla \eta\|_{L^\infty(\Omega)}^2}{8\sigma^2} \left[\frac{\beta^2}{\alpha} + \left(\alpha - \frac{p_0}{\sigma} \right) \right]$. Hence, using that $e^t - 1 \geq t$, for every $t \geq 0$, and that $G_k(s) \geq j - k$ for $s \geq j > k$ we derive that

$$(j - k)^2 \text{meas} \{x \in \omega : u(x) \geq j\}^{\frac{2}{2^*}} \leq \frac{C_0}{\sigma} \text{meas} \{x \in \omega' : u(x) \geq k\}. \quad (\text{A.9})$$

Now, if $\omega \subset \subset \Omega$ is fixed, we consider $R = \text{dist}(\omega, \partial\Omega)/2$, the set

$$\omega_r = \{x \in \Omega : \text{dist}(x, \omega) < r\} \subset \subset \Omega$$

and the function

$$\tau(k, r) = \text{meas} \{x \in \omega_r : u(x) \geq k\},$$

for every $r \in (0, R]$ and $k > 0$. Taking $\omega = \omega_r$ and $\omega' = \omega_R$ in (A.9) and choosing η such that $\|\nabla\eta\|_{L^\infty(\Omega)} \leq \frac{c}{R-r}$, we obtain

$$(j - k)^2 \tau(j, r)^{2/2^*} \leq c_1 \frac{\tau(k, R)}{(R - r)^2}$$

for some $c_1 > 0$ and the proof is concluded by applying Lemma A.4. \square

- Remarks A.5.**
1. We remark explicitly that in the above proof the constant Γ obtained by applying Lemma A.2 depends on $m_{\omega'}(f)$. In particular, since $m_{\omega'}(f) \leq m_\omega(f)$ for $\omega \subset\subset \omega'$, if $m_\omega(f)$ tends to zero, then this constant Γ and hence the a priori estimate C_ω given by Theorem A.1 diverge to $+\infty$.
 2. By adding a condition on the function $b(s)$ for negative s and using similar ideas to these ones in the above proof, it is possible to give also a priori estimates of the whole L^∞ norm of the solution in every compact subset ω of Ω . More precisely, if, in addition to the hypotheses of Theorem A.1, we strengthen (A.6) by imposing that

$$\begin{aligned} & b(s) \text{ is increasing and satisfies (2.10), } b(s)/s \text{ is nondecreasing,} \\ & \text{for large } s \text{ and for every } \omega \subset\subset \Omega \text{ there exists } m_\omega > 0 \text{ such that:} \\ & \forall s \in \mathbb{R}, \quad B(x, s) \text{ sign } s \geq m_\omega b(|s|) \geq 0 \quad \text{for a.e. } x \in \omega, \end{aligned} \tag{A.10}$$

then for every $\omega \subset\subset \Omega$ there exists $C_\omega > 0$ such that

$$|u(x)| \leq C_\omega, \quad \forall x \in \omega.$$

Theorem A.1 is an extension to quasilinear equations of the well-known local a priori estimate of Keller [24] and Osserman [33] (see also [5], [31], [32], [37], [38] and the references cited therein) for semilinear operators. This semilinear a priori estimate was the crucial tool in order to prove the existence of a large solution, i.e., a solution u of the semilinear equation satisfying $u = +\infty$ at $\partial\Omega$ in the sense that

$$\lim_{\text{dist}(x, \partial\Omega) \rightarrow 0} u(x) = +\infty.$$

Thus, it is natural to ask whether it is also possible to prove the existence of a large solution for (A.1). Clearly, in this nonlinear framework we have to specify the meaning we give to “infinity” at $\partial\Omega$, since it has no sense pointwise. Actually we will assume such a condition in a weak sense, through a condition on the trace on the boundary of the truncation of the solution. Specifically we consider the following equation

$$-\text{div}(a(x, u, \nabla u)) + B(x, u) = F(x), \quad x \in \Omega. \tag{A.11}$$

Definition A.6. An a.e. finite function $u(x)$ such that $T_k(u) \in H^1(\Omega) \forall k > 0$ is a *distributional large solution* for (A.11) with $F \in L^1_{\text{loc}}(\Omega)$, if:

- i) $|a(x, u, \nabla u)| \in L^1_{\text{loc}}(\Omega)$, $B(x, u) \in L^1_{\text{loc}}(\Omega)$;
- ii)

$$\int_{\Omega} a(x, u, \nabla u) \cdot \nabla \varphi + \int_{\Omega} B(x, u) \varphi = \int_{\Omega} F \varphi, \quad \forall \varphi \in C_c^\infty(\Omega);$$

- iii) $\forall k > 0, k - T_k(u) \in H^1_0(\Omega)$.

Remark A.7. In the above definition, iii) has the meaning of “infinity at $\partial\Omega$ ”. We mention that this definition of explosive boundary condition has already been introduced in [29], for a different class of nonlinear elliptic equations involving nonlinear “coercive” gradient terms.

We conclude by observing that even if not explicitly written in [27], all the estimates that we need in order to prove the existence of large solutions for (A.11) have been proved and thus we have the following result.

Theorem A.8. Suppose that $a(x, s, \varsigma)$ and $B(x, s)$ satisfy (A.2), (A.3), (A.4), (A.10) and

$$\sup_{|s| \leq k} |B(x, s)| \in L^1(\Omega), \quad \forall k > 0. \quad (\text{A.12})$$

Assume also that $F \in L^1_{\text{loc}}(\Omega)$ with $F^- \in L^1(\Omega)$. Then there exists a *distributional large solution* for (A.11).

Proof. We consider the following sequence of problems

$$\begin{cases} -\text{div } a(x, u_n, \nabla u_n) + B(x, u_n) = F_n & \text{in } \Omega, \\ u_n - n \in H^1_0(\Omega), \end{cases}$$

where $F_n = T_n(F)$. Since $B(x, s + n)s \geq 0$ for large $|s|$, the existence of a weak solution $u_n \in H^1(\Omega) \cap L^\infty(\Omega)$ is a consequence of [6] (Theorem 6.1), i.e. $u_n - n \in H^1_0(\Omega)$ and it satisfies

$$\int_{\Omega} a(x, u_n, \nabla u_n) \cdot \nabla v + \int_{\Omega} B(x, u_n) v = \int_{\Omega} F_n v, \quad \forall v \in H^1_0(\Omega) \cap L^\infty(\Omega). \quad (\text{A.13})$$

Observing that for any $n \geq k$, $k - T_k(u_n) \in H^1_0(\Omega) \cap L^\infty(\Omega)$, we can choose $v = k - T_k(u_n)$ as test function in (A.13) and we obtain,

$$-\int_{\Omega} a(x, u_n, \nabla u_n) \cdot \nabla T_k(u_n) + \int_{\Omega} B(x, u_n)[k - T_k(u_n)] = \int_{\Omega} F_n[k - T_k(u_n)].$$

Using (A.2), and (A.6) and (A.12) we have:

$$\alpha \int_{\Omega} |\nabla T_k(u_n)|^2 \leq 2k \int_{\Omega} \sup_{|s| \leq k} |B(x, s)| + 2k \|F_n^-\|_{L^1(\Omega)}.$$

Thus, for every $k \in \mathbb{N}$, we can now extract a subsequence (not relabeled) of $\{T_k(u_n)\}_{n \in \mathbb{N}}$ that weakly converges in $H^1(\Omega)$ and, by Rellich theorem, strongly in $L^2(\Omega)$.

Now, consider any sets $\omega \subset\subset \omega' \subset\subset \Omega$, a cut-off function $\eta(x)$ chosen as in (A.7) and $\xi = \sqrt{\varphi(\eta)}$. Arguing as in (A.8), we deduce that $v = T_k(u_n \xi^2)$ is an admissible test function for (A.13). Thus we have

$$\int_{A_k} a(x, u_n, \nabla u_n) \cdot \nabla [u_n \xi^2] + \int_{\Omega} B(x, u_n) T_k(u_n \xi^2) \leq k \|F\|_{L^1(\omega')},$$

where $A_k = \{x \in \Omega : |u_n| \xi^2 \leq k \text{ and } \xi(x) > 0\}$, and so, using (A.2) and (A.10), we get

$$\begin{aligned} & \alpha \int_{A_k} |\nabla u_n|^2 \xi^2 + m_{\omega'} \int_{A_k} |b(u_n)| T_k(u_n \xi^2) \\ & \leq k \|F\|_{L^1(\omega')} + 2\beta \int_{A_k} |\nabla u_n| |\nabla \xi| u_n \xi. \end{aligned}$$

By applying Young inequality, (A.3) and Lemma A.2 (with $\gamma = 1$ and for any fixed $C > \frac{\alpha^2 + 4\beta^2}{8\alpha m_{\omega'}} \|\nabla \eta\|_{L^\infty(\omega')}$ and taking into account Remarks A.5-2) we deduce that there exists $c > 0$ such that

$$\int_{\Omega} |\nabla T_k(u_n \xi^2)|^2 \leq c(k+1).$$

Then, using that $\xi = 1$ in ω , by Lemmas 4.1 and 4.2 of [6] it follows that u_n and $|\nabla u_n|$ are bounded respectively in $\mathcal{M}^{\frac{N}{N-2}}(\omega)$ and $\mathcal{M}^{\frac{N}{N-1}}(\omega)$, for any $\omega \subset\subset \Omega$. Combining this information with the strong convergence of $T_k(u_n)$ in $L^2(\Omega)$ we deduce that u_n is a Cauchy sequence in measure and so, up to subsequences (not relabeled), it converges for a.e. $x \in \Omega$ to a function $u \in W_{\text{loc}}^{1,q}(\Omega)$. This, in particular, implies that

$$\lim_{n \rightarrow +\infty} k - T_k(u_n) = k - T_k(u) \quad \text{weakly in } H_0^1(\Omega),$$

i.e. u satisfies the boundary condition.

On the other hand, we prove that the lower order term is bounded in $L_{\text{loc}}^1(\Omega)$; indeed, if, for $\varepsilon > 0$, we take $v = \frac{1}{\varepsilon} T_\varepsilon(u_n) \xi$ as test function in (A.13) (as before, such a function it is admissible). Thus, by (A.2), (A.3), and dropping positive terms, we get

$$\int_{\Omega} B(x, u_n) \frac{T_\varepsilon(u_n)}{\varepsilon} \xi \leq \|F\|_{L^1(\omega')} + \beta \|\nabla \xi\|_{L^\infty(\omega')} \int_{\omega'} |\nabla u_n|.$$

Since the right hand side is bounded being $\{|\nabla u_n|\}$ bounded in $\mathcal{M}_{\text{loc}}^{\frac{N}{N-1}}(\Omega)$ and $F \in L_{\text{loc}}^1(\Omega)$, letting $\varepsilon \rightarrow 0$, we deduce by Fatou lemma that there exists $c_\omega > 0$ such that

$$\int_{\omega} |B(x, u_n)| \leq c_\omega.$$

On the other hand, choosing $v = T_1(G_h(u_n \xi^2))$ as test function, where $\xi^2 = \varphi(\eta)$ we have, by using (A.2), (A.3), (A.10) and (A.12),

$$\begin{aligned} & \frac{\alpha}{2} \int_{h \leq |u_n \xi^2| \leq h+1} |\nabla u_n|^2 \xi^2 + \frac{1}{2} \int_{\Omega} B(x, u_n) T_1(G_h(u_n \xi^2)) \\ & \leq \int_{\omega' \cap \{u_n \xi^2 \geq h\}} |F_n| + \frac{2\beta^2}{\alpha} \|\nabla \eta\|_{L^\infty(\Omega)}^2 \text{meas}\{x \in \omega' : \xi^2 |u_n| \geq h\}. \end{aligned}$$

By the strong compactness of $\{F_n\}$ in $L^1(\omega')$ and the local uniform estimate of $\{u_n\}_{n \in \mathbb{N}}$ in $\mathcal{M}_{\text{loc}}^{\frac{N}{N-2}}(\Omega)$, we derive then that

$$\lim_{h \rightarrow +\infty} \sup_{n \in \mathbb{N}} \int_{\{x \in \omega : |u_n| \geq h\}} |B(x, u_n)| = 0.$$

As a consequence of Vitali theorem we deduce that $\{|B(x, u_n)|\}_{n \in \mathbb{N}}$ is strongly compact in $L^1(\omega')$, where $\omega' \subset \subset \Omega$ is arbitrary. Moreover, since the lower order term is bounded in $L^1_{\text{loc}}(\Omega)$, we can apply Lemma 1 in [10] in order to prove that ∇u_n converges to ∇u a.e. in Ω . This, and the weak convergence of u_n in $W^{1,q}(\omega')$, $\forall \omega' \subset \subset \Omega$, imply

$$u_n \rightharpoonup u \quad \text{in } W^{1,q}(\omega), \quad \forall 1 \leq q < \frac{N}{N-1}, \quad \forall \omega \subset \subset \Omega,$$

and, thanks to (A.3), we also have that

$$a(x, u_n, \nabla u_n) \longrightarrow a(x, u, \nabla u) \quad \text{in } L^1(\omega)^N, \quad \forall \omega \subset \subset \Omega. \quad (\text{A.14})$$

Now we can pass to the limit in the distributional formulation: indeed choosing any $\phi \in C_c^\infty(\Omega)$ in (A.13) we have

$$\int_{\Omega} a(x, u_n, \nabla u_n) \cdot \nabla \phi + \int_{\Omega} B(x, u_n) \phi = \int_{\Omega} F_n \phi.$$

Using (A.14) we deduce that

$$\lim_{n \rightarrow +\infty} \int_{\text{supp } \phi} a(x, u_n, \nabla u_n) \cdot \nabla \phi = \int_{\text{supp } \phi} a(x, u, \nabla u) \cdot \nabla \phi.$$

Moreover, by the strong convergence of $\{B(x, u_n)\}$ and $\{F_n\}$ in $L^1_{\text{loc}}(\Omega)$, we deduce that

$$\lim_{n \rightarrow +\infty} \int_{\text{supp } \phi} F_n \phi = \int_{\text{supp } \phi} F \phi$$

and

$$\lim_{n \rightarrow +\infty} \int_{\text{supp } \phi} B(x, u_n) \phi = \int_{\text{supp } \phi} B(x, u) \phi$$

and this concludes the proof. \square

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